# GENERALIZED HUKUHARA WEAK SUBDIFFERENTIAL AND ITS APPLICATION ON IDENTIFYING OPTIMALITY CONDITIONS FOR NONSMOOTH INTERVAL-VALUED FUNCTIONS 

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#### Abstract

In this paper, we introduce the idea of $g H$-weak subdifferential for interval-valued functions (IVFs) and show how to calculate $g H$-weak subgradients. It is observed that a nonempty $g H$-weak subdifferential set is convex and closed. In characterizing the class of functions for which the $g H$-weak subdifferential set is nonempty, it is identified that this class is the collection of $g H$-lower Lipschitz IVFs. In checking the validity of the sum rule of $g H$-weak subdifferential for a pair of IVFs, a counterexample is obtained, which reflects that the sum rule does not hold. However, under a mild restriction on one of the IVFs, one-sided inclusion for the sum rule holds. As applications, we employ $g H$-weak subdifferential to provide a few optimality conditions for nonsmooth IVFs. Further, a necessary optimality condition for interval optimization problems with a difference of two nonsmooth IVFs as the objective is established. Next, a necessary and sufficient condition via augmented normal cone and $g H$-weak subdifferential of IVFs for finding weak efficient points is presented. Lastly, in investigating a 'sup-relation' between $g H$-direction derivative and $g H$-weak subgradients, we approximately compute $g H$-weak subgradient at each iterative step. In the sequel, we propose $\mathscr{W}$-gH-weak subgradient method to identify a weak efficient solution of an unconstrained nonsmooth IOP. We apply the proposed method to solve an interval optimization problem by taking a test example. We present a convergence analysis of the proposed method for constant and diminishing step sizes.


Keywords. $g H$-weak subgradient; $g H$-Fréchet subdifferential; Interval optimization; Nonsmooth intervalvalued functions.

## 1. Introduction

The interval arithmetic of Moore [19] is the milestone in interval analysis. The realistic applicability of Moore's method is relevant till today. We can currently find several papers in the community of interval-valued optimization problems (IOPs) where Moore's interval analysis is applied extensively. To find optimality conditions for IOPs, ideas of derivatives for interval-valued functions (IVFs) were proposed [5, 13, 18, 21, 27]. In [18], the concept of $g H$-differentiability for IVFs was introduced. Chalco-Cano et al. [6] addressed the algebraic property of gH -differentiable interval-valued functions. Ghosh et al. [13] proved the existence of $g H$-directional derivative for convex IVFs and presented optimality conditions for IOPs.

[^0]It is a familiar fact that, in nonsmooth optimization, the classical gradient algorithm fails: even in finding the optimum point, as there is no derivative, the conventional optimality condition $\nabla f(x)=0$ does not hold. More crucially, it is observed that optima of almost everywhere differentiable function categorically arise at nondifferentiable points-for instance, take the minimization of $f(x)=|x|$. The notion of subdifferential, defined by Rockafellar [24], is a crucial factor in the body of optimization theory that perfectly replaces the role of the gradient to identify optima for convex functions. However, subdifferential is inadequate in developing optimality conditions for nonconvex optimization problems. Due to this insufficiency, the idea of subdifferential has been generalized. The most common of such generalizations is weak subdifferential [3]. Based on this notion, a strong duality theorem for the nonconvex inequality-constrained problems has been found by defining a weak conjugate function [30]. A substantial application of this notion in duality theory with the help of a weak subdifferentiable perturbation function was given in [26].

In the context of the nonsmooth calculus for nondifferentiable convex IVFs, Ghosh et al. [11] recently proposed the idea of $g H$-subgradient and $g H$-subdifferential. The same article [11] found that $g \mathrm{H}$-directional derivative is the maximum of all the products of the direction and gH -subgradients. Afterward, Anshika et al. [1] characterized weak efficiency for nonconvex composite optimization problems with the subdifferential sets of convex interval-valued functions. In [1], by formulating the supremum and infimum of an IVF, a Fermat-type, a Fritz-John-type, and a KKT-type weak efficiency condition for nonsmooth IOPs have been derived. Anshika and Ghosh [2] introduced gH subdifferential of the interval-valued function. Furthermore, Chauhan et al. [8] derived the notion of gH -Clarke derivative for IVFs and IOPs. Under the Clarke subdifferentiablility assumption, Chen and Li [7] provided KKT conditions for efficient solutions. In addition, Karaman [16] presented two subdifferentials for interval-valued functions and some optimality criteria, which were obtained by using subdifferentials.

From the available literature on nonsmooth IOPs, it is found that the study of $g H$-weak subdifferential notion has not yet been addressed. However, the notion of $g H$-weak subdifferential might be effective in characterizing and capturing the efficient solutions of IOPs with nonconvex and nonsmooth IVFs. By using a subgradient, one may face difficulties in solving the problem which does not satisfy the convexity assumption because a subgradient refers to the slope of a supporting hyperplane to the graph of convex functions in convex analysis. Thus, in this study, we introduce the notion of a weak subgradient, which does not need any kind of convexity.

In this article, we attempt to show various properties of weak-subdifferential and their use in nonsmooth nonconvex IOPs. As an application of the proposed $g H$-weak subdifferential, we will give a necessary and sufficient optimality condition for finding weak efficient points of difference of two IVFs. In the last, similar to the conventional weak-subgradient method [9] for real-valued optimization, we show a $g H$-weak subgradient method to obtain an efficient solution of nonsmooth, nonconvex IOPs.

The rest of the article is presented as follows. Section 2 is devoted to the conventional properties of intervals, followed by the calculus of IVFs. Section 3 introduces the notion of $g H$-weak subdifferential for IVFs and discusses their properties such as convexity, closedness, and nonemptiness. Additionally, the role of $g H$-weak subdifferential to derive the necessary condition for weak efficiency for $g H$-weak subdifferentiable IVFs is presented in Section 3. In Section 4, we analyze the necessary condition for obtaining an efficient solution of the difference of two IVFs. In Section 5, we establish a 'sup-relation' between $g H$-direction derivative and $g H$-weak subgradients. Using this relation, in Section 6, we present a $\mathscr{W}-g H$-weak subgradient method to obtain a weak efficient solution to an unconstrained IOP with its algorithmic implementation and convergence analysis. Finally, we draw a conclusion with future directions to extend the present study.

## 2. Preliminaries and Terminologies

In this section, required terminologies and notions on intervals, including calculus of IVFs are given. Throughout the paper, we extensively use the following notations.

- $\mathbb{R}$ is the set of real numbers.
- $\mathbb{R}_{+}$represents the set of nonnegative real numbers.
- $I(\mathbb{R})$ is the collection of all compact intervals.
- $\overline{I(\mathbb{R})}=I(\mathbb{R}) \cup\{-\infty,+\infty\}$.
- $\mathbf{0}=[0,0]$.
- Elements of $I(\mathbb{R})$ are presented by bold capital letters: $\mathbf{X}, \mathbf{Y}, \mathbf{Z}, \ldots$
- $\mathscr{B}(h, \boldsymbol{\delta})$ represents a ball with center at $h$ and radius $\delta$ in $\mathbb{R}^{n}$.
- $I(\mathbb{R})^{n}=I(\mathbb{R}) \times I(\mathbb{R}) \times I(\mathbb{R}) \times \cdots \times I(\mathbb{R})(n$ times $)$.
- Interval vectors in $I(\mathbb{R})^{n}$ are denoted by $\widehat{\mathbf{X}}, \widehat{\mathbf{Y}}, \widehat{\mathbf{Z}}, \ldots$.
- $B_{\alpha}(\bar{u})$ is the open ball with center at $\bar{u} \in \mathbb{R}^{n}$ and radius $\alpha \geq 0$.
- $\mathscr{N}(\bar{x})$ is a neighborhood of $\bar{x} \in \mathbb{R}^{n}$.
- $\|\cdot\|_{I(\mathbb{R})}$ denotes the norm on $I(\mathbb{R})$.
2.1. Arithmetic and dominance of intervals. Throughout this subsection, we represent an element $\mathbf{X}$ of $I(\mathbb{R})$ by the corresponding small letter:

$$
\mathbf{X}=[\underline{x}, \bar{x}], \text { where } \underline{x} \text { and } \bar{x} \text { are in } \mathbb{R} \text { with } \underline{x} \leq \bar{x}
$$

Recall that Moore's interval addition $(\oplus)$, subtraction $(\ominus)$, and multiplication $(\odot)[19,20]$ are given by

$$
\begin{aligned}
& \mathbf{X} \oplus \mathbf{Y}=[\underline{x}+\underline{y}, \bar{x}+\bar{y}], \mathbf{X} \ominus \mathbf{Y}=[\underline{x}-\bar{y}, \bar{x}-\underline{y}], \text { and } \\
& \mathbf{X} \odot \mathbf{Y}=[\min \{\underline{x} \underline{y}, \underline{x} \bar{y}, \bar{x} \underline{y}, \overline{x y}\}, \max \{\underline{x} \underline{y}, \underline{x} \bar{y}, \bar{x} \underline{y}, \overline{x y}\}] .
\end{aligned}
$$

Definition 2.1. ( $g H$-difference of intervals [25]). The $g H$-difference for a pair of intervals $\boldsymbol{P}$ and $\boldsymbol{Q}$, denoted by $\boldsymbol{P} \ominus_{g H} \boldsymbol{Q}$, is the interval $\boldsymbol{Y}$ such that $\boldsymbol{P}=\boldsymbol{Q} \oplus \boldsymbol{Y}$ or $\boldsymbol{Q}=\boldsymbol{P} \ominus \boldsymbol{Y}$. It is well-known that, for $\boldsymbol{P}=[\underline{p}, \bar{p}]$ and $\boldsymbol{Q}=[\underline{q}, \bar{q}]$,

$$
\boldsymbol{P} \ominus_{g H} \boldsymbol{Q}=[\min \{\underline{p}-\underline{q}, \bar{p}-\bar{q}\}, \max \{\underline{p}-\underline{q}, \bar{p}-\bar{q}\}] \text { and } \boldsymbol{P} \ominus_{g H} \boldsymbol{P}=\mathbf{0}
$$

For two elements $\widehat{\boldsymbol{I}}=\left(\boldsymbol{I}_{1}, \boldsymbol{I}_{2}, \ldots, \boldsymbol{I}_{n}\right)$ and $\widehat{\boldsymbol{J}}=\left(\boldsymbol{J}_{1}, \boldsymbol{J}_{2}, \ldots, \boldsymbol{J}_{n}\right)$ of $I(\mathbb{R})^{n}$, the algebraic operation $\widehat{\boldsymbol{I}} \star \widehat{\boldsymbol{J}}$ is defined by $\widehat{\boldsymbol{I}} \star \widehat{\boldsymbol{J}}=\left(\boldsymbol{I}_{1} \star \boldsymbol{J}_{1}, \boldsymbol{I}_{2} \star \boldsymbol{J}_{2}, \ldots, \boldsymbol{I}_{n} \star \boldsymbol{J}_{n}\right)$, where $\star \in\left\{\oplus, \ominus, \ominus_{g H}\right\}$.

