

A MODIFIED HYBRID ALGORITHM FOR SOLVING A COMPOSITE MINIMIZATION PROBLEM IN BANACH SPACES

SHIH-SEN CHANG^{1,*}, MIN LIU², LIANGCAI ZHAO², JINFANG TANG²

¹*College of Statistics and Mathematics, Yunnan University of Finance and Economics, Kunming, China*

²*College of Mathematics, Yibin University, Yibin, China*

Abstract. The purpose of this paper is to use a modified hybrid algorithm for finding a minimizer of a non-smooth composite minimization problem in Banach spaces. Without the assumptions that the potential function is Fréchet differentiable and its gradient is L -Lipschitz continuous, we prove that the iterative sequence generated by the hybrid algorithm converges strongly to a minimizer of the composite optimization problem in Banach spaces.

Keywords. Banach space; Composite optimization; Convex minimization problem; Lower semi-continuous function.

2010 Mathematics Subject Classification. 47J25, 65J15.

1. INTRODUCTION

Let X be a real Banach space. Denote by $\Gamma_0(X)$ the class of all proper convex and lower semi-continuous functions from X to $(-\infty, +\infty]$.

In this paper, we study the following non-smooth composite optimization problem: find $x^* \in X$ such that

$$f(x^*) + g(x^*) = \min_{x \in X} \{f(x) + g(x)\}, \quad (1.1)$$

where $f, g \in \Gamma_0(X)$. This problem has a typical scenario in linear inverse problems, and it has applications in image reconstruction, machine learning, data recovering and compressed sensing; see [2, 5, 6, 13, 18, 19, 20, 21] and the references therein.

In the case that X is a real Hilbert space H , problem (1.1) has been studied by many authors; see, for example, [7, 8, 10, 12, 19] and the references therein. In 2011, Xu [16] considered the following constrained convex minimization problem:

$$\min_{x \in C} f(x), \quad (1.2)$$

where C is a nonempty closed and convex subset of H , $f \in \Gamma_0(H)$ is Fréchet differentiable and ∇f is L -Lipschitz continuous. By using the gradient-projection algorithm, Xu [16] proved the following result.

*Corresponding author.

E-mail addresses: changss2013@163.com (S.S. Chang), liuminybsc@163.com (M. Liu), lczaoyb@163.com (L. Zhao), jinfangt_79@163.com (J. Tang).

Received March 21, 2019; Accepted July 17, 2019.

Theorem 1.1. Let f be Fréchet differentiable function and the gradient ∇f of f be L -Lipschitz continuous. Let $h : C \rightarrow C$ be a ρ -contraction with $\rho \in [0, 1)$. Let $\{x_n\}$ be a sequence generated by the following gradient projection algorithm: for any given $x_0 \in H$

$$x_{n+1} = \theta_n h(x_n) + (1 - \theta_n) \text{Proj}_C(x_n - \gamma_n \nabla f(x_n)), \quad n = 0, 1, 2, \dots, \quad (1.3)$$

where Proj_C is the projection from H onto C . If the set S of solutions of minimization problem (1.2) is nonempty, and the following conditions are satisfied:

- (i) $0 < \liminf_{n \rightarrow \infty} \gamma_n \leq \limsup_{n \rightarrow \infty} \gamma_n < \frac{2}{L}$;
- (ii) $\theta_n \rightarrow 0$; $\sum_{n=0}^{\infty} \theta_n = \infty$; $\sum_{n=0}^{\infty} |\theta_{n+1} - \theta_n| < \infty$;
- (iii) $\sum_{n=0}^{\infty} |\gamma_{n+1} - \gamma_n| < \infty$,

then sequence $\{x_n\}$ converges strongly to a minimizer of problem (1.2).

