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# EXISTENCE OF RADIAL SIGN-CHANGING SOLUTIONS FOR FRACTIONAL KIRCHHOFF-TYPE PROBLEMS IN $\mathbb{R}^{3}$ 

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#### Abstract

In this paper, the following fractional Kirchhoff-type problem $$
\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x\right)(-\Delta)^{s} u+V(x) u=f(x, u), x \in \mathbb{R}^{3},
$$ where $a, b>0$ are constants, $s \in\left(\frac{3}{4}, 1\right), 2_{s}^{*}=\frac{6}{3-2 s}, V: \mathbb{R}^{3} \rightarrow \mathbb{R}$ is a continuous function, and $f: \mathbb{R}^{3} \times \mathbb{R} \rightarrow$ $\mathbb{R}$ is a continuous function, is considered. It is demonstrated that the fractional Kirchhoff-type equation has a radial sign-changing solution $u_{b}$ and a radial solution $\bar{u}_{b}$ when $f$ does not satisfy the subcritical growth condition and the usual Nehari-type monotonicity condition. The main tools are the constraint variational method and some analysis techniques.


Keywords. Fractional Kirchhoff type problems; Sign-changing solution; Variational method.

## 1. Introduction and Main Results

This paper is concerned with the existence of radial sign-changing solutions for the following fractional Kirchhoff-type problem

$$
\begin{equation*}
\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x\right)(-\Delta)^{s} u+V(x) u=f(x, u), x \in \mathbb{R}^{3}, \tag{1.1}
\end{equation*}
$$

where $a$ and $b$ are positive parameters, $s \in\left(\frac{3}{4}, 1\right)$, and $2_{s}^{*}=\frac{6}{3-2 s}$ is the Sobolev embedding exponent. The fractional Laplacian operator $(-\Delta)^{s}$ is defined by

$$
(-\Delta)^{s} u=C_{3, s} P . V \cdot \int_{\mathbb{R}^{3}} \frac{u(x)-u(y)}{|x-y|^{3+2 s}} d y=-\frac{C_{3, s}}{2} \int_{\mathbb{R}^{3}} \frac{u(x+y)+u(x-y)-2 u(x)}{|y|^{3+2 s}} d y, u \in \mathscr{S}\left(\mathbb{R}^{3}\right),
$$

where $C_{3, s}$ is a normalization constant depending on 3 and $s, P . V$. stands for the Cauchy principal value of the integration, and $\mathscr{S}\left(\mathbb{R}^{3}\right)$ is the Schwartz space of rapidly decaying functions.

For the potential $V(x)$, we impose the following conditions:

[^0]$\left(V_{1}\right) V \in \mathscr{C}\left(\mathbb{R}^{3}\right)$ satisfies $\inf _{x \in \mathbb{R}^{3}} V(x) \geq V_{0}>0$, where $V_{0}$ is a positive constant; $V(x)=$ $V(|x|)$, and the operator $(-\Delta)^{s}+V(x): H^{s}\left(\mathbb{R}^{3}\right) \rightarrow H^{-s}\left(\mathbb{R}^{3}\right)$ satisfies
$$
\inf _{u \in H^{s}\left(\mathbb{R}^{3}\right),\|u\|_{2}=1} \int_{\mathbb{R}^{3}}\left(a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V(x) u^{2}\right) \mathrm{d} x>0
$$
$\left(V_{2}\right)$ there exists a sequence $\left\{t_{n}\right\} \subset(0, \infty)$ such that $t_{n} \rightarrow \infty$ and $\sup _{x \in \mathbb{R}^{3}, n \in \mathbb{N}} \frac{V\left(t_{n} x\right)}{t_{n}^{5-4 s} V(x)}<\infty$.
For the nonlinearity $f$, we assume that:
$\left(F_{1}\right) f(x, t)=o(|t|)$ as $t \rightarrow 0$ uniformly in $x \in \mathbb{R}^{3}$;
$\left(F_{2}\right) f \in \mathscr{C}\left(\mathbb{R}^{3} \times \mathbb{R}, \mathbb{R}\right)$, and $\lim _{|t| \rightarrow \infty} \frac{f(x, t)}{t^{2} \xi^{*}-1}=0$ uniformly in $x \in \mathbb{R}^{3}$;
$\left(F_{3}\right) \lim _{|t| \rightarrow \infty} \frac{|t|^{4 s-3} f(x, t)}{t^{3}}=+\infty$ uniformly in $x \in \mathbb{R}^{3}$;
$\left(F_{4}\right) \frac{f(x, t)-V(x) t}{|t|^{3}}$ is nondecreasing in $t$ on both $(-\infty, 0)$ and $(0, \infty)$ for every $x \in \mathbb{R}^{3}$.
In (1.1), if we set $s=1, V(x)=0$, and replace $\mathbb{R}^{3}$ by a bounded domain $\Omega \subset \mathbb{R}^{N}$, respectively, we gave the following Dirichlet problem of Kirchhoff type:
\[

$$
\begin{cases}-\left(a+b \int_{\Omega}|\nabla u|^{2} \mathrm{~d} x\right) \Delta u=f(x, u) & \text { in } \Omega  \tag{1.2}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$
\]

In recent years, the following fractional Kirchhoff type equation:

$$
-\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x\right)(-\Delta)^{s} u=f(u), x \in \mathbb{R}^{N}
$$

was studied extensively by using various nonlinear analytical methods. We refer to [1] when $f$ is subcritical growth, and to [2] for the critical nonlinearity $f$. For more existence results of fractional Kirchhoff type problems, we refer to $[3,4,5,6,7,8,9,10,11,12]$ and the references therein.

When $a=1$ and $b=0$, then problem (1.1) reduces to the following fractional Schrödinger equation

$$
\begin{equation*}
(-\Delta)^{s} u+V(x) u=f(x, u) \text { in } \mathbb{R}^{N} \tag{1.3}
\end{equation*}
$$

This was proposed by Laskin [13] in fractional quantum mechanics as a result of the extension of Feynman integrals from the Brownian like to the Lèvy like quantum mechanical paths. For the existence, the multiplicity, and the behavior of solutions to (1.3), we refer the reader to $[14,15,16,17,18]$ and the references therein.