Definition 2.2. (Dominance of intervals). Let $\boldsymbol{Z}$ and $\boldsymbol{W}$ be in $I(\mathbb{R})$.
(i) $\boldsymbol{W}$ is called dominated by $\boldsymbol{Z}$ if $\underline{z} \leq \underline{w}$ and $\bar{z} \leq \bar{w}$, and then we express it by $\boldsymbol{Z} \preceq \boldsymbol{W}$.
(ii) $\boldsymbol{W}$ is said to be strictly dominated by $\boldsymbol{Z}$ if either ' $\underline{z} \leq \underline{w}$ and $\bar{z}<\bar{w}$ ' or ' $\underline{z}<\underline{w}$ and $\bar{z} \leq \bar{w}$ ', and then we express it by $\boldsymbol{Z} \prec \boldsymbol{W}$.
(iii) If $\boldsymbol{W}$ is not dominated by $\boldsymbol{Z}$, then we write $\boldsymbol{Z} \npreceq \boldsymbol{W}$. If $\boldsymbol{W}$ is not strictly dominated by $\boldsymbol{Z}$, then we write $\boldsymbol{Z} \nprec \boldsymbol{W}$.
(iv) If $\boldsymbol{W} \npreceq \boldsymbol{Z}$ and $\boldsymbol{Z} \npreceq \boldsymbol{W}$, then it is called that none of $\mathbf{W}$ and $\mathbf{Z}$ dominates the other or $\boldsymbol{W}$ and $\boldsymbol{Z}$ are not comparable.

For any two elements $\widehat{\mathbf{I}}=\left(\mathbf{I}_{1}, \mathbf{I}_{2}, \ldots, \mathbf{I}_{n}\right)^{\top}$ and $\widehat{\mathbf{J}}=\left(\mathbf{J}_{1}, \mathbf{J}_{2}, \ldots, \mathbf{J}_{n}\right)^{\top}$ in $I(\mathbb{R})^{n}$,

$$
\widehat{\mathbf{I}} \preceq \widehat{\mathbf{J}} \Longleftrightarrow \mathbf{I}_{j} \preceq \mathbf{J}_{j} \text { for all } j=1,2, \ldots, n
$$

2.2. Concavity and differential calculus of IVFs. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let an IVF $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ be presented by

$$
\Phi(y)=[\underline{\phi}(y), \bar{\phi}(y)] \forall y \in \mathscr{Y},
$$

where $\underline{\phi}(y) \leq \bar{\phi}(y)$ for all $y \in \mathscr{Y}$ and $\underline{\phi}$ and $\bar{\phi}$ are called lower and upper real-valued functions on $\mathscr{Y}$.
Definition 2.3. (Concave IVF). If $\mathscr{Y}$ is convex, then an IVF $\Phi$ is said to be a concave IVF on $\mathscr{Y}$ if, for any $y_{1}, y_{2} \in \mathscr{Y}, \beta_{1}, \beta_{2} \in[0,1]$, and $\beta_{1}+\beta_{2}=1$,

$$
\beta_{1} \odot \Phi\left(y_{1}\right) \oplus \beta_{2} \odot \Phi\left(y_{2}\right) \preceq \Phi\left(\beta_{1} y_{1}+\beta_{2} y_{2}\right) .
$$

Lemma 2.1. If $\Phi$ is a concave IVF on a convex set $\mathscr{Y} \subseteq \mathbb{R}^{n}$, then $\phi$ and $\bar{\phi}$ are concave on $\mathscr{Y}$ and vice-versa.

Proof. The proof is similar to the proof of [29, Proposition 6.1].
Example 2.1. Let $\mathscr{Y}$ be the Euclidean space $\mathbb{R}^{n}$. Then, the $\operatorname{IVF} \Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ which is defined by

$$
\Phi(y)=\widehat{\boldsymbol{M}}^{\top} \odot y \ominus_{g H}\|y\|, \text { where } \widehat{\boldsymbol{M}}=\left(\boldsymbol{M}_{1}, \boldsymbol{M}_{2}, \ldots, \boldsymbol{M}_{n}\right) \in I(\mathbb{R})^{n}
$$

and for all $y=\left(y_{1}, y_{2}, \ldots, y_{n}\right) \in \mathscr{Y}$ is a concave IVF on $\mathscr{Y}$. The reason is as follows.
Without loss of generality, the first p components of y are assumed to be non-negative, and the rest $n-p$ be negative. Then, letting $\boldsymbol{M}_{i}=\left[\underline{m}_{i}, \bar{m}_{i}\right]$ for all $i=1,2, \ldots, n$,

$$
\Phi(y)=\bigoplus_{i=1}^{p}\left[\underline{m}_{i} y_{i}, \bar{m}_{i} y_{i}\right] \oplus \bigoplus_{j=p+1}^{n}\left[\bar{m}_{j} y_{j}, \underline{m}_{j} y_{j}\right] \ominus_{g H}\|y\|
$$

It is evident that $\sum_{i=1}^{p} \underline{m}_{i} y_{i}+\sum_{j=p+1}^{n} \bar{m}_{j} y_{j}$ and $\sum_{i=1}^{p} \bar{m}_{i} y_{i}+\sum_{j=p+1}^{n} \underline{m}_{j} y_{j}$, being linear, are concave functions. Also, $-\|y\|$ is a concave function. Therefore, $\sum_{i=1}^{p} \underline{m}_{i} y_{i}+\sum_{j=p+1}^{n} \bar{m}_{j} y_{j}-\|y\|$ and $\sum_{i=1}^{p} \bar{m}_{i} y_{i}+$ $\sum_{j=p+1}^{n} \underline{m}_{j} y_{j}-\|y\|$ are concave functions. Hence, by Lemma 2.1, $\Phi$ is a concave IVF.

Definition 2.4. ( $g H$-continuity [12]). An IVF $\Phi$ is said to be $g H$-continuous at $u \in \mathscr{Y}$ if $\lim _{\|d\| \rightarrow 0}(\Phi(u+$ d) $\left.\ominus_{g H} \Phi(u)\right)=\mathbf{0}$. If at every $u \in \mathscr{Y}, \Phi$ is $g H$-continuous, then $\Phi$ is called $g H$-continuous on $\mathscr{Y}$.

Lemma 2.2. (See [14]). For a gH-continuous IVF $\Phi$, its $\underline{\phi}$ and $\bar{\phi}$ are continuous and vice-versa.
Definition 2.5. ( gH -derivative [4]). Let $\mathscr{Y} \subseteq \mathbb{R}^{n}$. The $g H$-derivative of an IVF $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ at $u \in \mathscr{Y}$ is the limit

$$
\Phi^{\prime}(u):=\lim _{d \rightarrow 0} \frac{1}{d} \odot\left\{\Phi(u+d) \ominus_{g H} \Phi(u)\right\} .
$$

Definition 2.6. ( gH -Gáteaux derivative [13]). Let an IVF $\Phi$ be defined on a nonempty open subset $\mathscr{Y}$ of $\mathbb{R}^{n}$. Then, $\Phi$ is known to be $g H$-Gáteaux differentiable with $g H$-Gáteaux derivative $\Phi_{\mathscr{G}}(u)$ at $u \in \mathscr{Y}$ if the following limit

$$
\Phi_{\mathscr{G}}(u)(h):=\lim _{\beta \rightarrow 0+} \frac{1}{\beta} \odot\left(\Phi(u+\beta h) \ominus_{g H} \Phi(u)\right)
$$

is finite for all $h \in \mathbb{R}^{n}$ and $\Phi_{\mathscr{G}}(u)$ is a gH-continuous and linear $I V F$ from $\mathbb{R}^{n}$ to $I(\mathbb{R})$.
Definition 2.7. (gH-Fréchet derivative [13]). Let an IVF $\Phi$ be defined on a nonempty open subset $\mathscr{Y}$ of $\mathbb{R}^{n}$. Then, $\Phi$ is said to be $g H$-Fréchet differentiable at $u \in \mathscr{Y}$ if there exists a gH-continuous and linear mapping $\boldsymbol{G}: \mathscr{Y} \rightarrow I(\mathbb{R})$ such that

$$
\lim _{\|h\| \rightarrow 0} \frac{1}{\|h\|} \odot\left(\left\|\Phi(u+h) \ominus_{g H} \Phi(u) \ominus_{g H} \boldsymbol{G}(h)\right\|_{I(\mathbb{R})}\right)=0,
$$

where $\boldsymbol{G}$ will be referred to as $\Phi_{\mathscr{F}}(u)$.

Definition 2.8. (Efficient point [13]). Let $\mathscr{Y} \subseteq \mathbb{R}^{n}$ and $\Phi: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ be an IVF. A point $u \in \mathscr{Y}$ is said to be an efficient point of the IVF $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ if $\Phi(y) \nprec \Phi(u)$ for all $y \in \mathscr{Y}$.
Definition 2.9. (Weak efficient point [1]). Let $\mathscr{Y} \subseteq \mathbb{R}^{n}$ and $\Phi: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ be an IVF. A point $u \in \mathscr{Y}$ is said to be $a$ weak efficient point of the IVF $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ if $\Phi(u) \preceq \Phi(y)$ for all $y \in \mathscr{Y}$.
2.3. Few properties of the elements in $I(\mathbb{R})$. Let $\mathbf{Y}=[\underline{y}, \bar{y}]$ and $\widehat{\mathbf{Y}}=\left(\mathbf{Y}_{1}, \mathbf{Y}_{2}, \ldots, \mathbf{Y}_{n}\right)$ be elements in $I(\mathbb{R})$ and $I(\mathbb{R})^{n}$, respectively. The following two functions $\|\cdot\|_{I(\mathbb{R})}: I(\mathbb{R}) \rightarrow \mathbb{R}_{+}$and $\|\cdot\|_{I(\mathbb{R})^{n}}$ : $I(\mathbb{R})^{n} \rightarrow \mathbb{R}_{+}$are referred to as norm $[19,20]$ on $I(\mathbb{R})$ and $I(\mathbb{R})^{n}$, respectively:

$$
\|\mathbf{Y}\|_{I(\mathbb{R})}=\max \{|\underline{y}|,|\bar{y}|\}, \text { and }\|\widehat{\mathbf{Y}}\|_{I(\mathbb{R})^{n}}=\sum_{j=1}^{n}\left\|\mathbf{Y}_{j}\right\|_{I(\mathbb{R})} .
$$

Lemma 2.3. For any $\boldsymbol{W}, \boldsymbol{Y}, \boldsymbol{Z} \in I(\mathbb{R})$ and $\varepsilon \geq 0$, we have

$$
\varepsilon \preceq\left(\boldsymbol{W} \ominus_{g H} \boldsymbol{Y}\right) \ominus_{g H} \boldsymbol{Z} \Longrightarrow \boldsymbol{Z} \oplus \varepsilon \preceq \boldsymbol{W} \ominus_{g H} \boldsymbol{Y}
$$

Proof. See Appendix A.
Lemma 2.4. For any $\boldsymbol{X}, \boldsymbol{Y}, \boldsymbol{Z}, \boldsymbol{W} \in I(\mathbb{R})$, we have

$$
(\boldsymbol{X} \oplus \boldsymbol{Y}) \ominus_{g H}(\boldsymbol{Z} \oplus \boldsymbol{W}) \subseteq\left(\boldsymbol{X} \ominus_{g H} \boldsymbol{Z}\right) \oplus\left(\boldsymbol{Y} \ominus_{g H} \boldsymbol{W}\right)
$$

Proof. See Appendix B.
Lemma 2.5. For any $\boldsymbol{W}, \boldsymbol{Y}, \boldsymbol{Z} \in I(\mathbb{R})$,

$$
\boldsymbol{0} \ominus_{g H}\left\{\left((-1 \odot \boldsymbol{W}) \ominus_{g H}(-1 \odot \boldsymbol{Y})\right) \ominus_{g H}(-1 \odot \boldsymbol{Z})\right\}=\left(\left(\boldsymbol{W} \ominus_{g H} \boldsymbol{Y}\right) \ominus_{g H} \boldsymbol{Z}\right) .
$$

Proof. See Appendix C.