Recently, Guo and Cui [8] considered the following composite optimization problem in Hilbert space H :

$$\min_{x \in X} \{f(x) + g(x)\}, \quad (1.4)$$

where $f, g \in \Gamma_0(H)$, f is differentiable, and ∇f is L -Lipschitz continuous. Let $\{x_n\}$ be a sequence generated by the following gradient projection algorithm: for given $x_0 \in H$

$$x_{n+1} = t_n h(x_n) + (1 - t_n) \text{Prox}_{\alpha_n g}(I - \alpha_n \nabla f(x_n)) + e(x_n), \quad n \geq 0 \quad (1.5)$$

where $\text{Prox}_{\lambda g}$ is a proximal operator defined by

$$\text{Prox}_{\alpha g}(x) := \arg \min_{y \in H} \left\{ \frac{\|y - x\|^2}{2\alpha} + g(y) \right\}, \quad x \in H, \quad \alpha \geq 0,$$

and $e : H \rightarrow H$ is a perturbation operator. They proved the following results.

Theorem 1.2. Let S be the set of minimizers of problem (1.4). If $S \neq \emptyset$ and the following conditions are satisfied:

- (i) $\sum_{n=0}^{\infty} \|e(x_n)\| < \infty$;
- (ii) $0 < a = \inf_n \alpha_n \leq \alpha_n < \frac{2}{L}$, $\sum_{n=0}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$;
- (iii) $\{t_n\} \subset (0, 1)$, $\lim_{n \rightarrow \infty} t_n = 0$; and $\sum_{n=0}^{\infty} t_n = \infty$; $\sum_{n=0}^{\infty} |t_{n+1} - t_n| < \infty$;

Then the sequence $\{x_n\}$ generated in (1.5) converges strongly to a point $x^* \in S$.

Very recently, Sabach and Shtern [14] introduced and studied the following bi-level optimization problem in Euclidean space \mathbf{R}^n . The outer level is given by the following constraint minimization problem

$$\min_{x \in S} \omega(x), \quad (1.6)$$

where S is the set of minimizers of the following inner level minimization problem:

$$\min_{x \in \mathbf{R}^n} \{f(x) + g(x)\}. \quad (1.7)$$

Assume the following conditions are satisfied:

- (1) $f : \mathbf{R}^n \rightarrow \mathbf{R}$ is convex and continuously differentiable and its gradient ∇f is Lipschitz with constant $L_f > 0$; $g : \mathbf{R}^n \rightarrow (-\infty, \infty]$ is proper, lower semicontinuous and convex, and S is nonempty;

(2) $\omega : \mathbf{R}^n \rightarrow \mathbf{R}$ is strongly convex with parameter $\sigma > 0$, i.e., there exists $\sigma > 0$ such that for all $x, y \in \mathbf{R}^n$, and $\alpha \in (0, 1)$

$$\omega(\alpha x + (1 - \alpha)y) + \alpha(1 - \alpha)\frac{\sigma}{2}\|x - y\|^2 \leq \alpha\omega(x) + (1 - \alpha)\omega(y).$$

Assume further that ω is continuously differentiable and $\nabla\omega$ is L_ω -Lipschitz continuous;

(3) $\{\alpha_k\}$ is a sequence in $(0, 1]$, $\alpha_k \rightarrow 0$, $\sum_{k=0}^{\infty} \alpha_k = \infty$ and $\lim_{k \rightarrow \infty} \frac{\alpha_{k+1}}{\alpha_k} = 1$.

If $t \in (0, \frac{1}{L_f}]$, and $s \in (0, \frac{2}{(L_\omega + \sigma)}]$, then the sequence $\{x_n\}$ generated via the following manner: $x_0 \in \mathbf{R}^n$,

$$\begin{cases} y_k = \text{Prox}_{tg}(x_{k-1} - t\nabla f(x_{k-1})), \\ z_k = x_{k-1} - s\nabla\omega(x_{k-1}), \\ x_k = \alpha_k z_k + (1 - \alpha_k)y_k \end{cases} \quad k = 1, 2, \dots \quad (1.8)$$

converges strongly to a solution of problem (1.6).