In recent years, Cheng and Gao [19] studied the existence and asymptotic behavior of signchanging solutions for (1.1), where $f$ satisfies $\left(F_{1}\right)$ and the following assumptions:
$\left(F_{2^{\prime}}\right) f \in \mathscr{C}\left(\mathbb{R}^{3} \times \mathbb{R}, \mathbb{R}\right)$ and there exist $C_{0}>0$ and $2<p<2_{s}^{*}$ such that $|f(x, t)| \leq C_{0}(1+$ $\left.|t|^{p-1}\right), \forall(x, t) \in \mathbb{R}^{3} \times \mathbb{R} ;$
$\left(F_{3^{\prime}}\right) \lim _{|t| \rightarrow \infty} \frac{f(x, t)}{t^{3}}=+\infty$ uniformly in $x \in \mathbb{R}^{3}$;
$\left(F_{4^{\prime}}\right) \frac{f(x, t)}{\mid t t^{3}}$ is nondecreasing in $t$ on both $(-\infty, 0)$ and $(0, \infty)$ for every $x \in \mathbb{R}^{3}$.
Recently, Chen, Tang and Liao [20] proved the existence of radial sign-changing solutions of (1.1) when $f$ satisfies $\left(F_{1}\right),\left(F_{2^{\prime}}\right),\left(F_{3}\right)$, and $\left(F_{4}\right)$. The inspiration of this paper mainly comes from [20]. It is worthwhile pointing out that, under our assumptions, condition ( $F_{2}$ ) is weaker than condition $\left(F_{2^{\prime}}\right)$. The main purpose of this paper is to study the existence of radial
sign-changing solutions of problem (1.1) when $f$ does not satisfy the subcritical growth condition and the usual Nehari-type monotonicity condition. Based on the constraint variational method and some analysis techniques, we prove the same result under more generic conditions, which generalizes the results presented in [20]. From the technical points of view, the difficulty in finding sign-changing solutions of (1.1) results from two nonlocal terms: $(-\Delta)^{s} u$ and $\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2}(-\Delta)^{s} u$. In this sense, (1.1) is different from the classical case $s=1$ and the methods of finding sign-changing solutions for (1.3) with $s \in(0,1]$, and (1.2) cannot be directly applied to (1.1). This gives rise to some mathematical difficulties that make the study of the sign-changing solutions for (1.1) particularly interesting. In this paper, by combining the constraint variational method with some new inequalities, we prove that (1.1) with $b \geq 0$ has a radial sign-changing solution $u_{b}$ and a radial solution $\bar{u}_{b}$.

Before stating our main result, let us consider the fractional Laplacian in the weak sense. As a rule, for any $s \in(0,1)$, we have

$$
\int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} v=C_{3, s} \int_{\mathbb{R}^{3}} \int_{\mathbb{R}^{3}} \frac{[u(x)-u(y)][v(x)-v(y)]}{|x-y|^{3+2 s}} \mathrm{~d} x \mathrm{~d} y
$$

and

$$
\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2}=C_{3, s} \int_{\mathbb{R}^{3}} \int_{\mathbb{R}^{3}} \frac{[u(x)-u(y)]^{2}}{|x-y|^{3+2 s}} \mathrm{~d} x \mathrm{~d} y,
$$

and define the fractional Sobolev space $H^{s}\left(\mathbb{R}^{3}\right)$ as follows $H^{s}\left(\mathbb{R}^{3}\right)=\left\{u \in L^{2}\left(\mathbb{R}^{3}\right):(-\Delta)^{\frac{s}{2}} u \in\right.$ $\left.L^{2}\left(\mathbb{R}^{3}\right)\right\}$, equipped with the scalar product $(u, v)_{H^{s}\left(\mathbb{R}^{3}\right)}=\int_{\mathbb{R}^{3}}\left[(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} v+u v\right] \mathrm{d} x$, and the corresponding norm

$$
\|u\|_{H^{s}\left(\mathbb{R}^{3}\right)}=\left(\int_{\mathbb{R}^{3}}\left[\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+u^{2}\right] \mathrm{d} x\right)^{\frac{1}{2}}
$$

Throughout this paper, we define $H_{r}^{s}\left(\mathbb{R}^{3}\right)=\left\{u \in H^{s}\left(\mathbb{R}^{3}\right): u(x)=u(|x|)\right\}$, and denote the fractional Sobolev space for (1.1) by $H=\left\{u \in H_{r}^{s}\left(\mathbb{R}^{3}\right): \int_{\mathbb{R}^{3}} V(x) u^{2} \mathrm{~d} x<\infty\right\}$, where the scalar product is given by $(u, v)=\int_{\mathbb{R}^{3}}\left[a(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} v+V(x) u v\right] \mathrm{d} x$, and the associated norm is

$$
\|u\|=\left(\int_{\mathbb{R}^{3}}\left[a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V(x) u^{2}\right] \mathrm{d} x\right)^{\frac{1}{2}}
$$

Under the condition $\left(V_{1}\right)$ and $a>0$, the embedding $H \hookrightarrow H_{r}^{s}\left(\mathbb{R}^{3}\right)$ is continuous. We know from [21] that the embedding $H \hookrightarrow L^{q}\left(\mathbb{R}^{3}\right)$ is compact for $2<q<2_{s}^{*}$ when $s \in(0,1)$.

We say that $u \in H$ is a weak solution to (1.1) if

$$
\begin{align*}
0= & \left\langle I_{b}^{\prime}(u), \varphi\right\rangle \\
= & \int_{\mathbb{R}^{3}}\left[a(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} \varphi+V(x) u(x) \varphi(x)\right] \mathrm{d} x  \tag{1.4}\\
& +b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} \varphi \mathrm{~d} x-\int_{\mathbb{R}^{3}} f(x, u) \varphi(x) \mathrm{d} x
\end{align*}
$$

for any $\varphi \in H$. We will omit weak throughout this paper for convenience. Define the corresponding energy functional $I_{b}: H \rightarrow \mathbb{R}$ to problem (1.1) as below:

$$
\begin{equation*}
I_{b}(u)=\frac{1}{2} \int_{\mathbb{R}^{3}}\left[a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V(x) u^{2}\right] \mathrm{d} x+\frac{b}{4}\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x\right)^{2}-\int_{\mathbb{R}^{3}} F(x, u) \mathrm{d} x . \tag{1.5}
\end{equation*}
$$

Analogously to [22, 23, 24, 25], also in the case that the nonlinear term does not satisfy the subcritical growth condition, by $\left(F_{1}\right)$ and $\left(F_{2}\right)$, for any $\varepsilon>0$, there exists $C_{\varepsilon}>0$ such that $|F(x, t)| \leq \varepsilon t^{2}+C_{\varepsilon}|t|^{2_{s}^{*}}$ for all $(x, t) \in \mathbb{R}^{3} \times \mathbb{R}$. It is easy to see that $I_{b}$ belongs to $\mathscr{C}^{1}(H, \mathbb{R})$ and the critical points of $I_{b}$ are the solutions to (1.1). Furthermore, if $u \in H$ is a solution to (1.1) and $u^{ \pm} \neq 0$, we say that $u$ is a radial sign-changing solution of (1.1), where $u^{+}(x)=\max \{u(x), 0\}$ and $u^{-}(x)=\min \{u(x), 0\}$.