Lemma 2.6. For all $\boldsymbol{X}, \boldsymbol{Y}$, and $\boldsymbol{Z}$ of $I(\mathbb{R})$,
(i) if $\boldsymbol{0} \preceq \boldsymbol{X} \ominus_{g H} \boldsymbol{Y}$, then $\boldsymbol{0} \ominus_{g H} \boldsymbol{Z} \preceq\left(\boldsymbol{X} \ominus_{g H} \boldsymbol{Y}\right) \ominus_{g H} \boldsymbol{Z}$,
(ii) if $\boldsymbol{Z} \preceq \boldsymbol{X}_{\ominus_{g H}} \boldsymbol{Y}$, then $\boldsymbol{Z} \ominus_{g H} \boldsymbol{W} \preceq\left(\boldsymbol{X} \ominus_{g H} \boldsymbol{Y}\right) \ominus_{g H} \boldsymbol{W}$ for all $\boldsymbol{W} \in I(\mathbb{R})$,
(iii) if $\boldsymbol{X} \ominus_{g H} \boldsymbol{Y} \preceq[L, L]$, then $[-L,-L] \preceq \boldsymbol{Y} \ominus_{g H} \boldsymbol{X}$, where $L \in \mathbb{R}$,
(iv) if $[-\gamma,-\gamma] \preceq \boldsymbol{X} \ominus_{g H} \boldsymbol{Y}$, then $\boldsymbol{Y} \ominus_{g H}[\gamma, \gamma] \preceq \boldsymbol{X}$, where $\gamma \in \mathbb{R}$, and
(v) if $\boldsymbol{Z} \preceq \boldsymbol{X} \oplus \boldsymbol{Y}$, then $\boldsymbol{Z} \ominus_{g H} \boldsymbol{Y} \preceq \boldsymbol{X}$.

Proof. See Appendix D.

Definition 2.10. (Sequence in $\left.I(\mathbb{R})^{n}[11]\right)$. A function $\widehat{\Phi}: \mathbb{N} \rightarrow I(\mathbb{R})^{n}$ is called a sequence in $I(\mathbb{R})^{n}$, where $\mathbb{N}$ is the set of all natural numbers.
Definition 2.11. (Closed set in $\left.I(\mathbb{R})^{n}[1]\right)$. A nonempty subset $\mathscr{U} \subseteq I(\mathbb{R})^{n}$ is known to be closed iffor every convergent sequence $\left\{\widehat{\boldsymbol{M}}_{k}\right\}$ in $\mathscr{U}$ converging to $\widehat{\boldsymbol{M}}, \widehat{\boldsymbol{M}}$ must belong to $\mathscr{U}$.
Definition 2.12. (Closure of a set in $\left.I(\mathbb{R})^{n}\right)$. Let $\mathscr{Y} \subseteq I(\mathbb{R})^{n}$. The intersection of all closed sets containing $\mathscr{Y}$ is called the closure of $\mathscr{Y}$, abbreviated by $\operatorname{cl}(\mathscr{Y})$.
Definition 2.13. (Convergent sequence in $\left.I(\mathbb{R})^{n}[11]\right)$. Let $\left\{\widehat{\boldsymbol{M}}_{k}\right\}$ be a sequence in $I(\mathbb{R})^{n}$. If there exists $\widehat{\boldsymbol{M}} \in I(\mathbb{R})^{n}$ for which for any $\varepsilon>0$ there exists $p \in \mathbb{N}$ such that $\left\|\widehat{\boldsymbol{M}}_{k} \ominus_{g H} \widehat{\boldsymbol{M}}\right\|_{I(\mathbb{R})^{n}}<\varepsilon$ for all $k \geq p$, then $\left\{\widehat{\boldsymbol{M}}_{k}\right\}$ is said to be convergent and converges to $\widehat{\boldsymbol{M}}$.
Remark 2.1. It is to note that if a sequence $\left\{\widehat{\boldsymbol{M}}_{k}\right\}=\left(\boldsymbol{M}_{k 1}, \boldsymbol{M}_{k 2}, \ldots, \boldsymbol{M}_{k n}\right)^{\top}$ in $I(\mathbb{R})^{n}$ converges to $\widehat{\boldsymbol{M}}=\left(\boldsymbol{M}_{1}, \boldsymbol{M}_{2}, \ldots, \boldsymbol{M}_{n}\right)^{\top} \in I(\mathbb{R})^{n}$, then by the definition of norm on $I(\mathbb{R})^{n}$, the sequence $\boldsymbol{M}_{k j}$ in $I(\mathbb{R})$ converges to $\boldsymbol{M}_{j} \in I(\mathbb{R})$ for all $j=1,2, \ldots, n$. Also, according to the definition of norm on $I(\mathbb{R})$, the sequences $\left\{\underline{m}_{k j}\right\}$ and $\left\{\bar{m}_{k j}\right\}$ in $\mathbb{R}$ converge to $\left\{\underline{m}_{j}\right\}$ and $\left\{\bar{m}_{j}\right\}$, respectively, for all $j$.

Definition 2.14. (Infimum and supremum of a subset of $\overline{I(\mathbb{R})}[17]$ ).
Let $\mathscr{U} \subseteq \overline{I(\mathbb{R})}$. We call an interval $\mathbf{X} \in I(\mathbb{R})$ a lower bound (respectively, an upper bound) of $\mathscr{U}$ if $\boldsymbol{U} \in \mathscr{U}$ implies $\mathbf{X} \preceq \boldsymbol{U}$ (respectively, $\mathbf{U} \preceq \boldsymbol{X}$ ).
A lower bound $\mathbf{X}$ of $\mathscr{U}$ is called infimum of $\mathscr{U}$, denoted by $\inf \mathscr{U}$, if for any lower bound $\mathbf{Z}$ of $\mathscr{U}$, $\mathbf{Z} \preceq \mathbf{X}$.
An upper bound $\mathbf{X}$ of $\mathscr{U}$ is called supremum of $\mathscr{U}$, denoted by sup $\mathscr{U}$, if for any upper bound $\mathbf{Z}$ of $\mathscr{U}, \mathbf{X} \preceq \boldsymbol{Z}$.
Remark 2.2. [17] Let $\mathscr{S}=\left\{\left[a_{\mu}, b_{\mu}\right] \in \overline{I(\mathbb{R})}: \mu \in \Lambda\right.$ and $\Lambda$ being an index set $\}$. Then, by Definition 2.14, it follows that $\inf \mathscr{S}=\left[\inf _{\mu \in \Lambda} a_{\mu}, \inf _{\mu \in \Lambda} b_{\mu}\right]$ and $\sup \mathscr{S}=\left[\sup _{\mu \in \Lambda} \mathrm{a}_{\mu}, \sup _{\mu \in \Lambda} \mathrm{b}_{\mu}\right]$.

## 3. $g H$-Weak Subdifferential Calculus for IVFs

In this section, we introduce the ideas of $g H$-weak subgradient and $g H$-weak subdifferential for IVFs. Some properties of $g H$-weak subdifferential and inclusion for sum rule are provided. Its relation with $g H$-Fréchet lower subdifferential is also discussed.

Definition 3.1. ( $g H$-weak subdifferential). Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$ and $\Phi$ be an IVF defined on $\mathscr{Y}$. A pair $\left(\widehat{\boldsymbol{G}^{\boldsymbol{w}}}, c\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}$is said to be a $g H$-weak subgradient of $\Phi$ at $u \in \mathscr{Y}$ if, for every $y \in \mathscr{Y}$,

$$
\begin{equation*}
{\widehat{\boldsymbol{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) . \tag{3.1}
\end{equation*}
$$

The set of all $g H$-weak subgradients of $\Phi$ at $u \in \mathscr{Y}$, i.e.,

$$
\partial^{w} \Phi(u)=\left\{\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}:{\widehat{\boldsymbol{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) \forall y \in \mathscr{Y}\right\}
$$

is said to be $g H$-weak subdifferential of $\Phi$ at $u \in \mathscr{Y}$.
Example 3.1. Let an IVF $\Phi:[-1,1] \rightarrow I(\mathbb{R})$ be defined by $\Phi(y)=\left[y^{2},|y|\right]$, where $y \in[-1,1]$.
Let us compute the $g H$-weak subdifferential of $\Phi$ at 0 and 1, i.e., $\partial^{w} \Phi(0)$ and $\partial^{w} \Phi(1)$, respectively. Note that

$$
\begin{aligned}
\partial^{w} \Phi(0) & =\left\{\left(\mathbf{G}_{1}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}: \mathbf{G}_{1}^{w} \odot y \ominus_{g H} c|y| \preceq\left[y^{2},|y|\right] \forall y \in[-1,1]\right\} \\
& =\left\{\left(\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right], c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right] \odot y \ominus_{g H} c|y| \preceq\left[y^{2},|y|\right] \forall y \in[-1,1]\right\},
\end{aligned}
$$

which yields the following two cases corresponding to $y \in[0,1]$ and $y \in[-1,0]$.
(i)

$$
\begin{aligned}
\partial^{w} \Phi(0) & =\left\{\left(\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right], c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right] \odot y \ominus_{g H} c|y| \preceq\left[y^{2},|y|\right] \forall y \in[0,1]\right\} \\
& =\left\{\left(\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right], c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}: \underline{g_{1}^{w}} y-c y \leq y^{2} \text { and } \overline{g_{1}^{w}} y-c y \leq y \forall y \in[0,1]\right\} \\
& =\left\{\left(\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right], c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}: \underline{g_{1}^{w}}-c \leq 0 \text { and } \overline{g_{1}^{w}}-c \leq 1\right\} .
\end{aligned}
$$

(ii) Likewise,

$$
\partial^{w} \Phi(0)=\left\{\left(\left[\underline{g_{1}^{w}}, \overline{g_{1}^{w}}\right], c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:-1 \leq \underline{g_{1}^{w}}+c \text { and } 0 \leq \overline{g_{1}^{w}}+c\right\} .
$$

Hence, by combining Case (i) and Case (ii), we obtain

$$
\partial^{w} \Phi(0)=\left\{\left(\mathbf{G}_{1}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:[-1-c,-c] \preceq \mathbf{G}_{1}^{w} \preceq[c, 1+c]\right\} .
$$

Similarly,

$$
\partial^{w} \Phi(1)=\left\{\left(\mathbf{G}_{2}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:[1-c, 2-c] \preceq \mathbf{G}_{2}^{w}\right\}
$$

Remark 3.1. To understand the geometric interpretation of the $g H$-weak subdifferential of an IVF $\Phi$, let $\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in \partial^{w} \Phi(u)$. This means that $\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}$, for every $c \geq 0$, is a gH-weak subgradient of $\Phi$ at $u \in \mathscr{Y}$ if and only if there exists a concave and gH-continuous IVF $\boldsymbol{H}: \mathscr{Y} \rightarrow I(\mathbb{R})$, which is defined by $\boldsymbol{H}(y)=\Phi(u) \oplus{\widehat{\boldsymbol{G}^{\boldsymbol{w}}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \forall y \in \mathscr{Y}$, that satisfies

$$
(\forall y \in \mathscr{Y}) \boldsymbol{H}(y) \preceq \Phi(y) \text { and } \boldsymbol{H}(u)=\Phi(u) .
$$