Motivated and inspired by the results going on in this direction, the purpose of this paper is to use a modified hybrid algorithm for solving non-smooth composite minimization problem (1.1) in Banach spaces without the assumptions that f is Fréchet differentiable and ∇f is L -Lipschitz continuous. Our results improve and extend the corresponding results in [7, 8, 11, 12, 16, 17].

2. PRELIMINARIES

In order to prove the main results, we need the following basic concepts, notations and lemmas.

In the sequel, we assume that X is a real smooth, strictly convex, and reflexive Banach space (the definitions and properties, see, e.g. [4]), and X^* is the dual of X .

- A mapping $J : X \rightarrow 2^{X^*}$ defined by

$$J(x) = \{x^* \in X^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\}, \quad x \in X \quad (2.1)$$

is called the normalized duality mapping. By Hahn-Banach theorem, $J(x) \neq \emptyset$ for each $x \in X$. $J : X \rightarrow 2^{X^*}$ is single-valued, one-to-one, and onto (see [4]).

- Let X be a smooth, strictly convex and reflexive Banach space, and let C be a nonempty closed and convex subset of X . Let $\phi : X \times X \rightarrow \mathbf{R}^+$ be the Lyapunov functional which is defined by

$$\phi(x, y) = \|x\|^2 - 2\langle x, Jy \rangle + \|y\|^2, \quad \forall x, y \in X. \quad (2.2)$$

It is obvious from the definition of ϕ that

$$(\|x\| - \|y\|)^2 \leq \phi(x, y) \leq (\|x\| + \|y\|)^2, \quad \forall x, y \in X. \quad (2.3)$$

- Following Alber [1], the generalized projection $\Pi_C : X \rightarrow C$ is defined by

$$\Pi_C(x) = \inf_{y \in C} \phi(y, x), \quad x \in X. \quad (2.4)$$

Lemma 2.1. [1] *Let X be a smooth, strictly convex and reflexive Banach space, and let C be a nonempty closed and convex subset of X . Then*

(1) $\phi(x, \Pi_C y) + \phi(\Pi_C y, y) \leq \phi(x, y)$, $\forall x \in C, y \in X$.

(2) Let $x \in X$ and $z \in C$, then

$$z = \Pi_C x \Leftrightarrow \langle z - y, Jx - Jz \rangle \geq 0, \quad \forall y \in C. \quad (2.5)$$

Remark 2.1. (i) If X is a real Hilbert space H , then $\phi(x, y) = \|x - y\|^2$ and Π_C is the metric projection P_C of H onto C .

(ii) If X is a smooth, strictly convex and reflexive Banach space, then for $x, y \in X$, $\phi(x, y) = 0$ if and only if $x = y$ (see [4]).

Lemma 2.2. [9] *Let X be a smooth and uniformly convex Banach space. Let $\{x_n\}$ and $\{y_n\}$ be sequences in X such that either $\{x_n\}$ or $\{y_n\}$ is bounded. If $\lim_{n \rightarrow \infty} \phi(x_n, y_n) = 0$, then $\lim_{n \rightarrow \infty} \|x_n - y_n\| = 0$.*

Now we consider the following non-smooth composite optimization problem: find a point $x^* \in C$ such that

$$f(x^*) + g(x^*) = \min_{x \in C} \{f(x) + g(x)\}, \quad (2.6)$$

where C is a nonempty closed convex subset in a real Banach space X and $f, g : C \rightarrow (-\infty, +\infty]$ are proper convex and lower semi-continuous. If we set

$$\Theta(x, y) := f(y) - f(x), \quad (2.7)$$

then problem (2.6) is equivalent to the problem of finding $x^* \in C$ such that

$$\Theta(x^*, y) + g(y) - g(x^*) \geq 0, \quad \forall y \in C. \quad (2.8)$$

Setting

$$F(x, y) := \Theta(x, y) + g(y) - g(x), \quad \forall x, y \in C. \quad (2.9)$$

we show that the function $F(x, y) : C \times C \rightarrow (-\infty, +\infty]$ has the following properties:

(A1) $F(x, x) = 0$, $\forall x \in C$;

(A2) F is monotone, i.e., $F(x, y) + F(y, x) \leq 0$, $\forall x, y \in C$;

(A3) $\limsup_{t \downarrow 0} F(x + t(z - x), y) \leq F(x, y)$, $\forall x, y, z \in C$;

(A4) The function $y \mapsto F(x, y)$ is convex and lower semi-continuous.