Our goal in this paper is to seek the sign-changing solutions of (1.1). So, we borrow some ideals from [19, 20, 26, 27, 28]. We first try to seek a minimizer of the energy functional $I_{b}$ over the following constraints:

$$
\begin{gathered}
\mathscr{M}_{b}:=\left\{u \in H: u^{ \pm} \neq 0,\left\langle I_{b}^{\prime}(u), u^{+}\right\rangle=\left\langle I_{b}^{\prime}(u), u^{-}\right\rangle=0\right\}, \\
m_{b}:=\inf _{u \in \mathscr{M}_{b}} I_{b}(u), \forall b \geq 0, \\
\mathscr{N}_{b}:=\left\{u \in H: u \neq 0,\left\langle I_{b}^{\prime}(u), u\right\rangle=0\right\} \\
c_{b}:=\inf _{u \in \mathscr{N}_{b}} I_{b}(u), \quad \forall b \geq 0
\end{gathered}
$$

and then prove that the minimizers of $m_{b}$ is radial sign-changing solutions of (1.1) and the minimizers of $c_{b}$ are ground state solutions to (1.1).

When $s=1, b=0$, and $a=1$, (1.1) turns out to be the (1.3) mentioned above. There are several ways in the literature to obtain sign-changing solution for (1.3); see [29, 30, 31, 32] and the references therein. However, there only exist few results on the sign-changing solutions of (1.1). Indeed, in the case $s \in(0,1)$, we have the following decomposition:

$$
\begin{align*}
\left\|(-\Delta)^{\frac{s}{2}} u^{+}+(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2}= & \left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+\left\|(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2} \\
& -4 C_{3, s} \int_{\mathbb{R}^{6}} \frac{u^{+}(x) u^{-}(y)}{|x-y|^{3+2 s}} \mathrm{~d} x \mathrm{~d} y, \quad \forall u \in H^{s}\left(\mathbb{R}^{3}\right) \tag{1.6}
\end{align*}
$$

Since $\left\langle u^{+}, u^{-}\right\rangle_{H^{s}\left(\mathbb{R}^{3}\right)}>0$ when $u^{ \pm} \neq 0$, a straightforward computation yields that

$$
\begin{gather*}
I_{b}(u)=I_{b}\left(u^{+}\right)+I_{b}\left(u^{-}\right)+2 a P\left(u^{+}, u^{-}\right)+\frac{b}{2}\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}\left\|(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2} \\
+2 b P\left(u^{+}, u^{-}\right)\left[\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+\left\|(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2}+2 P\left(u^{+}, u^{-}\right)\right] \\
>  \tag{1.7}\\
>I_{b}\left(u^{+}\right)+I_{b}\left(u^{-}\right), \\
\left\langle I_{b}^{\prime}(u), u^{+}\right\rangle>\left\langle I_{b}^{\prime}\left(u^{+}\right), u^{+}\right\rangle \text {and }\left\langle I_{b}^{\prime}(u), u^{-}\right\rangle>\left\langle I_{b}^{\prime}\left(u^{-}\right), u^{-}\right\rangle, \\
\forall u \in H, u^{+}, u^{-} \neq 0
\end{gather*}
$$

where

$$
P\left(u^{+}, u^{-}\right):=-C_{3, s} \int_{\mathbb{R}^{3}} \int_{\mathbb{R}^{3}} \frac{u^{+}(x) u^{-}(y)}{|x-y|^{3+2 s}} \mathrm{~d} x \mathrm{~d} y>0, \quad \forall u \in H, u^{+}, u^{-} \neq 0
$$

which implies that $u^{ \pm} \notin \mathscr{N}_{b}$ for $u \in \mathscr{M}_{b}$.
The main result can be stated as follows.

Theorem 1.1. Suppose that $\left(V_{1}\right)-\left(V_{2}\right)$ and $\left(F_{1}\right)-\left(F_{4}\right)$ hold. Then problem (1.1) has a radial sign-changing solution $u_{b} \in \mathscr{M}_{b}$ such that $I_{b}\left(u_{b}\right)=\inf _{\mathscr{M}_{b}} I_{b}>0$ and has a radial solution $\bar{u}_{b} \in$ $\mathscr{N}_{b}$ such that $I_{b}\left(\bar{u}_{b}\right)=\inf _{\mathscr{N}_{b}} I_{b}>0$.

Remark 1.1. We know that $\left(F_{2}\right)$ is obviously weaker than $\left(F_{2^{\prime}}\right)$. There exist functions satisfying the generalized subcritical condition $\left(F_{2}\right)$ and not satisfying the subcritical growth condition $\left(F_{2^{\prime}}\right)$. For example, for the sake of simplicity, drop the $x$-dependence. Let $F(t)=\frac{t^{2 *}}{\ln \left(e+t^{2}\right)}$. Then

$$
f(t)=\frac{2_{s}^{*} t^{2_{s}^{*}-1}\left(e+t^{2}\right) \ln \left(e+t^{2}\right)-2 t^{2_{s}^{*}+1}}{\left(e+t^{2}\right)\left(\ln \left(e+t^{2}\right)\right)^{2}}
$$