This condition shows that $\boldsymbol{H}$ must intersect $\Phi$ at least at the point $(u, \Phi(u))$ from bottom. Hence, it concludes that if $\Phi$ is gH-weak subdifferentiable at $u$ and $\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in \partial^{w} \Phi(u)$, then the graph of IVF H, that is,

$$
\operatorname{Gr}(\boldsymbol{H})=\{(y, \boldsymbol{Y}) \in \mathscr{Y} \times I(\mathbb{R}): \boldsymbol{Y}=\boldsymbol{H}(y)\}
$$

always lie below the epigraph of $\Phi$, i.e.,

$$
\operatorname{Epi}(\Phi)=\{(y, \boldsymbol{Y}) \in \mathscr{Y} \times I(\mathbb{R}): \Phi(y) \preceq \boldsymbol{Y}\}
$$

such that

$$
E p i(\Phi) \subset E p i(\boldsymbol{H}) \text { and } c l(E p i(\Phi)) \bigcap G r(\boldsymbol{H}) \text { is nonempty. }
$$



Figure 1. Geometrical representation of two possible $g H$-Dini Hadamard $\varepsilon$ subgradients of $\Psi$ of Example 3.1

For example, Let $\mathscr{Y}=[-1,2]$. Consider an IVF $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ which is given by

$$
\Phi(y)= \begin{cases}{\left[y^{2}-1,(y-1)^{2}\right],} & \text { if } y \in[-1,1] \\ {\left[(y-1)^{2}, y^{2}-1\right],} & \text { if } y \in(1,2]\end{cases}
$$

The $g H$-weak subdifferential of $\Phi$ at $u=1$ is

$$
\partial^{w} \Phi(1)=\left\{\left(\mathbf{G}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:[-c, 2-c] \preceq \mathbf{G}^{w} \preceq[c, 2+c]\right\} .
$$

For instance, $\left(\mathbf{G}^{w}, c\right)=([0.25,1.5], 0.5) \in \partial^{w} \Phi(1)$, geometrically indicates that the IVF

$$
\mathbf{H}(y)=\Phi(1) \oplus[0.25,1.5] \odot(y-1) \ominus_{g H} 0.5|y-1|
$$

intersects

$$
\operatorname{Epi}(\Phi)=\{(y, \mathbf{4}) \in \mathscr{Y} \times \mathbb{R}: \Phi(y) \preceq \mathbf{4}\}
$$

at the point $\mathrm{M}(1, \mathbf{0})$ from below as shown in Figure 1. We also observe from the figure that

$$
\operatorname{Epi}(\Phi) \subset \operatorname{Epi}(\mathbf{H}), \text { and } c l(\operatorname{Epi}(\Phi)) \bigcap G r(\mathbf{H}) \text { is nonempty. }
$$

Theorem 3.1. (Convexity of $g H$-weak subdifferential). Let $\mathscr{Y} \subset \mathbb{R}^{n}$. Let the $g H$-weak subdifferential of $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ at u be nonempty. Then, $\partial^{w} \Phi(u)$ is convex.
Proof. Let $\left(\widehat{\mathbf{G}_{1}^{w}}, c_{1}\right)$ and $\left(\widehat{\mathbf{G}_{2}^{w}}, c_{2}\right) \in \partial^{w} \Phi(u)$, where

$$
\widehat{\mathbf{G}_{1}^{w}}=\left(\mathbf{G}_{11}^{w}, \mathbf{G}_{12}^{w}, \ldots, \mathbf{G}_{1 n}^{w}\right)^{\top}
$$

and

$$
\widehat{\mathbf{G}_{2}^{w}}=\left(\mathbf{G}_{21}^{w}, \mathbf{G}_{22}^{w}, \ldots, \mathbf{G}_{2 n}^{w}\right)^{\top} .
$$

Let $\beta \in[0,1]$. From the definition of $\partial^{w} \Phi(u)$, we have

$$
\begin{align*}
& {\widehat{\mathbf{G}_{1}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c_{1}\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) \text { and }  \tag{3.2}\\
& {\widehat{\mathbf{G}_{2}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c_{2}\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u), \tag{3.3}
\end{align*}
$$

for all $y \in \mathscr{Y}$. Up to a rearrangement of terms, let the first $m$ components of $(y-u)$ be non-negative, and the rest be negative. Then, from inequalities (3.2) and (3.3), we have

$$
\bigoplus_{i=1}^{m}\left(y_{i}-u_{i}\right) \odot \mathbf{G}_{1 i}^{w} \bigoplus_{j=m+1}^{n}\left(y_{j}-u_{j}\right) \odot \mathbf{G}_{1 j}^{w} \ominus_{g H} c_{1}\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u)
$$

and

$$
\bigoplus_{i=1}^{m}\left(y_{i}-u_{i}\right) \odot \mathbf{G}_{2 i}^{w} \bigoplus_{j=m+1}^{n}\left(y_{j}-u_{j}\right) \odot \mathbf{G}_{2 j}^{w} \ominus_{g H} c_{2}\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) .
$$

Thus,

$$
\begin{equation*}
\bigoplus_{i=1}^{m} \beta \odot\left(\left(y_{i}-u_{i}\right) \odot \mathbf{G}_{1 i}^{w}\right) \bigoplus_{j=m+1}^{n} \beta \odot\left(\left(y_{j}-u_{j}\right) \odot \mathbf{G}_{1 j}^{w}\right) \ominus_{g H} \beta c_{1}\|y-u\| \preceq \beta \odot(\Phi(y) \ominus \Phi(u)) \tag{3.4}
\end{equation*}
$$

and

$$
\begin{align*}
& \bigoplus_{i=1}^{m}(1-\beta) \odot\left(\left(y_{i}-u_{i}\right) \odot \mathbf{G}_{2 i}^{w}\right) \bigoplus_{j=m+1}^{n}(1-\beta) \odot\left(\left(y_{j}-u_{j}\right) \odot \mathbf{G}_{2 j}^{w}\right) \ominus_{g H}(1-\beta) c_{2}\|y-u\| \\
& \preceq(1-\beta) \odot(\Phi(y) \ominus \Phi(u)) . \tag{3.5}
\end{align*}
$$

By adding (3.4) and (3.5), we obtain

$$
\begin{align*}
& \bigoplus_{i=1}^{m}\left(y_{i}-u_{i}\right) \odot\left\{\beta \odot \mathbf{G}_{1 i}^{w} \oplus(1-\beta) \odot \mathbf{G}_{2 i}^{w}\right\} \bigoplus_{j=m+1}^{n}\left(y_{j}-u_{j}\right) \odot\left\{\beta \odot \mathbf{G}_{1 j}^{w} \oplus(1-\beta) \odot \mathbf{G}_{2 j}^{w}\right\} \\
& \ominus_{g H}\left(\beta c_{1} \oplus(1-\beta) c_{2}\right)\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) . \tag{3.6}
\end{align*}
$$

Therefore, we have

$$
\left\{\boldsymbol{\beta} \odot \widehat{\mathbf{G}_{1}^{w}} \oplus(1-\beta) \odot \widehat{\mathbf{G}_{2}^{w}}\right\}^{\top} \odot(y-u) \ominus_{g H}\left(\beta c_{1} \oplus(1-\beta) c_{2}\right)\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u),
$$

i.e., $\left(\beta \odot \widehat{\mathbf{G}_{1}^{w}} \oplus(1-\beta) \odot \widehat{\mathbf{G}_{2}^{w}}, \beta c_{1} \oplus(1-\beta) c_{2}\right) \in \partial^{w} \Phi(u)$, which proves the convexity of $\partial^{w} \Phi(u)$.

Theorem 3.2. (Closedness of $g H$-weak subdifferential). Let $\emptyset \neq \mathscr{Y} \subseteq I(\mathbb{R})^{n}$. Iffor an IVF $\Psi: \mathscr{Y} \rightarrow$ $I(\mathbb{R})$, the set $\partial^{w} \Psi(u)$ is nonempty at $u \in \mathscr{Y}$, then $\partial^{w} \Psi(u)$ is closed.

Proof. Let $\left\{\left(\widehat{\mathbf{G}_{k}^{w}}, c_{k}\right)\right\}$ be an arbitrary sequence in $\partial^{w} \Psi(u)$ converging to $\left(\widehat{\mathbf{G}^{w}}, c\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}$, where $\widehat{\mathbf{G}_{k}^{w}}=\left(\mathbf{G}_{k 1}^{w}, \mathbf{G}_{k 2}^{w}, \ldots, \mathbf{G}_{k n}^{w}\right)^{\top}$ and $\widehat{\mathbf{G}^{w}}=\left(\mathbf{G}_{1}^{w}, \mathbf{G}_{2}^{w}, \ldots, \mathbf{G}_{n}^{w}\right)^{\top}$. Since $\left(\widehat{\mathbf{G}_{k}^{w}}, c\right) \in \partial^{w} \Psi(u)$ for all $d \in \mathscr{Y}$, we obtain $\widehat{\mathbf{G}_{k}^{w}} \odot d \ominus_{g H} c_{k}\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u)$, which implies

$$
\begin{equation*}
\bigoplus_{i=1}^{n} d_{i} \odot \mathbf{G}_{k i}^{w} \ominus_{g H} c_{k}\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) . \tag{3.7}
\end{equation*}
$$

Up to a rearrangement of terms, let the first $p$ components of $d$ be non-negative, and the rest be negative. Then, from (3.7), we have

$$
\begin{aligned}
& \bigoplus_{i=1}^{p} d_{i} \odot \mathbf{G}_{k i}^{w} \bigoplus_{j=p+1}^{n} d_{j} \odot \mathbf{G}_{k j}^{w} \ominus_{g H} c_{k}\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) \\
\Longrightarrow & \bigoplus_{i=1}^{p} d_{i} \odot\left[\underline{g_{k i}^{w}}, \overline{g_{k i}^{w}}\right] \bigoplus_{j=p+1}^{n} d_{j} \odot\left[\underline{g_{k j}^{w}}, \overline{g_{k j}^{w}}\right] \ominus_{g H} c_{k}\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) .
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
\sum_{i=1}^{p} g_{k i}^{w} d_{i}+\sum_{j=p+1}^{n} \overline{g_{k j}^{w}} d_{j}-c_{k}\|d\| \leq \min \{\underline{\Psi}(u+d)-\underline{\Psi}(u), \bar{\Psi}(u+d)-\bar{\Psi}(u)\} \tag{3.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{i=1}^{p} \overline{g_{k i}^{w}} d_{i}+\sum_{j=p+1}^{n} \underline{g_{k j}^{w}} d_{j}-c_{k}\|d\| \leq \max \{\underline{\Psi}(u+d)-\underline{\Psi}(u), \bar{\Psi}(u+d)-\bar{\Psi}(u)\} . \tag{3.9}
\end{equation*}
$$