It is easy to prove that F has the properties (A1) – (A3). Now we only prove that $F(x, \cdot)$ has the property (A4) for each $x \in C$. In fact, for each $x \in C$, we have

$$\begin{aligned} F(x, ty + (1-t)z) &= f(ty + (1-t)z) - f(x) + g(ty + (1-t)z) - g(x) \\ &\leq tf(y) + (1-t)f(z) - f(x) + tg(y) + (1-t)g(z) - g(x) \\ &= t(\Theta(x, y) + g(y) - g(x)) + (1-t)(\Theta(x, z) + g(z) - g(x)) \\ &= tF(x, y) + (1-t)F(x, z). \end{aligned}$$

The conclusion is proved.

Lemma 2.3. [3, 15] *Let X be a smooth, strictly convex and reflexive Banach space. Let C be a nonempty closed and convex subset of X and let $F : C \times C \rightarrow \mathbf{R}$ be the bifunction defined by (2.9). Let $r > 0$ and $x \in X$.*

(i) *There exists $z \in C$ such that*

$$F(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \quad y \in C; \quad (2.10)$$

(ii) Define a mapping $T_r : X \rightarrow C$ by

$$T_r(x) = \{z \in C : F(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \forall y \in C\}, x \in X. \quad (2.11)$$

Then, the following conclusions hold:

(a) T_r is single-valued;

(b) T_r is a firmly nonexpansive-type mapping, i.e., $\forall z, y \in X$,

$$\langle T_r z - T_r y, JT_r z - JT_r y \rangle \leq \langle T_r z - T_r y, Jz - Jy \rangle;$$

(c) $\text{Fix}(T_r) = \Omega$, where Ω is the solution set of problem (2.8), (i.e., the set of minimizers of problem (2.6)) and Ω is closed and convex.

(d) $\phi(q, T_r x) + \phi(T_r x, x) \leq \phi(q, x)$, $\forall q \in \text{Fix}(T_r)$.

3. MAIN RESULTS

We are in a position to give the following main result.

Theorem 3.1. Let X be a real uniformly smooth and uniformly convex Banach space. Let C be a nonempty closed and convex subset of X . Let $f, g : C \rightarrow (-\infty, +\infty]$ be two proper convex and lower semi-continuous functions, and let $F : C \times C \rightarrow (-\infty, +\infty]$ be the bifunction defined by (2.9). Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, \\ C_0 = C, \\ F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jx_n \rangle \geq 0, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad \forall n \geq 0, \end{cases} \quad (3.1)$$

where $J : E \rightarrow E^*$ is the normalized duality mapping, $\{r_n\}$ is a sequence of positive numbers with $r_n \geq r > 0$. If Ω (the set of minimizers of problem (2.6)) is nonempty, then $\{x_n\}$ converges strongly to $\Pi_\Omega(x_0)$, which is a minimizer of problem (2.6).

Proof. We divide the proof into six parts.

(I) We prove that $C_n, \forall n \geq 0$, is a closed and convex subset of C .

In fact, since $C_0 = C$, we assert that C_0 is closed convex. By induction, if for some $n \geq 1$, C_n is closed and convex. We now prove that C_{n+1} is also closed and convex. Indeed,

$$\phi(v, u_n) \leq \phi(v, x_n) \Leftrightarrow 2\langle v, Jx_n - Ju_n \rangle \leq \|u_n\|^2 + \|x_n\|^2.$$

This implies that C_{n+1} is closed and convex.