Moreover, when $\lim _{x \in \mathbb{R}^{3}} V(x) \geq 1$, there exist functions satisfying $\left(F_{3}\right)$ and $\left(F_{4}\right)$, but do not satisfy $\left(F_{3^{\prime}}\right)$ or $\left(F_{4^{\prime}}\right)$. For example, $f(x, t)=K(x) t^{3}-|t|^{\frac{3}{2}} t+|t| t$, where $K \in \mathscr{C}\left(\mathbb{R}^{3},[m, n]\right)$ with $m, n>0$. Then,

$$
\lim _{|t| \rightarrow \infty} \frac{f(x, t)}{t^{3}}=\lim _{|t| \rightarrow \infty} \frac{K(x) t^{3}-|t|^{\frac{3}{2}} t+|t| t}{t^{3}}=\lim _{|t| \rightarrow \infty} K(x)-\frac{1}{|t|^{\frac{1}{2}}}+\frac{1}{|t|}=K(x) \in[m, n] \neq+\infty,
$$

and

$$
\begin{aligned}
\lim _{|t| \rightarrow \infty} \frac{|t|^{4 s-3} f(x, t)}{t^{3}} & =\lim _{|t| \rightarrow \infty} \frac{K(x) t^{3}|t|^{4 s-3}-|t|^{4 s-\frac{3}{2}} t+|t|^{4 s-2} t}{t^{3}} \\
& =\lim _{|t| \rightarrow \infty} K(x)|t|^{4 s-3}-|t|^{4 s-\frac{7}{2}}+|t|^{4 s-4}=+\infty
\end{aligned}
$$

where $s \in\left(\frac{3}{4}, 1\right)$. Therefore, $f(x, t)$ satisfies $\left(F_{3}\right)$ but not $\left(F_{3^{\prime}}\right)$. Similarly, when $\inf _{x \in \mathbb{R}^{3}} V(x) \geq 1$, we can prove by some simple computation that $f(x, t)$ satisfies $\left(F_{4}\right)$ but not $\left(F_{4^{\prime}}\right)$.

This paper is organized as follows. In Section 2, we give the proof to Theorem 1.1 by combining the constraint variational method with some new inequalities. Throughout this paper, we use the following notations: $\|u\|_{p}$ denotes the $L^{p}$-norm of the space $L^{p}\left(\mathbb{R}^{3}\right)$ for $p \geq 2$; $B_{r}(x)=\left\{y \in \mathbb{R}^{3}:|y-x|<r\right\} ;$ and $C_{i}(i=1,2, \ldots)$ are some positive constant could change from line to line.

## 2. Proof of Theorem 1.1

Proof of theorem 1.1. The proof is split into three steps.
We first prove that, for $b \geq 0$, the following sets

$$
\begin{aligned}
\mathscr{E}_{b}:= & \left\{u \in H: b\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} u^{ \pm} \mathrm{d} x\right. \\
& \left.+\int_{\mathbb{R}^{3}}\left[V(x)\left(u^{ \pm}\right)^{2}-f\left(x, u^{ \pm}\right) u^{ \pm}\right] \mathrm{d} x<0\right\}
\end{aligned}
$$

and

$$
\overline{\mathscr{E}}_{b}:=\left\{u \in H: b\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{4}+\int_{\mathbb{R}^{3}}\left[V(x) u^{2}-f(x, u) u\right] \mathrm{d} x<0\right\}
$$

are not empty by scaling technique (see [20, Lemma 2.5]).

STEP 1. for each $u \in \mathscr{E}_{b}$, there is a unique pair $\left(\alpha_{u}, \beta_{u}\right) \in\left(\mathbb{R}^{+} \times \mathbb{R}^{+}\right)$such that $\alpha_{u} u^{+}+\beta_{u} u^{-} \in$ $\mathscr{M}_{b}$; and for each $u \in \overline{\mathscr{E}}_{b}$, there is a unique $\bar{\beta}_{u}>0$ such that $\bar{\beta}_{u} u \in \mathscr{N}_{b}$.

To prove STEP 1, let us first prove $\mathscr{M}_{b} \neq \emptyset$. Let

$$
\begin{align*}
g_{1}(\alpha, \beta)= & \left\langle I_{b}^{\prime}\left(\alpha u^{+}+\beta u^{-}\right), \alpha u^{+}\right\rangle \\
= & a \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)(-\Delta)^{\frac{s}{2}} \alpha u^{+} \mathrm{d} x \\
& +\int_{\mathbb{R}^{3}}\left[V(x)\left(\alpha u^{+}\right)^{2}-f\left(x, \alpha u^{+}\right) \alpha u^{+}\right] \mathrm{d} x \\
& +b\left\|(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}\right) \mathrm{d} x \tag{2.1}
\end{align*}
$$

and

$$
\begin{align*}
g_{2}(\alpha, \beta)= & \left\langle I_{b}^{\prime}\left(\alpha u^{+}+\beta u^{-}\right), \beta u^{-}\right\rangle \\
= & a \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)(-\Delta)^{\frac{s}{2}} \beta u^{-} \mathrm{d} x \\
& +\int_{\mathbb{R}^{3}}\left[V(x)\left(\beta u^{-}\right)^{2}-f\left(x, \beta u^{-}\right) \beta u^{-}\right] \mathrm{d} x \\
& +b\left\|(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}}\left(\alpha u^{+}+\beta u^{-}\right)(-\Delta)^{\frac{s}{2}}\left(\beta u^{-}\right) \mathrm{d} x . \tag{2.2}
\end{align*}
$$

By $\left(F_{4}\right)$, one has $f(x, \alpha \tau) \alpha \tau \geq f(x, \tau) \tau \alpha^{4}-V(x)\left(\alpha^{2}-1\right)(\alpha \tau)^{2}$ for all $x \in \mathbb{R}^{3}, \alpha \geq 1, \tau \in \mathbb{R}$, which implies

$$
\begin{equation*}
\int_{\mathbb{R}^{3}}\left[V(x)\left(\alpha u^{+}\right)^{2}-f\left(x, \alpha u^{+}\right) \alpha u^{+}\right] \mathrm{d} x \leq \alpha^{4} \int_{\mathbb{R}^{3}}\left[V(x)\left(u^{+}\right)^{2}-f\left(x, u^{+}\right) u^{+}\right] \mathrm{d} x, \forall \alpha \geq 1 . \tag{2.3}
\end{equation*}
$$