Since sequence $\widehat{\mathbf{G}_{k}^{w}}$ converges to $\widehat{\mathbf{G}^{w}}$, and sequences $\left\{\underline{g_{k i}^{w}}\right\}$ and $\left\{\overline{g_{k i}^{w}}\right\}$ converge to $\left\{\underline{g_{i}^{w}}\right\}$ and $\left\{\overline{g_{i}^{w}}\right\}$, respectively for all $i$. Thus, by (3.8) and (3.9), we have

$$
\begin{aligned}
\sum_{i=1}^{p} g_{k i}^{w} d_{i}+\sum_{j=p+1}^{n} \overline{g_{k j}^{w}} d_{j}-c_{k}\|d\| & \rightarrow \sum_{i=1}^{p} \underline{g_{i}^{w}} d_{i}+\sum_{j=p+1}^{n} \overline{g_{j}^{w}} d_{j}-c\|d\| \\
& \leq \min \{\underline{\Psi}(u+d)-\underline{\Psi}(u), \bar{\Psi}(u+d)-\bar{\Psi}(u)\}
\end{aligned}
$$

and

$$
\begin{aligned}
\sum_{i=1}^{p} \overline{g_{k i}^{w}} d_{i}+\sum_{j=p+1}^{n} \underline{g_{k j}^{w}} d_{j}-c_{k}\|d\| & \rightarrow \sum_{i=1}^{p} \overline{g_{i}^{w}} d_{i}+\sum_{j=p+1}^{n} \underline{g_{j}^{w}} d_{j}-c\|d\| \\
& \leq \max \{\underline{\Psi}(u+d)-\underline{\Psi}(u), \bar{\Psi}(u+d)-\bar{\Psi}(u)\}
\end{aligned}
$$

Hence, for any $u \in \mathscr{Y}$,

$$
\begin{aligned}
& {\left[\sum_{i=1}^{p} g_{i}^{w} d_{i}+\sum_{j=p+1}^{n} \overline{g_{j}^{w}} d_{j}-c\|d\|, \sum_{i=1}^{p} \overline{g_{i}^{w}} d_{i}+\sum_{j=p+1}^{n} g_{j}^{w} d_{j}-c\|d\|\right] \preceq \Psi(u+d) \ominus_{g H} \Psi(u) } \\
& \Longrightarrow \bigoplus_{i=1}^{p}\left[\underline{g_{i}^{w}} d_{i}, \overline{g_{i}^{w}} d_{i}\right] \bigoplus_{j=p+1}^{n}\left[\overline{g_{j}^{w}} d_{j}, \underline{g_{j}^{w}} d_{j}\right] \ominus_{g H} c\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) \\
& \Longrightarrow \bigoplus_{i=1}^{p} d_{i} \odot \mathbf{G}_{i}^{w} \bigoplus_{j=p+1}^{n} d_{j} \odot \mathbf{G}_{j}^{w} \ominus_{g H} c\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) \\
& \Longrightarrow \widehat{\mathbf{G}}^{\top} \\
& \top \\
& \top \ominus_{g H} c\|d\| \preceq \Psi(u+d) \ominus_{g H} \Psi(u) .
\end{aligned}
$$

Therefore, $\widehat{\mathbf{G}^{w}} \in \partial^{w} \Psi(u)$, and hence $\partial^{w} \Psi(u)$ is closed.
Definition 3.2. ( $g H$-Fréchet lower subdifferential). $\operatorname{Let} \Phi: \mathscr{Y} \rightarrow I(\mathbb{R}) \cup\{-\infty,+\infty\}$ be an IVF that is finite at an $u \in \mathscr{Y}$. Then, the $g H$-Fréchet lower subdifferential of $\Phi$ at $u$ is defined by

$$
\partial_{\mathscr{F}}^{-} \Phi(u)=\left\{\widehat{\boldsymbol{G}}: \boldsymbol{0} \preceq \liminf _{\substack{y \rightarrow u \\ y \neq u}} \frac{1}{\|y-u\|} \odot\left\{\Phi(y) \ominus_{g H} \Phi(u) \ominus_{g H} \widehat{\boldsymbol{G}}^{\top} \odot(y-u)\right\},\right.
$$

where $\widehat{\boldsymbol{G}}: \mathscr{Y} \rightarrow I(\mathbb{R})$ is a gH-continuous and linear IVF $\}$.
One important fact is that $g H$-weak subdifferential is an immediate consequence of $g H$-Fréchet lower subdifferential.

Theorem 3.3. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. If $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ has $g H$-Fréchet lower subdifferential $\widehat{\boldsymbol{G}}$ at the point $u$, then $(\widehat{\boldsymbol{G}}, \varepsilon)$ is a $g H$-weak subgradient of $\Phi$ at $u$ for any $\varepsilon \in \mathbb{R}_{+}$.
Proof. Let $\widehat{\mathbf{G}} \in \partial_{\mathscr{F}}^{-} \Phi(u)$. Due to Definition 3.2, we can write

$$
\mathbf{0} \preceq \liminf _{\substack{y \rightarrow u \\ y \neq u}} \frac{1}{\|y-u\|} \odot\left\{\Phi(y) \ominus_{g H} \Phi(u) \ominus_{g H} \widehat{\mathbf{G}}^{\top} \odot(y-u)\right\} .
$$

Then, for the $\varepsilon>0$ in the hypothesis there exists $\delta>0$ such that

$$
-\varepsilon\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) \ominus_{g H} \widehat{\mathbf{G}}^{\top} \odot(y-u) \forall y \in B_{\delta}(u),
$$

Then, from Lemma 2.3, we have $\widehat{\mathbf{G}}^{\top} \odot(y-u) \ominus_{g H} \varepsilon\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u)$. By Definition 3.1, $(\widehat{\mathbf{G}}, \varepsilon)$ is a $g H$-weak subdifferential of $\Phi$ at $u$.
Lemma 3.1. For any $y \in \mathbb{R}^{n}$ and $\widehat{\boldsymbol{C}}=\left(\boldsymbol{C}_{1}, \boldsymbol{C}_{2}, \boldsymbol{C}_{3}, \ldots, \boldsymbol{C}_{n}\right) \in I(\mathbb{R})^{n},-\|y\|\|\widehat{\boldsymbol{C}}\|_{I(\mathbb{R})^{n}} \preceq\left\|y^{\top} \odot \widehat{\boldsymbol{C}}\right\|_{I(\mathbb{R})}$. Proof. See Appendix E.

To investigate the class of interval-valued functions for which weak subgradients always exist, we need the following definition.

Definition 3.3. ( $g H$-lower Lipschitz IVF). Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. An IVF $\Phi: \mathscr{Y} \rightarrow \overline{I(\mathbb{R})}$ is called gH-lower locally Lipschitz at $u \in \mathscr{Y}$ if $\exists L \geq 0$ and a neighbourhood $\mathscr{N}(u)$ of $u$ such that

$$
\begin{equation*}
-L\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) \forall y \in \mathscr{N}(u) . \tag{3.10}
\end{equation*}
$$

If the inequality (3.10) satisfies for all $y \in \mathscr{Y}$, then $\Phi$ is called $g H$-lower Lipschitz at $u \in \mathscr{Y}$ with Lipschitz constant $L$.

Example 3.2. Let $\Phi:[1, \infty) \rightarrow I(\mathbb{R})$ be an IVF, and defined by $\Phi(y)=\ln y \odot \boldsymbol{C}$ for all $y \in[1, \infty)$, where $\mathbf{0} \preceq \boldsymbol{C}=[\underline{c}, \bar{c}]$. Let $\delta>0$. We choose the neighbourhood of $u, \mathscr{N}_{\delta}(u)=\{y:|y-u|<\delta\}$. If $0<y-u<\delta$, then $u<y$ and also then $\frac{y}{u}>1$ and then

$$
\begin{align*}
0<\ln \frac{y}{u} & <\frac{y}{u}-1, \text { since } \ln (1+p)<p \text { if } p>0 \\
& \leq y-u . \tag{3.11}
\end{align*}
$$

Since $\underline{c}, \bar{c} \geq 0$, we have $(\ln y-\ln u) \underline{c} \leq(y-u) \underline{c}$ and $(\ln y-\ln u) \bar{c} \leq(y-u) \bar{c}$. Then,

$$
\begin{equation*}
(\ln y-\ln u) \odot \boldsymbol{C} \preceq(y-u) \odot \boldsymbol{C} . \tag{3.12}
\end{equation*}
$$

If $-\delta<y-u<0$, then $y<u$ and also then $\frac{u}{y}>1$ and then

$$
\begin{align*}
0<\ln \frac{u}{y} & <\frac{u}{y}-1, \text { since } \ln (1+p)<p \text { if } p>0 \\
& \leq u-y . \tag{3.13}
\end{align*}
$$

Then, $(\ln u-\ln y) \odot \boldsymbol{C} \preceq(u-y) \odot \boldsymbol{C}$, which together with (3.12) yields that

$$
\begin{aligned}
& |\ln y-\ln u| \odot \boldsymbol{C} \preceq|y-u| \odot \boldsymbol{C} \\
\Longrightarrow & \ln u \odot \boldsymbol{C} \ominus_{g H} \ln y \odot \boldsymbol{C} \preceq|y-u| \odot \boldsymbol{C} \\
\Longrightarrow & -|y-u| \odot \boldsymbol{C} \preceq \ln y \odot \boldsymbol{C} \ominus_{g H} \ln u \odot \boldsymbol{C} \\
\Longrightarrow & -\bar{c}|y-u| \preceq \Phi(y) \ominus_{g H} \Phi(u) .
\end{aligned}
$$

This shows that $\Phi$ is gH -lower locally Lipschitz on $\mathscr{N}_{\delta}(u)$ with $L=\bar{c}$. From arbitrariness of $y$,u in $[1, \infty)$, we conclude that $\Phi$ is $g H$-lower Lipschitz on $[1, \infty)$.
Theorem 3.4. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi: \mathscr{Y} \rightarrow \overline{I(\mathbb{R})}$ be an IVF, where $\Phi(u)$ is finite for some $u \in \mathscr{Y}$. Then, the following three statements are equivalent:
(a) $\Phi$ is gH -weak subdifferentiable at $u$.
(b) $\Phi$ is gH -lower Lipschitz at u.
(c) $\Phi$ is $g H$-lower locally Lipschitz at $u$, and there exists a number $p \geq 0$ and an interval $\boldsymbol{Q}$ such that

$$
\begin{equation*}
-p\|y\| \oplus \boldsymbol{Q} \preceq \boldsymbol{\Phi}(y) \forall y \in \mathscr{\mathscr { Y }} . \tag{3.14}
\end{equation*}
$$

Proof. (a) implies (b) : Suppose that $\Phi$ is $g H$-weak subdifferentiable at $u$. Then, there exists $\left(\widehat{\mathbf{G}^{w}}, c\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}$such that, for any $y \in \mathscr{Y}$,

$$
\begin{equation*}
{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) . \tag{3.15}
\end{equation*}
$$

From Lemma 3.1, we have $-\left\|\widehat{\mathbf{G}^{w}}\right\|_{I(\mathbb{R})^{n}}\|y-u\|-c\|y-u\| \preceq \widehat{\mathbf{G}^{w}} \odot(y-u) \ominus_{g H} c\|y-u\|$. Hence, the inequality (3.15) yields

$$
-\left(\left\|\widehat{\mathbf{G}^{w}}\right\|+c\right)\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) \text { by Lemma } 2.3 \text { (ii) of [1]. }
$$

By choosing $L=\left(\left\|\widehat{\mathbf{G}^{w}}\right\|+c\right)$, we obtain $-L\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u)$ for all $y \in \mathscr{Y}$. So, $\Phi$ is $g H$-lower Lipschitz at $u$.
(b) implies (c) : Suppose that (b) is satisfied. It needs to prove that the inequality (3.14) holds. Then, there exists an $L \geq 0$ such that

$$
\begin{equation*}
-L\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u) . \tag{3.16}
\end{equation*}
$$