(II) We prove that $\Omega \subset C_n$ for each $n \geq 0$.

In fact, it is obvious that $\Omega \subset C_0$. If for some $n \geq 1$, we have $\Omega \subset C_n$. We next prove that $\Omega \subset C_{n+1}$.

Indeed, it follows from Lemma 2.3 (ii) (a)-(d) and (3.1) that $u_n = T_{r_n}(x_n)$ and $\text{Fix}(T_{r_n}) = \Omega$. Therefore, for each $u \in \Omega \subset C_n$, we have

$$\phi(u, u_n) = \phi(u, T_{r_n}(x_n)) \leq \phi(u, x_n),$$

i.e., $u \in C_{n+1}$. This implies that $\Omega \subset C_{n+1}$. Summing up the above arguments, $\{C_n\}_{n=0}^\infty$ is a sequence of nonempty closed and convex subsets in C . Therefore the sequence $\{x_n\}$ is well defined.

(III) We prove that $\{x_n\}$ is bounded

In fact, it follows from (3.1) that $x_n = \Pi_{C_n}(x_0)$, $\forall n \geq 0$. For any given $u \in \Omega$, we have

$$\phi(x_n, x_0) = \phi(\Pi_{C_n}(x_0), x_0) \leq \phi(u, x_0) - \phi(u, \Pi_{C_n}(x_0)) \leq \phi(u, x_0), \quad \forall n \geq 0. \quad (3.2)$$

This implies that $\{\phi(x_n, x_0)\}$ is bounded. By virtue of (2.3), we have that $\{x_n\}$ is bounded.

(IV) We prove that $\{x_n\}$ is a Cauchy sequence.

Since $x_{n+1} = \Pi_{C_{n+1}}x_0 \in C_n$ and $x_n = \Pi_{C_n}x_0$. From the definition of Π_{C_n} , we have

$$\phi(x_n, x_0) \leq \phi(x_{n+1}, x_0), \quad \forall n \geq 0.$$

This shows that $\{\phi(x_n, x_0)\}$ is nondecreasing and bounded. Hence $\lim_{n \rightarrow \infty} \phi(x_n, x_0)$ exists. By Lemma 2.1 (1), for any given positive integer m , we have

$$\begin{aligned} \phi(x_{n+m}, x_n) &= \phi(x_{n+m}, \Pi_{C_n}x_0) \leq \phi(x_{n+m}, x_0) - \phi(\Pi_{C_n}x_0, x_0) \\ &= \phi(x_{n+m}, x_0) - \phi(x_n, x_0), \quad \forall n \geq 0. \end{aligned}$$

This implies that

$$\lim_{n \rightarrow \infty} \phi(x_{n+m}, x_n) = 0, \quad \forall m \geq 1.$$

By Remark 2.1, we have

$$\lim_{n \rightarrow \infty} \|x_{n+m} - x_n\| = 0, \quad \forall m \geq 1, \quad (3.3)$$

i.e., $\{x_n\}$ is a Cauchy sequence in C . Without loss of the generality, we may assume that

$$\lim_{n \rightarrow \infty} x_n = p \in C. \quad (3.4)$$

(V) We prove that $x_n \rightarrow p \in \Omega$.

Since $x_{n+1} = \Pi_{C_{n+1}}x_0 \in C_{n+1} \subset C_n$, it follows from the definition of C_{n+1} , we have

$$\phi(x_{n+1}, u_n) \leq \phi(x_{n+1}, x_n), \quad \forall n \geq 0. \quad (3.5)$$

Since X is uniformly smooth and uniformly convex, it follows from (3.3)-(3.5) and Lemma 2.3 that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - u_n\| = \lim_{n \rightarrow \infty} \|x_n - u_n\| = 0. \quad (3.6)$$

This implies that

$$\lim_{n \rightarrow \infty} \frac{\|Ju_n - Jx_n\|}{r_n} \leq \lim_{n \rightarrow \infty} \frac{\|Ju_n - Jx_n\|}{r} = 0. \quad (3.7)$$