From (2.1) and (2.3), we derive that

$$
\begin{align*}
g_{1}(\alpha, \alpha)= & a \alpha^{2}\left[\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+2 P\left(u^{+}, u^{-}\right)\right]+b \alpha^{4} \phi\left(u, u^{+}\right) \\
& +\int_{\mathbb{R}^{3}}\left[V(x)\left(\alpha u^{+}\right)^{2}-f\left(x, \alpha u^{+}\right) \alpha u^{+}\right] \mathrm{d} x \\
\leq & a \alpha^{2}\left[\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+2 P\left(u^{+}, u^{-}\right)\right]+\alpha^{4}\left\{b \phi\left(u, u^{+}\right)\right. \\
& \left.+\int_{\mathbb{R}^{3}}\left[V(x)\left(u^{+}\right)^{2}-f\left(x, u^{+}\right) u^{+}\right] \mathrm{d} x\right\}, \forall \alpha \geq 1 \tag{2.4}
\end{align*}
$$

where

$$
\phi\left(u, u^{+}\right):=\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} u^{+} \mathrm{d} x, \quad \forall u \in H .
$$

Using (2.4), it is easy to prove that $g_{1}(\alpha, \alpha)<0$ for $\alpha$ large due to $u \in \mathscr{E}_{b}$. Similarly, we have $g_{2}(\beta, \beta)<0$ for $\beta$ large. Combining (2.1) with (2.2), we prove that there exists $r \in(0, R)$ such that

$$
\begin{equation*}
g_{1}(r, r)>0, \quad g_{1}(R, R)<0 ; \quad g_{2}(r, r)>0, \quad g_{2}(R, R)<0 \tag{2.5}
\end{equation*}
$$

From (2.1) and (2.2), we have that $g_{1}(\alpha, \cdot)$ is increasing for any fixed $\alpha>0$, and $g_{2}(\cdot, \beta)$ is increasing for any fixed $\beta>0$. Hence, it follows from (2.1), (2.2), and (2.5) that

$$
g_{1}(r, \beta)>g_{1}(r, r)>0, g_{1}(R, \beta)<g_{1}(R, R)<0, \quad \forall \beta \in[r, R],
$$

and

$$
g_{2}(\alpha, r)>g_{2}(r, r)>0, g_{2}(\alpha, R)<g_{2}(R, R)<0, \quad \forall \alpha \in[r, R] .
$$

Therefore, by applying Miranda's Theorem [33], there exists some point $\left(\alpha_{u}, \beta_{u}\right) \in[r, R] \times[r, R]$ such that $g_{1}\left(\alpha_{u}, \beta_{u}\right)=g_{2}\left(\alpha_{u}, \beta_{u}\right)=0$. So, $\alpha_{u} u^{+}+\beta_{u} u^{-} \in \mathscr{M}_{b}$.

Now, we prove the uniqueness of the pair $\left(\alpha_{u}, \beta_{u}\right)$. Let $\left(\alpha_{1}, \beta_{1}\right)$ and $\left(\alpha_{2}, \beta_{2}\right)$ such that $\alpha_{i} u^{+}+$ $\beta_{i} u^{-} \in \mathscr{M}_{b}, i=1,2$. In view of [20, Lemma 2.2], one has

$$
\begin{aligned}
& I_{b}\left(\alpha_{1} u^{+}+\beta_{1} u^{-}\right) \\
& \geq I_{b}\left(\alpha_{2} u^{+}+\beta_{2} u^{-}\right)+\frac{a\left(\alpha_{1}^{2}-\alpha_{2}^{2}\right)^{2}}{\alpha_{1}^{2}}\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+\frac{a\left(\beta_{1}^{2}-\beta_{2}^{2}\right)^{2}}{\beta_{1}^{2}}\left\|(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2},
\end{aligned}
$$

and

$$
\begin{aligned}
& I_{b}\left(\alpha_{2} u^{+}+\beta_{2} u^{-}\right) \\
& \geq I_{b}\left(\alpha_{1} u^{+}+\beta_{1} u^{-}\right)+\frac{a\left(\alpha_{1}^{2}-\alpha_{2}^{2}\right)^{2}}{\alpha_{2}^{2}}\left\|(-\Delta)^{\frac{s}{2}} u^{+}\right\|_{2}^{2}+\frac{a\left(\beta_{1}^{2}-\beta_{2}^{2}\right)^{2}}{\beta_{2}^{2}}\left\|(-\Delta)^{\frac{s}{2}} u^{-}\right\|_{2}^{2}
\end{aligned}
$$

The above inequalities imply $\left(\alpha_{1}, \beta_{1}\right)=\left(\alpha_{2}, \beta_{2}\right)$.
Furthermore, we let $g(\beta)=\left\langle I_{b}^{\prime}(\beta u), \beta u\right\rangle$ for $u \in \overline{\mathscr{E}}_{b}$. From (1.4) and (F4), we derive that

$$
g(\beta) \leq a \beta^{2}\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2}+\beta^{4}\left\{b\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{4}+\int_{\mathbb{R}^{3}}\left[V(x) u^{2}-f(x, u) u\right] \mathrm{d} x\right\}, \forall \beta \geq 1,
$$

which demonstrates that there exists $R_{0}>0$ sufficiently large such that $g\left(R_{0}\right)<0$. Choosing $r_{0}>0$ sufficiently small, we see that $g\left(r_{0}\right) \geq 0$. Thus there exists $\bar{\beta}_{u}>0$ such that $g\left(\bar{\beta}_{u}\right)=0$ for $u \in \overline{\mathscr{E}}_{b}$. Similarly, we can deduce that $\bar{\beta}_{u}$ is unique. So we obtain that, for $u \in \overline{\mathscr{E}}_{b}$, there exists a unique $\bar{\beta}_{u}>0$ such that $\bar{\beta}_{u} u \in \mathscr{N}_{b}$. The proof of STEP 1 is complete.