Note that $-L\|y\|-L\|u\| \leq-L\|y-u\|$. So, inequality (3.16) gives $-L\|y\|-L\|u\| \preceq \Phi(y) \ominus_{g H} \Phi(u)$, which gives $\Phi(u) \ominus_{g H} L\|u\|-L\|y\| \preceq \Phi(y)$ by (iv) of Lemma 2.6. Taking $\mathbf{Q}=\Phi(u) \ominus_{g H} L\|u\|$ and $p=L$, we obtain $-p\|y\| \oplus \mathbf{Q} \preceq \Phi(y)$ for all $y \in \mathscr{Y}$.
(c) implies (a) : Let $\mathscr{N}(u)$ be an $\varepsilon$-neighbourhood of $u$ such that (3.10) holds. Then,

$$
\begin{equation*}
-L\|y-u\| \preceq \Phi(y) \ominus_{g H} \Phi(u), \forall y \in \mathscr{N}(u) \tag{3.17}
\end{equation*}
$$

and

$$
\begin{equation*}
-p\|y\| \oplus \mathbf{Q} \preceq \Phi(y), \forall y \in \mathbb{R}^{n} \tag{3.18}
\end{equation*}
$$

Assume to the contrary that $\Phi$ is not $g H$-weak subdifferentiable at $u$. Then, for any $\left(\widehat{\mathbf{G}_{n}^{w}}, c_{n}\right) \in$ $I(\mathbb{R})^{n} \times \mathbb{R}_{+}$, there exists $y_{n}$ such that

$$
\Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) \prec{\widehat{\mathbf{G}_{n}^{w}}}^{\top} \odot\left(y_{n}-u\right) \ominus_{g H} c_{n}\left\|y_{n}-u\right\| .
$$

If the sequence $\left\{\widehat{\mathbf{G}_{n}^{w}}\right\}$ is assumed to be converging to $\widehat{\mathbf{G}^{w}}$, then

$$
\begin{align*}
\Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) & \preceq{\widehat{\mathbf{G}^{w}}}^{\top} \odot\left(y_{n}-u\right) \ominus_{g H} c_{n}\left\|y_{n}-u\right\| \\
& \preceq\left\|\widehat{\mathbf{G}}^{\widehat{w}}\right\|\left\|y_{n}-u\right\|-c_{n}\left\|y_{n}-u\right\|, \text { by Theorem } 3.1 \text { of [11]. } \tag{3.19}
\end{align*}
$$

By putting $y=y_{n}$ in (3.18), we have

$$
-p\left\|y_{n}-u\right\|-p\|u\| \oplus \mathbf{Q} \preceq-p\left\|y_{n}\right\| \oplus \mathbf{Q} \preceq \Phi\left(y_{n}\right),
$$

which implies

$$
\begin{equation*}
\left(-p\left\|y_{n}-u\right\|-p\|u\| \oplus \mathbf{Q}\right) \ominus_{g H} \Phi(u) \preceq \Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) \text { by Note } 2 \text { of [1]. } \tag{3.20}
\end{equation*}
$$

From (3.19), (3.20), and [1, Lemma 2.3 (ii)], we deduce that

$$
\begin{gather*}
\quad\left(-p\left\|y_{n}-u\right\|-p\|u\| \oplus \mathbf{Q}\right) \ominus_{g H} \Phi(u) \preceq\left\|\widehat{\mathbf{G}^{w}}\right\|\left\|y_{n}-u\right\|-c_{n}\left\|y_{n}-u\right\|, \\
\text { or, }\left(c_{n}-p-\left\|\widehat{\mathbf{G}^{\widehat{w}}}\right\|\right)\left\|y_{n}-u\right\| \preceq \Phi(u) \oplus p\|u\| \ominus_{g H} \mathbf{Q} \text { by (iii) of Lemma 2.6. } \tag{3.21}
\end{gather*}
$$

Assume, without loss of generality, that $c_{n}-p-\left\|\widehat{\mathbf{G}^{w}}\right\| \neq 0$. Then, from (2.6), we obtain

$$
\left\|y_{n}-u\right\| \preceq \frac{1}{c_{n}-p-\left\|\widehat{\mathbf{G}^{w}}\right\|} \odot\left\{\Phi(u) \oplus p\|u\| \ominus_{g H} \mathbf{Q}\right\}
$$

As $\left(\Phi(u) \oplus p\|u\| \ominus_{g H} \mathbf{Q}\right)$ is bounded below on $\mathscr{N}(u)$, we have $y_{n} \rightarrow u$ as $c_{n} \rightarrow \infty$. Thus, $y_{n} \in \mathscr{N}(u)$ for large $n$. Then, it follows from (3.17) that

$$
\begin{equation*}
-L\left\|y_{n}-u\right\| \preceq \Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) . \tag{3.22}
\end{equation*}
$$

In view of (3.19), we obtain

$$
\Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) \preceq\left\|\widehat{\mathbf{G}^{\hat{w}}}\right\|\left\|y_{n}-u\right\|-c_{n}\left\|y_{n}-u\right\|=-\left(c_{n}-\left\|\widehat{\mathbf{G}^{\hat{w}}}\right\|\right)\left\|y_{n}-u\right\| .
$$

Since $c_{n} \rightarrow+\infty$ and $L \geq 0$, we can pick $c_{n}$ sufficiently large so that $c_{n}-\left\|\widehat{\mathbf{G}^{\omega}}\right\| \geq L$. So,

$$
\Phi\left(y_{n}\right) \ominus_{g H} \Phi(u) \preceq-L\left\|y_{n}-u\right\| .
$$

This inequality leads to a contradiction. So, the result follows.
Theorem 3.5. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Psi: \mathscr{Y} \rightarrow I(\mathbb{R})$ be gH-Fréchet differentiable at $u$ with gH-Fréchet derivative $\Psi_{\mathscr{F}}(u)$. Then, $\left\{\left(\Psi_{\mathscr{F}}(u), c\right): c \geq 0\right\} \subset \partial^{w} \Psi(u)$.

Proof. Since $\Psi$ is $g H$-Fréchet differentiable at $u$ with $g H$-Fréchet derivative $\Psi_{\mathscr{F}}(u)$, we have

$$
\begin{aligned}
& \lim _{y \rightarrow u} \frac{1}{\|y-u\|} \odot\left\{\Psi(y) \ominus_{g H} \Psi(u) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}=\mathbf{0} \\
\Longrightarrow & \liminf _{\substack{y \rightarrow u \\
y \neq u}} \frac{1}{\|y-u\|} \odot\left\{\Psi(y) \ominus_{g H} \Psi(u) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}=\mathbf{0} .
\end{aligned}
$$

Therefore, by Definition 3.2, $\Psi_{\mathscr{F}}(u) \in \partial_{\mathscr{F}}^{-} \Psi(u)$, one has

$$
\begin{aligned}
& \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u) \preceq \Psi(y) \ominus_{g H} \Psi(u) \forall y \in \mathscr{Y} \\
\Longrightarrow & \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi(y) \ominus_{g H} \Psi(u), \text { for any } c \geq 0 .
\end{aligned}
$$

Hence, $\left(\Psi_{\mathscr{F}}(u), c\right) \in \partial^{w} \Psi(u)$.
Lemma 3.2. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ be $g H$-Fréchet differentiable at $u$ with $g H$-Fréchet derivative $\Phi_{\mathscr{F}}(u)$. Then, $-1 \odot \Phi_{\mathscr{F}}(u) \in \partial_{\mathscr{F}}^{-}(-1 \odot \Phi)(u)$.

Proof. Since $\Phi$ is $g H$-Fréchet differentiable at $u$ with $g H$-Fréchet derivative $\Phi_{\mathscr{F}}(u)$, one sees that

$$
\lim _{y \rightarrow u} \frac{1}{\|y-u\|} \odot\left\{\Phi(y) \ominus_{g H} \Phi(u) \ominus_{g H} \Phi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}=\mathbf{0} .
$$

By applying Lemma 2.5 , we have

$$
\begin{aligned}
& \left.\lim _{\substack{y \rightarrow u \\
y \neq u}} \frac{1}{\|y-u\|} \odot\left\{\mathbf{0} \ominus_{g H}\left\{(-1 \odot \Phi)(y) \ominus_{g H}(-1 \odot \Phi)(u) \ominus_{g H}\left(-1 \odot \Phi_{\mathscr{F}}(u)^{\top}\right) \odot(y-u)\right\}\right\}\right\}=\mathbf{0} \\
\Longrightarrow & \lim _{\substack{y \rightarrow u \\
y \neq u}} \frac{1}{\|y-u\|} \odot\left\{(-1 \odot \Phi)(y) \ominus_{g H}(-1 \odot \Phi)(u) \ominus_{g H}\left(-1 \odot \Phi_{\mathscr{F}}(u)\right)^{\top} \odot(y-u)\right\}=\mathbf{0} \\
\Longrightarrow & \liminf _{\substack{y \rightarrow u \\
y \neq u}} \frac{1}{\|y-u\|} \odot\left\{(-1 \odot \Phi)(y) \ominus_{g H}(-1 \odot \Phi)(u) \ominus_{g H}\left(-1 \odot \Phi_{\mathscr{F}}(u)\right)^{\top} \odot(y-u)\right\}=\mathbf{0} .
\end{aligned}
$$

Hence, $-1 \odot \Phi_{\mathscr{F}}(u) \in \partial_{\overline{\mathscr{F}}}^{-}(-1 \odot \Phi)(u)$.
Next, we focus on investigating the sum rule of two functions in terms of $g H$-weak subdifferential. For two real-valued functions $f_{1}$ and $f_{2}$, the sum rule [15] for their weak subdifferential is $\partial^{w}\left(f_{1}+\right.$ $\left.f_{2}\right)(x)=\partial^{w} f_{1}(x)+\partial^{w} f_{2}(x)$. However, this sum rule does not hold for interval-valued functions. In the following, we provide such an example.

Consider the interval-valued functions $\Phi_{1}:[-1,1] \rightarrow I(\mathbb{R})$ and $\Phi_{2}:[-1,1] \rightarrow I(\mathbb{R})$, defined by

$$
\Phi_{1}(y)=\left\{\begin{array}{ll}
{\left[-y, \frac{1}{2} y\right],} & \text { if } y \in[0,1] \\
{\left[-\frac{1}{2} y,-y\right],} & \text { if } y \in[-1,0]
\end{array} \text { and } \Phi_{2}(y)=\left[y^{2},-y+3\right]\right.
$$

respectively. For these two functions, the $g H$-weak subdifferential at $u=0$ are given by

$$
\partial^{w} \Phi_{1}(0)=\left\{\left(\mathbf{G}_{1}^{w}, c_{1}\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:\left[-1,-\frac{1}{2}\right] \preceq \mathbf{G}_{1}^{w} \oplus c_{1}, \mathbf{G}_{1}^{w} \ominus_{g H} c_{1} \preceq\left[-1, \frac{1}{2}\right]\right\}
$$

and

$$
\partial^{w} \Phi_{2}(0)=\left\{\left(\mathbf{G}_{2}^{w}, c_{2}\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:[-1,0] \preceq \mathbf{G}_{2}^{w} \oplus c_{2}, \mathbf{G}_{2}^{w} \ominus_{g H} c_{2} \preceq[-1,0]\right\} .
$$

Thus, we have

$$
\begin{align*}
& \partial^{w} \Phi_{1}(0) \oplus \partial^{w} \Phi_{2}(0) \\
= & \left\{\left(\mathbf{H}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:\left[-2,-\frac{1}{2}\right] \preceq \mathbf{H}^{w} \oplus c, \mathbf{H}^{w} \ominus_{g H} c \preceq\left[-2, \frac{1}{2}\right], \forall y \in[-1,1]\right\} . \tag{3.23}
\end{align*}
$$