Since $F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jx_n \rangle \geq 0$, $\forall y \in C$, by condition (A1), we have

$$\frac{1}{r_n} \langle y - u_n, Ju_n - Jx_n \rangle \geq -F(u_n, y) \geq H(y, u_n), \quad \forall y \in C. \quad (3.8)$$

Let $n \rightarrow \infty$ in (3.8). It follows from (3.7) and $y \mapsto F(x, y)$ is convex and lower semi-continuous that $H(y, p) \leq 0$, $\forall y \in C$. For each $t \in (0, 1]$ and each $y \in C$, let $y_t = ty + (1-t)p$. Hence $y_t \in C$ and $F(y_t, p) \leq 0$. By conditions (A1) and (A4), we have

$$0 = F(y_t, y_t) \leq tF(y_t, y) + (1-t)F(y_t, p) \leq tF(y_t, y).$$

Dividing both sides by t , we have $F(y_t, y) \geq 0$, $\forall y \in C$. Letting $t \downarrow 0$, we have by condition (A3) that $F(p, y) \geq 0$, $\forall y \in C$, i.e., $p \in \Omega$.

(VI) We prove that $x_n \rightarrow p = \Pi_\Omega(x_0)$, i.e., p is the unique minimizer of Problem (2.6).

Letting $w = \Pi_\Omega(x_0)$, we have $w \in \Omega \subset C_{n+1}$, for each $n \geq 0$ and $x_{n+1} = \Pi_{C_{n+1}}x_0$. Therefore,

$$\begin{aligned}\phi(x_{n+1}, x_0) &\leq \phi(w, x_0), \quad \forall n \geq 0, \text{ i.e.,} \\ \phi(p, x_0) &= \lim_{n \rightarrow \infty} \phi(x_n, x_0) \leq \phi(w, x_0).\end{aligned}\tag{3.9}$$

By the definition of $\Pi_\Omega(x_0)$ and (3.9) we have $w = p$, i.e., $\lim_{n \rightarrow \infty} x_n = p = \Pi_\Omega(x_0)$, which is a minimizer of problem (2.6). This completes the proof of Theorem 3.1. \square

Now we consider the following composite optimization problem in Hilbert space H :

$$\min_{x \in C} \{f(x) + g(x)\},\tag{3.10}$$

where C is a nonempty closed and convex subset of H and $f, g : C \rightarrow (-\infty, +\infty]$ are two proper convex and lower semi-continuous functions.

The following result can be obtained from Theorem 3.1 immediately.

Corollary 3.1. *Let H, C, f, g be the same as in Theorem 3.1. Let $F : C \times C \rightarrow (-\infty, +\infty]$ be the bifunction defined by (2.9). Let $\{x_n\}$ be the sequence generated by*

$$\begin{cases} x_0 \in C, C_0 = C, \\ F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \\ C_{n+1} = \{v \in C_n : \|v - u_n\|^2 \leq \|v - x_n\|^2\}, \\ x_{n+1} = \text{Proj}_{C_{n+1}} x_0, \end{cases} \quad \forall n \geq 0$$

where $\text{Proj}_C : H \rightarrow C$ is the metric projection, $\{r_n\}$ is a sequence of positive numbers with $r_n \geq r > 0$. If Γ (the set of minimizers of problem (3.10)) is nonempty, then $\{x_n\}$ converges strongly to $\text{Proj}_\Gamma(x_0)$, which is a minimizer of problem (3.1).

Acknowledgments

The authors are grateful to the reviewers for useful suggestions which improved this paper. This paper was supported by the Scientific Research Fund of Science and Technology Department of Sichuan Province, China (grant No.2018JY0340).