STEP 2. $m_{b}=\inf _{u \in \mathscr{M}_{b}} I_{b}(u)>0$ and $c_{b}=\inf _{u \in \mathscr{N}_{b}} I_{b}(u)>0$ are achieved.
By $\left(F_{1}\right)$ and $\left(F_{2}\right)$, we see that, for every $\varepsilon>0$, there exists $C_{\varepsilon}>0$ such that

$$
\begin{equation*}
|f(x, t) t| \leq \varepsilon t^{2}+C_{\varepsilon}|t|^{2_{s}^{*}},|F(x, t)| \leq \varepsilon t^{2}+C_{\mathcal{E}}|t|^{2_{s}^{*}}, \quad \forall(x, t) \in \mathbb{R}^{3} \times \mathbb{R} . \tag{2.6}
\end{equation*}
$$

By $\left(V_{1}\right)$, there exists $\gamma_{0}>0$ such that

$$
\begin{equation*}
\gamma_{0}\|u\|_{H^{s}\left(\mathbb{R}^{3}\right)}^{2} \leq\|u\|^{2}, \quad \forall u \in H . \tag{2.7}
\end{equation*}
$$

First, we prove that $m_{b}>0$ and $c_{b}>0$. For $u \in \mathscr{M}_{b}$, it follows from (1.4), (2.6), (2.7), [20, Lemma 2.1], the expression for $P\left(u^{+}, u^{-}\right)$, and [19, Lemma 2.1] that

$$
\begin{align*}
\gamma_{0}\left\|u^{ \pm}\right\|_{H^{s}\left(\mathbb{R}^{3}\right)}^{2} \leq\left\|u^{ \pm}\right\|^{2} \leq & a\left\|(-\Delta)^{\frac{s}{2}}\left(u^{ \pm}\right)\right\|_{2}+2 a P\left(u^{+}, u^{-}\right)+\int_{\mathbb{R}^{3}} V(x)\left(u^{ \pm}\right)^{2} \mathrm{~d} x \\
& +b\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u(-\Delta)^{\frac{s}{2}} u^{ \pm} \mathrm{d} x \\
= & \int_{\mathbb{R}^{3}} f\left(x, u^{ \pm}\right) u^{ \pm} \mathrm{d} x \\
\leq & \frac{\gamma_{0}}{2}\left\|u^{ \pm}\right\|_{2}^{2}+C_{1}\left\|u^{ \pm}\right\|_{2_{s}^{s}}^{2_{*}^{*}} \\
\leq & \frac{\gamma_{0}}{2}\left\|u^{ \pm}\right\|_{H^{s}\left(\mathbb{R}^{3}\right)}^{2}+C_{2_{s}^{*}}\left\|u^{ \pm}\right\|_{H^{s}\left(\mathbb{R}^{3}\right)}^{2^{*}} . \tag{2.8}
\end{align*}
$$

We can then deduce that there exists a constant $\mu>0$ independent of $b$ such that

$$
\begin{equation*}
\left\|u^{ \pm}\right\| \geq \sqrt{\gamma_{0}}\left\|u^{ \pm}\right\|_{H^{s}\left(\mathbb{R}^{3}\right)} \geq \mu, \quad \forall u \in \mathscr{M}_{b} \tag{2.9}
\end{equation*}
$$

Similarly, there exists a constant $\mu_{0}>0$ independent of $b$ such that $\|u\| \geq \sqrt{\gamma_{0}}\|u\|_{H^{s}\left(\mathbb{R}^{3}\right)} \geq \mu_{0}$, $\forall u \in \mathscr{N}_{b}$. Since $\mathscr{M}_{b} \subset \mathscr{N}_{b}$, we have $m_{b} \geq c_{b}$. Note that

$$
I_{b}(u) \geq I_{b}(t u)+\frac{1-t^{4}}{4}\left\langle I_{b}^{\prime}(u), u\right\rangle+\frac{a\left(1-t^{2}\right)^{2}}{4}\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2}, \forall u \in H, t \geq 0
$$

With $t=0$ (see [20, Lemma 2.3]), one has

$$
\begin{equation*}
I_{b}(u)=I_{b}(u)-\frac{1}{4}\left\langle I_{b}^{\prime}(u), u\right\rangle \geq \frac{a}{4}\left\|(-\Delta)^{\frac{s}{2}} u\right\|_{2}^{2}, \quad \forall u \in \mathscr{N}_{b}, \tag{2.10}
\end{equation*}
$$

which implies $c_{b}=\inf _{u \in \mathcal{N}_{b}} I_{b}(u) \geq 0$.
We now demonstrate that $c_{b}>0$. To this end, we choose $\left\{u_{n}\right\} \subset \mathscr{N}_{b}$ such that $I_{b}\left(u_{n}\right) \rightarrow c_{b}$. There are two possible cases: (1) $\inf _{n \in \mathbb{N}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}>0$ and (2) $\inf _{n \in \mathbb{N}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}=0$.

Case 1. $\inf _{n \in \mathbb{N}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}=\mu_{1}>0$.
In this case, we conclude from (2.10) that $c_{b}+o(1)=I_{b}\left(u_{n}\right) \geq \frac{a}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2} \geq \frac{a}{4} \mu_{1}^{2}$.
Case 2. $\inf _{n \in \mathbb{N}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}=0$.
Since $\left\|u_{n}\right\|^{2} \geq \mu_{0}^{2}>0$, up to a subsequence, one has

$$
\begin{equation*}
\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2} \rightarrow 0, \int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x \geq \mu_{2}>0 \text { for some constant } \mu_{2}>0 \tag{2.11}
\end{equation*}
$$

Let $t_{n}=\left[\int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x\right]^{-\frac{1}{2}}$. It follows from (2.11) that $t_{n} \leq \mu_{2}^{-\frac{1}{2}}$. By (2.6), (2.7), and the Sobolev inequality, we obtain that

$$
\begin{align*}
\left|\int_{\mathbb{R}^{3}} F\left(x, t_{n} u_{n}\right) \mathrm{d} x\right| & \leq \int_{\mathbb{R}^{3}}\left[\frac{\gamma_{0}}{4} t_{n}^{2} u_{n}^{2}+C_{3}\left|t_{n} u_{n}\right|^{2_{s}^{*}}\right] \mathrm{d} x \\
& \leq \frac{t_{n}^{2}}{4}\left\|u_{n}\right\|^{2}+C_{3}\left|t_{n}\right|^{2_{s}^{*}} S_{s}^{2_{s}^{2}} \tag{2.12}
\end{align*}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2_{s}^{*}},
$$

where

$$
S_{s}=\inf _{u \in \mathscr{D}, 2\left(\mathbb{R}^{3}\right) \backslash\{0\}} \frac{\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x}{\left(\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} \mathrm{~d} x\right)^{\frac{2}{2_{s}^{*}}}} .
$$