Now, let $\left(\mathbf{H}^{w}, c\right) \in \partial^{w}\left(\Phi_{1} \oplus \Phi_{2}\right\}(0)$, where

$$
\left(\Phi_{1} \oplus \Phi_{2}\right)(y)= \begin{cases}{\left[y^{2}-y,-\frac{1}{2} y+3\right]} & \text { if } y \in[0,1] \\ {\left[y^{2}-\frac{1}{2} y,-2 y+3\right]} & \text { if } y \in[-1,0]\end{cases}
$$

There are the following two cases corresponding to $y \in[0,1]$ and $y \in[-1,0]$.
(i) As $y \geq 0$, we have

$$
\begin{aligned}
& \mathbf{H}^{w} \odot y \ominus_{g H} c \odot y \preceq\left(\Phi_{1} \oplus \Phi_{2}\right)(y) \ominus_{g H}\left(\Phi_{1} \oplus \Phi_{2}\right)(0) \\
\Longrightarrow & {\left[h^{w}-c, \overline{h^{w}}-c\right] \odot y \preceq\left[y^{2}-y,-\frac{1}{2} y\right] } \\
\Longrightarrow & \underline{h^{w}}-c \leq-1 \text { and } \overline{h^{w}}-c \leq-\frac{1}{2} .
\end{aligned}
$$

(ii) As $-1 \leq y \leq 0$, we have

$$
\begin{aligned}
& {\left[\left(\overline{h^{w}}+c\right) y,\left(\underline{h^{w}}+c\right) y\right] \preceq\left[y^{2}-\frac{1}{2} y,-2 y+3\right] \ominus_{g H}[0,3] } \\
\Longrightarrow & {\left[\left(\overline{h^{w}}+c\right) y,\left(\underline{h^{w}}+c\right) y\right] \preceq\left[y^{2}-\frac{1}{2} y,-2 y\right] } \\
\Longrightarrow & -2-c \leq \underline{h^{w}} \text { and }-\frac{1}{2}-c \leq \overline{h^{w}} .
\end{aligned}
$$

Therefore, from Case (i) and Case (ii), we have

$$
\begin{align*}
& \partial^{w}\left(\Phi_{1} \oplus \Phi_{2}\right)(0) \\
= & \left\{\left(\mathbf{H}^{w}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}:\left[-2,-\frac{1}{2}\right] \preceq\left(\mathbf{H}^{w} \oplus c\right),\left(\mathbf{H}^{w} \ominus_{g H} c\right) \preceq\left[-1,-\frac{1}{2}\right]\right\} . \tag{3.24}
\end{align*}
$$

Thus, (3.23) and (3.24) are not equal.
In the following theorem, we show that under some restriction on $\Phi_{1}$ and $\Phi_{2}$ one-sided inclusion for the sum rule holds.

Theorem 3.6. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi_{1}: \mathscr{Y} \rightarrow I(\mathbb{R})$ be gH-weak subdifferential at $u$ and $\Phi_{2}: \mathscr{Y} \rightarrow \mathbb{R}$ be $g H$-Fréchet differentiable at $u$. Then, $\partial^{w}\left(\Phi_{1} \oplus \Phi_{2}\right)(u) \subset \partial^{w} \Phi_{1}(u) \oplus \partial^{w} \Phi_{2}(u)$, provided that $w\left(\widehat{\boldsymbol{G}_{1}^{w}}\right) \leq w\left(\widehat{\boldsymbol{G}_{2}^{w}}\right)$ for all $\widehat{\boldsymbol{G}_{1}^{w}} \in \partial \Phi_{2}(y)$ and $\widehat{\boldsymbol{G}_{2}^{w}} \in \partial\left(\Phi_{1} \oplus \Phi_{2}\right)(y)$, where $w(\boldsymbol{A})$ is the width of the interval $\boldsymbol{A} \in I(\mathbb{R})$.
Proof. If $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w}\left(\Phi_{1} \oplus \Phi_{2}\right)(u)$, then

$$
\begin{equation*}
{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq\left(\Phi_{1} \oplus \Phi_{2}\right)(y) \ominus_{g H}\left(\Phi_{1} \oplus \Phi_{2}\right)(u) . \tag{3.25}
\end{equation*}
$$

We know that $\Phi_{2}: \mathscr{Y} \rightarrow I(\mathbb{R})$ is $g H$-Fréchet differentiable at $u$ with the $g H$-Fréchet derivative $\Phi_{2 \mathscr{F}}(u)$. Hence, $\Phi_{2 \mathscr{F}}(u) \in \partial_{\mathscr{F}}^{-} \Phi_{2}(u)$ implies $-1 \odot \Phi_{2 \mathscr{F}}(u) \in \partial_{\mathscr{F}}^{-}\left(-1 \odot \Phi_{2}\right)(u)$. We can then write

$$
\begin{align*}
& -1 \odot \Phi_{2 \mathscr{F}}(u) \odot(y-u) \preceq\left(-1 \odot \Phi_{2}\right)(u) \ominus_{g H}\left(-1 \odot \Phi_{2}\right)(u) \\
\Longrightarrow & -1 \odot \Phi_{2 \mathscr{F}}(u) \odot(y-u) \preceq-1 \odot\left(\Phi_{2}(u) \ominus_{g H} \Phi_{2}(u)\right) \\
& \text { by properties of } g H \text {-difference (iv) of [28]. } \tag{3.26}
\end{align*}
$$

In view of Lemma 2.4, (3.25) becomes

$$
\widehat{\mathbf{G}}^{\top}{ }^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq\left(\Phi_{1}(y) \ominus_{g H} \Phi_{1}(u)\right) \oplus\left(\Phi_{2}(y) \ominus_{g H} \Phi_{2}(u)\right) .
$$

Using (v) of Lemma 2.6, this inequality reduces to

$$
{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H}\left(\Phi_{2}(y) \ominus_{g H} \Phi_{2}(u)\right) \ominus_{g H} c\|y-u\| \preceq \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) .
$$

Now, from the inequality (3.26), we see that

$$
{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} \Phi_{2 \mathscr{F}}(u) \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) .
$$

Thus,

$$
\left(\widehat{\mathbf{G}^{w}} \ominus_{g H} \Phi_{2 \mathscr{F}}(u)\right)^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) .
$$

Then, $\left(\widehat{\mathbf{G}^{w}} \ominus_{g H} \Phi_{2 \mathscr{F}}(u), c\right) \in \partial^{w} \Phi_{1}(u)$ and $\left(\Phi_{2 \mathscr{F}}(u), 0\right) \in \partial^{w} \Phi_{2}(u)$. Therefore, $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi_{1}(u) \oplus$ $\partial^{w} \Phi_{2}(u)$. Hence, the result follows.

Theorem 3.7. Let $\mathscr{Y}$ be a nonempty set of $\mathbb{R}^{n}$. Let $\Phi_{1}: \mathscr{Y} \rightarrow I(\mathbb{R})$ be $g H$-Fréchet differentiable at u. Let $\Phi_{2}: \mathscr{Y} \rightarrow I(\mathbb{R})$ be an IVF. If $u$ is a weak efficient point of $\Phi_{1} \oplus \Phi_{2}$, then $\left(-1 \odot \Phi_{1 \mathscr{F}}(u), 0\right) \in$ $\partial^{w} \Phi_{2}(u)$.
Proof. Since $u$ is a weak efficient point of $\Phi_{1} \oplus \Phi_{2}$, for any $y \in \mathscr{Y}$,

$$
\begin{align*}
& \left(\Phi_{1} \oplus \Phi_{2}\right)(u) \preceq\left(\Phi_{1} \oplus \Phi_{2}\right)(y) \\
\Longrightarrow & \Phi_{1}(u) \oplus \Phi_{2}(u) \preceq \Phi_{1}(y) \oplus \Phi_{2}(y) \\
\Longrightarrow & \Phi_{1}(u) \ominus_{g H} \Phi_{1}(y) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u), \text { using Lemma } 2 \text { of [1] } \\
\Longrightarrow & (-1) \odot\left\{\Phi_{1}(y) \ominus_{g H} \Phi_{1}(u)\right\} \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u), \text { by } \ominus_{g H} \text { property in (iv) of [28] } \\
\Longrightarrow & \left(-1 \odot \Phi_{1}\right)(y) \ominus_{g H}\left(-1 \odot \Phi_{1}\right)(u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u), \\
& \text { by } \ominus_{g H} \text { property in (iv) of [28]. } \tag{3.27}
\end{align*}
$$

By Lemma 3.2, we also obtain that

$$
\begin{equation*}
(-1) \odot \Phi_{1 \mathscr{F}}(u) \odot(y-u) \preceq\left(-1 \odot \Phi_{1}\right)(y) \ominus_{g H}\left(-1 \odot \Phi_{1}\right)(u) \forall y \in \mathscr{Y} . \tag{3.28}
\end{equation*}
$$

We see from (3.27) and (3.28) that

$$
(-1) \odot \Phi_{1 \mathscr{F}}(u) \odot(y-u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u) \text { by lemma } 1 \text { of [1], }
$$

which shows that $\left((-1) \odot \Phi_{1 \mathscr{F}}(u), 0\right) \in \partial^{w} \Phi_{2}(u)$.
Theorem 3.8. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Psi$ be $g H$-Fréchet differentiable at $u$ with the $g H$-Fréchet derivative $\Psi_{\mathscr{F}}(u)$. Then, $\Psi$ has weak efficient solution at $u$ if and only if, for any $y \in \mathscr{Y}, \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)=$ 0.

Proof. If $\Psi$ has a weak efficient point at $u$, then

$$
\begin{aligned}
\Psi(u) & \preceq \Psi(y) \\
\text { or, } \mathbf{0} & \preceq \Psi(y) \ominus_{g H} \Psi(u), \text { by Lemma } 2.1 \text { of [13]. }
\end{aligned}
$$

By $g H$-Fréchet differentiability of $\Psi$ at $u$, we have

$$
\lim _{\|h\| \rightarrow 0} \frac{\left\|\left(\Psi(u+h) \ominus_{g H} \Psi(u)\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot h\right\|_{I(\mathbb{R})}}{\|h\|}=0
$$

If we take $h=\lambda(y-u)$, then

$$
\begin{equation*}
\lim _{\lambda \rightarrow 0} \frac{\left\|\left(\Psi(u+\lambda(y-u)) \ominus_{g H} \Psi(u)\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot\{\lambda(y-u)\}\right\|_{I(\mathbb{R})}}{\|\lambda(y-u)\|}=0 \tag{3.29}
\end{equation*}
$$

Since $u$ is a weak efficient point of $\Psi$, we have from (3.29) that

$$
\begin{aligned}
& \lim _{\lambda \rightarrow 0} \frac{\left\|\mathbf{0} \ominus_{g H} \lambda \odot\left\{\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}\right\|_{I(\mathbb{R})}}{\|\lambda(y-u)\|} \leq 0 \text { by (i) of Lemma } 2.6 \\
\Longrightarrow & \lim _{\lambda \rightarrow 0} \frac{\left\|\lambda \odot\left\{\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}\right\|_{I(\mathbb{R})}}{\|\lambda(y-u)\|} \leq 0 \\
\Longrightarrow & \lim _{\lambda \rightarrow 0} \frac{\lambda\left\|\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\|_{I(\mathbb{R})}}{\lambda\|(y-u)\|} \leq 0 .
\end{aligned}
$$

Since the norm gives a non-negative value, we see that

$$
\frac{1}{\|y-u\|} \odot\left\{\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\}=\mathbf{0} .
$$

Thus, we obtain

$$
\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)=\mathbf{0} \text { for any } y \in \mathscr{Y} .
$$

To show the reverse part, we suppose that $\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)=\mathbf{0}$ for all $y$. Then, we have $\Psi_{\mathscr{F}}(u) \in$ $\partial_{\mathscr{F}}^{-} \Psi(u)$ and this clearly yields

$$
\begin{aligned}
& \mathbf{0}=\Psi_{\mathscr{F}}(u)^{\top} \odot(y-u) \preceq \Psi(y) \ominus_{g H} \Psi(u) \\
\Longrightarrow & \Psi(u) \preceq \Psi(y) \text { by (ii) of Lemma 2.1 in [13], }
\end{aligned}
$$

which means that $u$ is weak efficient point of $\Psi$.
Theorem 3.9. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. If $\Psi$ is $g H$-Fréchet differentiable at $u$, then $\Psi$ is $g H$-weak subdifferentiable at $u$ if and only if $\Psi_{\mathscr{F}}(u)$ is $g H$-weak subdifferentiable at $0 \in \mathscr{Y}$, and $\partial^{w}(\Psi(u))=$ $\partial^{w}\left(\Psi_{\mathscr{F}}(u)(0)\right)$.