REFERENCES

- [1] Y.I. Alber, Metric and generalized projection operators in Banach spaces: properties and applications. Theory and Applications of Nonlinear Operators of Accretive and Monotone Type (ed. Kartosator, A. G.), Marcel Dekker, New York, 15-50 (1996)
- [2] A. Beck, M. Teboulle, A fast iterative shrinkage-thresholding algorithm for linear inverse problems, SIAM J. Imaging Sci. 2 (2009), 183-202.
- [3] E. Blum, W. Oettli, From optimization and variational inequalities to equilibrium problems, Math. Stud. 63 (1994), 123-145.
- [4] I. Cioranescu, Geometry of Banach Spaces, Duality Mappings and Nonlinear Problems, Kluwer Academic Publishers, Dordrecht (1990).

- [5] S.S. Chang, C.F. Wen, J.C. Yao, Common zero point for a finite family of inclusion problems of accretive mappings in Banach spaces, *Optimization*, 67 (2018), 1183-1196.
- [6] S.S. Chang, C.F. Wen, J.C. Yao, Forward-backward splitting method for solving a system of quasi-variational inclusions, *Bull. Malays. Math. Sci. Soc.* (2018). doi: 10.1007/s40840-017-0599-0.
- [7] S.Y. Cho, X. Qin, L. Wang, Strong convergence of a splitting algorithm for treating monotone operators, *Fixed Point Theory Appl.* 2014 (2014), Article ID 94.
- [8] Y. Guo, W. Cui, Strong convergence and bounded perturbation resilience of a modified proximal gradient algorithm, *J. Inequal. Appl.* 2018 (2018), Article ID 103.
- [9] S. Kamimura, W. Takahashi, Strong convergence of a proximal-type algorithm in a Banach space, *SIAM J. Optim.* 13 (2002), 938-945.
- [10] L. Liu, A hybrid steepest descent method for solving split feasibility problems involving nonexpansive mappings, *J. Nonlinear Convex Anal.* 20 (2019), 471-488.
- [11] Y. Malitsky, Proximal extrapolated gradient methods for variational inequalities, *Optim. Methods Software*, 33 (2018), 140-164.
- [12] X. Qin, S.Y. Cho, L. Wang, A regularization method for treating zero points of the sum of two monotone operators, *Fixed Point Theory Appl.* 2014 (2014), Article ID 75.
- [13] X. Qin, J.C. Yao, Projection splitting algorithms for nonself operators, *J. Nonlinear Convex Anal.* 18 (2017), 925-935.
- [14] S. Sabach, S. Shtern, A first order method for solving convex bi-level optimization problems, *SIAM J. Optim.* 27 (2017), 640-660.
- [15] W. Takahashi, K. Zembayashi, Strong and weak convergence theorems for equilibrium problems and relatively nonexpansive mappings in Banach spaces. *Nonlinear Anal.* 70 (2008), 45-57.
- [16] H.K. Xu, Averaged mappings and the gradient-projection algorithm, *J. Optim. Theory Appl.* 150 (2011), 360-378.
- [17] H.K. Xu, Properties and iterative methods for the lasso and its variants, *Chin. Ann. Math., Ser. B* 35 (2014), 501-518.
- [18] H.K. Xu, Bounded perturbation resilience and superiorization techniques for the projected scaled gradient method, *Inverse Probl.* 33 (2017), Article ID 044008.
- [19] J. Yunier, B. Cruz, On proximal subgradient splitting method for minimizing the sum of two nonsmooth convex functions, *Set-Valued Var. Anal.* 25 (2017), 245-263.
- [20] I. Yamada, M. Yukawa, M. Yamagishi, Minimizing the Moreau envelope of nonsmooth convex functions over the fixed point set of certain quasi-nonexpansive mappings, in *Fixed- Point Algorithms for Inverse Problems in Science and Engineering*, Springer New York, 2011, pp. 345-390.
- [21] X. Zhao, K.F. Ng, C. Li, J.C. Yao, Linear regularity and linear convergence of projection-based methods for solving convex feasibility problems, *Appl. Math. Optim.* 78 (2018), 613-641.