Since $u_{n} \in \mathscr{N}_{b}$, it follows from (1.5), (2.11), (2.12), and [20, Corollary 2.4] that

$$
\begin{aligned}
c_{b}+o(1) & =I_{b}\left(u_{n}\right) \geq I_{b}\left(t_{n} u_{n}\right) \\
& =\frac{a t_{n}^{2}}{2}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2}+\frac{t_{n}^{2}}{2} \int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x+\frac{b t_{n}^{4}}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{4}-\int_{\mathbb{R}^{3}} F\left(x, t_{n} u_{n}\right) \mathrm{d} x \\
& \geq \frac{t_{n}^{2}}{4} \int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x-C_{3}\left|t_{n}\right|^{2_{s}^{*}} S_{s}^{-\frac{2}{s}_{2}^{2}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2_{s}^{*}}=\frac{1}{4}+o(1) .
\end{aligned}
$$

Case 1 and 2 imply that $c_{b}=\inf _{u \in \mathscr{N}_{b}} I_{b}(u)>0$. Therefore, $m_{b} \geq c_{b}>0$.
Next, we prove that $m_{b}$ can be achieved. Let $\left\{u_{n}\right\} \subset \mathscr{M}_{b}$ be a minimizing sequence such that $I_{b}\left(u_{n}\right) \rightarrow m_{b}$. Then, (2.10) implies that

$$
m_{b}+o(1) \geq I_{b}\left(u_{n}\right)-\frac{1}{4}\left\langle I_{b}^{\prime}\left(u_{n}\right), u_{n}\right\rangle \geq \frac{a}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2}
$$

So $\left\{\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}\right\}$ is bounded. In order to obtain the boundedness of $\left\{u_{n}\right\}$, we have to prove that $\int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x$ is bounded. By contradiction, we assume that $\int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x \rightarrow \infty$. Let

$$
t_{n}=\frac{2\left(m_{b}+1\right)^{\frac{1}{2}}}{\left(\int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x\right)^{\frac{1}{2}}}
$$

Then $t_{n} \rightarrow 0$, and (2.12) still holds. Using (1.5), (2.12), and [20, Corollary 2.4], we have that

$$
\begin{align*}
m_{b}+o(1) & =I_{b}\left(u_{n}\right) \geq I_{b}\left(t_{n} u_{n}\right) \\
& =\frac{a t_{n}^{2}}{2}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2}+\frac{t_{n}^{2}}{2} \int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x+\frac{b t_{n}^{4}}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{4}-\int_{\mathbb{R}^{3}} F\left(x, t_{n} u_{n}\right) \mathrm{d} x \\
& \geq \frac{t_{n}^{2}}{4} \int_{\mathbb{R}^{3}} V(x) u_{n}^{2} \mathrm{~d} x-C_{3}\left|t_{n}\right|^{2_{s}^{*}} S_{s}^{-\frac{2_{s}^{*}}{2}}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2_{s}^{*}} \\
& =m_{b}+1+o(1) . \tag{2.13}
\end{align*}
$$

This contradiction demonstrates that $\left\{u_{n}\right\}$ is bounded in $H$. Up to a subsequence, we have $u_{n}^{ \pm} \rightharpoonup u_{b}^{ \pm}$weakly in $H$ and $u_{n}^{ \pm} \rightarrow u_{b}^{ \pm}$strongly in $L^{q}\left(\mathbb{R}^{3}\right)$ for $q \in\left(2,2_{s}^{*}\right)$. By [23, Lemma 2.4], we have

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} F\left(x, u_{n}^{ \pm}\right) \mathrm{d} x=\int_{\mathbb{R}^{3}} F\left(x, u_{n}^{ \pm}-u_{b}^{ \pm}\right) \mathrm{d} x+\int_{\mathbb{R}^{3}} F\left(x, u_{b}^{ \pm}\right) \mathrm{d} x+o(1) \tag{2.14}
\end{equation*}
$$

Using (2.6), we obtain

$$
\left|\int_{\mathbb{R}^{3}} F\left(x, u_{n}^{ \pm}-u_{b}^{ \pm}\right) \mathrm{d} x\right| \leq \varepsilon \int_{\mathbb{R}^{3}}\left|u_{n}^{ \pm}-u_{b}^{ \pm}\right|^{2} \mathrm{~d} x+C_{\varepsilon}\left|u_{n}^{ \pm}-u_{b}^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x=\varepsilon J_{1}+C_{\varepsilon} J_{2}
$$

where $J_{1}=\int_{\mathbb{R}^{3}}\left|u_{n}^{ \pm}-u_{b}^{ \pm}\right|^{2} \mathrm{~d} x$ and $J_{2}=\int_{\mathbb{R}^{3}}\left|u_{n}^{ \pm}-u_{b}^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x$. Since $\left\|u_{n}\right\|$ is bounded, in connection with Minkowski inequality, one has $\left|J_{1}\right| \leq C_{1}$ and $\left|J_{2}\right| \leq C_{1}$, where $C_{1}>0$. So, $\int_{\mathbb{R}^{3}} F\left(x, u_{n}^{ \pm}-\right.$ $\left.u_{b}^{ \pm}\right) \mathrm{d} x \rightarrow 0$ as $n \rightarrow \infty$. Furthermore, it follows from (2.14) that $\int_{\mathbb{R}^{3}} F\left(x, u_{n}^{ \pm}\right) \mathrm{d} x=\int_{\mathbb{R}^{3}} F\left(x, u_{b}^{ \pm}\right) \mathrm{d} x+$ $o(1)$, which implies

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} f\left(x, u_{n}^{ \pm}\right) u_{n}^{ \pm} \mathrm{d} x=\int_{\mathbb{R}^{3}} f\left(x, u_{b}^{ \pm}\right) u_{b}^{ \pm} \mathrm{d} x+o(1) . \tag{2.15}
\end{equation*}
$$

From (2.8), (2.9), and (2.15), we deduce that

$$
0<\mu^{2} \leq\left\|u_{n}^{ \pm}\right\|^{2} \leq \int_{\mathbb{R}^{3}} f\left(x, u_{n}^{ \pm}\right) u_{n}^{ \pm} \mathrm{d} x=\int_{\mathbb{R}^{3}} f\left(x, u_{b}^{ \pm}\right) u_{b}^{ \pm} \mathrm{d} x+o(1),
$$

which yields $u_{b}^{ \pm} \neq 0$. From (2.15), [20, Lemma 2.1], the weak semicontinuity of norm, and the Fatou's Lemma, we conclude that

$$
\begin{aligned}
& a\left\|(-\Delta)^{\frac{s}{2}}\left(u_{b}^{ \pm}\right)\right\|_{2}+2 a P\left(u_{b}^{+}, u_{b}^{-}\right)+\int_{\mathbb{R}^{3}} V(x)\left(u_{b}^{ \pm}\right)^{2} \mathrm{~d} x+b\left\|(-\Delta)^{\frac{s}{2}} u_{b}\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u_{b}(-\Delta)^{\frac{s}{2}} u_{b}^{ \pm} \mathrm{d} x \\
& \leq \liminf _{n \rightarrow \infty}\left[a\left\|(-\Delta)^{\frac{s}{2}}\left(u_{n}^{ \pm}\right)\right\|_{2}+2 a P\left(u_{n}^{+}, u_{n}^{-}\right)+\int_{\mathbb{R}^{3}} V(x)\left(u_{n}^{ \pm}\right)^{2} \mathrm{~d} x\right. \\
& \left.\quad+b\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2} \int_{\mathbb{R}^{3}}(-\Delta)^{\frac{s}{2}} u_{n}(-\Delta)^{\frac{s}{2}} u_{n}^{ \pm} \mathrm{d} x\right] \\
& =\liminf _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} f\left(x, u_{n}^{ \pm}\right) u_{n}^{ \pm} \mathrm{d} x=\int_{\mathbb{R}^{3}} f\left(x, u_{b}^{ \pm}\right) u_{b}^{ \pm} \mathrm{d} x
\end{aligned}
$$

which demonstrates that $\left\langle I_{b}^{\prime}\left(u_{b}\right), u_{b}^{ \pm}\right\rangle \leq 0$. Moreover, by (1.4), it is easy to verify that $u_{b} \in \mathscr{E}_{b}$. In STEP 1 , there exist $\alpha_{u_{b}}, \beta_{u_{b}}>0$ such that $\alpha_{u_{b}} u_{b}^{+}+\beta_{u_{b}} u_{b}^{-} \in \mathscr{M}_{b}$. By ( $F_{4}$ ), one has

$$
\begin{aligned}
& \frac{1-t^{2}}{4} \tau f(x, \tau)+F(x, t \tau)-F(x, \tau)+\frac{V(x)}{4}\left(1-t^{2}\right)^{2} \tau^{2} \\
& =\int_{t}^{1}\left[\frac{f(x, \tau)-V(x) \tau}{\tau^{3}}-\frac{f(x, \alpha \tau)-V(x) \alpha \tau}{(\alpha \tau)^{3}}\right] \alpha^{3} \tau^{4} \mathrm{~d} \alpha \geq 0
\end{aligned}
$$

for all $t \geq 0$ and $\tau \in \mathbb{R} \backslash\{0\}$. Letting $t=0$ in the equality above, we have $\frac{1}{4} f(x, \tau) \tau-F(x, \tau)+$ $\frac{1}{4} V(x) \tau^{2} \geq 0, x \in \mathbb{R}^{3}$ and $\tau \in \mathbb{R}$. Thus, by (1.4), (1.5), [20, Lemmas 2.2 and 2.7], the weak semicontinuity of norm, and the Fatou's Lemma, we have

$$
\begin{aligned}
m_{b} & =\lim _{n \rightarrow \infty}\left[I_{b}\left(u_{n}\right)-\frac{1}{4}\left\langle I_{b}^{\prime}\left(u_{n}\right), u_{n}\right\rangle\right] \\
& =\lim _{n \rightarrow \infty}\left\{\frac{a}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{n}\right\|_{2}^{2}+\int_{\mathbb{R}^{3}}\left[\frac{1}{4} f\left(x, u_{n}\right) u_{n}-F\left(x, u_{n}\right)+\frac{1}{4} V(x) u_{n}^{2}\right] \mathrm{d} x\right\} \\
& \geq \frac{a}{4}\left\|(-\Delta)^{\frac{s}{2}} u_{b}\right\|_{2}^{2}+\int_{\mathbb{R}^{3}}\left[\frac{1}{4} f\left(x, u_{b}\right) u_{b}-F\left(x, u_{b}\right)+\frac{1}{4} V(x) u_{b}^{2}\right] \mathrm{d} x \\
& =I_{b}\left(u_{b}\right)-\frac{1}{4}\left\langle I_{b}^{\prime}\left(u_{b}\right), u_{b}\right\rangle \\
& \geq \sup _{\alpha, \beta \geq 0}\left[I_{b}\left(\alpha u_{b}^{+}+\beta u_{b}^{-}\right)+\frac{1-\alpha^{4}}{4}\left\langle I_{b}^{\prime}\left(u_{b}\right), u_{b}^{+}\right\rangle+\frac{1-\beta^{4}}{4}\left\langle I_{b}^{\prime}\left(u_{b}\right), u_{b}^{-}\right\rangle\right]-\frac{1}{4}\left\langle I_{b}^{\prime}\left(u_{b}\right), u_{b}\right\rangle \\
& \geq \sup _{\alpha, \beta \geq 0} I_{b}\left(\alpha u_{b}^{+}+\beta u_{b}^{-}\right) \\
& \geq I_{b}\left(\alpha_{u_{b}} u_{b}^{+}+\beta_{u_{b}} u_{b}^{-}\right) \\
& \geq m_{b}
\end{aligned}
$$

which implies that $I_{b}\left(u_{b}\right)=m_{b}$ and $u_{b} \in \mathscr{M}_{b}$. Similarly, we can prove that there exists $\bar{u}_{b} \in \mathscr{N}_{b}$ such that $I_{b}\left(\bar{u}_{b}\right)=c_{b}$. The proof of STEP 2 is complete.

STEP 3. Critical point of $I_{b}$.
Using [20, Lemma 2.9], we let $u_{b} \in \mathscr{M}_{b}$ and $\bar{u}_{b} \in \mathscr{N}_{b}$ satisfy $I_{b}\left(u_{b}\right)=m_{b}=\inf _{u \in \mathscr{M}_{b}} I_{b}(u)$ and $I_{b}\left(\bar{u}_{b}\right)=c_{b}=\inf _{u \in \mathcal{N}_{b}} I_{b}(u)$. So we prove that $u_{b}$ and $\bar{u}_{b}$ are critical point of $I_{b}$. Moreover, $u_{b}$ is a radial sign-changing solution to problem (1.1) and $\bar{u}_{b}$ is a radial solution to problem (1.1).

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