Proof. By the $g H$-Fréchet differentiability of $\Psi$ at $u$, we have

$$
\lim _{\|h\| \rightarrow 0} \frac{1}{\|h\|} \odot\left\{\left(\Psi(u+h) \ominus_{g H} \Psi(u)\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot h\right\}=\mathbf{0}
$$

Inserting $h=\lambda \odot(y-u)$, by $g H$-weak subdifferentiability of $\Psi$ at $u$, we see that there exists $\left(\widehat{\mathbf{G}^{w}}, c\right) \in$ $\partial^{w} \Psi(u)$ such that, for any $y \in \mathscr{Y}$,

$$
{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi(y) \ominus_{g H} \Psi(u) .
$$

Hence,

$$
\lim _{\lambda \rightarrow 0} \frac{1}{\|\lambda(y-u)\|} \odot\left\{\left(\Psi(u+\lambda(y-u)) \ominus_{g H} \Psi(u)\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot \lambda(y-u)\right\}=\mathbf{0} .
$$

In view of the $g H$-weak subdifferentiability of $\Psi$ at $u$, we see, for any $y \in \mathscr{Y}$, that

$$
\lim _{\lambda \rightarrow 0} \frac{1}{\|\lambda(y-u)\|} \odot\left\{\left({\widehat{\mathbf{G}^{w}}}^{\top} \odot \lambda(y-u) \ominus_{g H} \lambda c\|y-u\|\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot \lambda(y-u)\right\} \preceq \mathbf{0}
$$

(by (ii) of Lemma 2.6)

$$
\Longrightarrow \frac{1}{\|(y-u)\|} \odot\left\{\left({\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\|\right) \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\} \preceq \mathbf{0} .
$$

Therefore, $\widehat{\mathbf{G}}^{\top}{ }^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \ominus_{g H} \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u) \preceq \mathbf{0}$ for all $y \in \mathscr{Y}$. Letting $z=y-u$, we obtain

$$
\begin{equation*}
{\widehat{\mathbf{G}^{w}}}^{\top} \odot z \ominus_{g H} c\|z\| \preceq \Psi_{\mathscr{F}}(u)^{\top} \odot z \forall z \in \mathscr{Y} . \tag{3.30}
\end{equation*}
$$

Note that the $g H$-Fréchet derivative $\Psi_{\mathscr{F}}(u)$ is also $g H$-Gáteaux derivative (see Theorem 5.2 of [13]). Hence, it is a linear IVF as in Definition 4.1 of [13]. By this fact, we have $\Psi_{\mathscr{F}}(u)^{\top} \odot(0)=\mathbf{0}$. Then, inequality (3.30) implies that $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w}\left(\Psi_{\mathscr{F}}(u)(0)\right)$.

Conversely, let $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w}\left(\Psi_{\mathscr{F}}(u)(0)\right)$. Then, we can write

$$
\begin{aligned}
& {\widehat{\mathbf{G}^{w}}}^{\top} \odot y \ominus_{g H} c\|y\| \preceq \Psi_{\mathscr{F}}(u)^{\top} \odot y \forall y \in \mathscr{Y} \\
\Longrightarrow & {\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi_{\mathscr{F}}(u)^{\top} \odot(y-u) \forall y \in \mathscr{Y} .
\end{aligned}
$$

Since $\Psi$ has $g H$-Fréchet derivative $\Psi_{\mathscr{F}}(u)$ and it is also a $g H$-subgradient, it follows that

$$
\Psi_{\mathscr{F}}(y)^{\top} \odot(y-u) \preceq \Psi(y) \ominus_{g H} \Psi(u) \forall y \in \mathscr{Y} .
$$

Thus ${\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi(y) \ominus_{g H} \Psi(u)$. Hence the proof is complete.
Theorem 3.10. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi$ be $g H$-Fréchet differentiable at $u$. If $u$ is a weak efficient point of $\Phi$, then

$$
\sup \left\{\widehat{\boldsymbol{G}}^{\top}{ }^{\top} \odot(y-u) \ominus_{g H} c\|y-u\|:\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in \partial^{w} \Phi(u)\right\}=\boldsymbol{0}
$$

Proof. First, we show that

$$
\Phi_{\mathscr{F}}(u)^{\top} \odot(y-u)=\sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u)\right\}
$$

by which the desired equality can be easily proved. Using the $g H$-Fréchet differentiability of $\Phi$ and taking the supremum on the inequality (3.30), we obtain

$$
\begin{aligned}
\sup _{\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u)}\left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\|\right\} & \preceq \sup _{\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u)}\left\{\Phi_{\mathscr{F}}(u)^{\top} \odot(y-u)\right\} \\
& =\Phi_{\mathscr{F}}(u)^{\top} \odot(y-u) .
\end{aligned}
$$

Since $\left(\Phi_{\mathscr{F}}(u), 0\right) \in \partial^{w} \Phi(u)$, one has

$$
\Phi_{\mathscr{F}}(u) \odot(y-u) \in\left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u)\right\}
$$

and hence the result follows.

## 4. Optimality for the Difference of Two IVFs

In this section, we consider the constrained IOP as below:

$$
\begin{equation*}
\min _{y \in \mathscr{Y}}\left\{\Phi_{2}(y) \ominus_{g H} \Phi_{1}(y)\right\} \tag{4.1}
\end{equation*}
$$

where $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$ and $\Phi_{1}, \Phi_{2}: \mathscr{Y} \rightarrow I(\mathbb{R})$ are two IVFs. We are going to study weak efficiency conditions for the IOP (4.1) under some additional assumptions.

Theorem 4.1. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi_{1}, \Phi_{2}: \mathscr{Y} \rightarrow I(\mathbb{R})$ be $g H$-weak subdifferentiable at $u$, which is a weak-efficient point of $\Phi_{2} \ominus_{g H} \Phi_{1}$. If $\Phi_{1}(u)=\Phi_{2}(u)$, then $\partial^{w} \Phi_{1}(u) \subset \partial^{w} \Phi_{2}(u)$.

Proof. The $g H$-weak subdifferentiability of $\Phi_{1}$ at $u$ implies that $\partial^{w} \Phi_{1}(u)$ is nonempty. Hence, there exists $\left(\widehat{\mathbf{U}^{w}}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}$such that

$$
\begin{equation*}
\widehat{\mathbf{U}}^{\top}{ }^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \text { for all } y \in \mathscr{Y} . \tag{4.2}
\end{equation*}
$$

Since $\Phi_{2} \ominus_{g H} \Phi_{1}$ gets the weak efficiency value $\mathbf{0}$ at $u$ for any $y \in \mathscr{Y}$, we have

$$
\begin{align*}
& \mathbf{0} \preceq\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y) \\
\Longrightarrow & \mathbf{0} \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{1}(y) \\
\Longrightarrow & \Phi_{1}(y) \preceq \Phi_{2}(y) \text { by Lemma 2.1(ii) of [13] } \\
\Longrightarrow & \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u) \text { by Note } 2 \text { of [1]. } \tag{4.3}
\end{align*}
$$

Consequently, inequality (4.3) implies that

$$
\widehat{\mathbf{U}}^{\boldsymbol{w}} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u) .
$$

This means $\left(\widehat{\mathbf{U}^{w}}, c\right) \in \partial^{w} \Phi_{2}(u)$. Hence, the result follows.
Note 4.1. If we take an efficient solution of $\Phi_{2} \ominus_{g H} \Phi_{1}$ instead of a weak efficient solution, the additional condition $\Phi_{1}(u)=\Phi_{2}(u)$ becomes essential for Theorem 4.1 to hold. For instance, let two IVFs $\Phi_{1}:\left[-\frac{1}{2}, \frac{1}{2}\right] \rightarrow I(\mathbb{R})$ and $\Phi_{2}:\left[-\frac{1}{2}, \frac{1}{2}\right] \rightarrow I(\mathbb{R})$ be defined as

$$
\Phi_{1}(y)=[2|y|,|y|+1] \text { and } \Phi_{2}(y)=\left[|y|, 2 y^{2}+|y|\right],
$$

respectively. Now, according to Theorem 4.1, $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y)=\left[2 y^{2}-1,-|y|\right]$, and 0 is an efficient point of $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)$ because $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y)$ and $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(0)$ are not comparable for all $y \in$ $\left[-\frac{1}{2}, \frac{1}{2}\right]$. Note that

$$
\begin{aligned}
\partial^{w} \Phi_{1}(0) & =\left\{\left(\boldsymbol{K}_{1}^{w}, c_{1}\right):[-2,-1] \preceq\left(\boldsymbol{K}_{1}^{w} \oplus c_{1}\right),\left(\boldsymbol{K}_{1}^{w} \ominus_{g H} c_{1}\right) \preceq[1,2]\right\} \\
\text { and } \partial^{w} \Phi_{2}(0) & =\left\{\left(\boldsymbol{K}_{2}^{w}, c_{2}\right):[-1,-1] \preceq\left(\boldsymbol{K}_{2}^{w} \oplus c_{2}\right),\left(\boldsymbol{K}_{2}^{w} \ominus_{g H} c_{2}\right) \preceq[1,1]\right\} .
\end{aligned}
$$

Hence, $\partial^{w} \Phi_{1}(0) \not \subset \partial^{w} \Phi_{2}(0)$. So, $\Phi_{1}(u)=\Phi_{2}(u)$ is an essential condition.

As the restriction $\Phi_{1}(u)=\Phi_{2}(u)$ is a bit restrictive, in the next result, we give more flexible condition for which the inclusion in Theorem 4.1 holds.

Theorem 4.2. Let $\emptyset \neq \mathscr{Y} \subseteq \mathbb{R}^{n}$. Let $\Phi_{1}, \Phi_{2}$ have $g H$-weak subdifferential at $u \in \mathscr{Y}$, and $\Phi_{2} \ominus_{g H} \Phi_{1}$ attains weak efficient solution at $u$. Then,

$$
\begin{equation*}
\partial^{w} \Phi_{1}(u) \subset \partial^{w} \Phi_{2}(u), \tag{4.4}
\end{equation*}
$$

provided that $w\left(\Phi_{1}(y)\right) \geq w\left(\Phi_{2}(y)\right)$ for all $y \in \mathscr{Y}$ or $w\left(\Phi_{1}(y)\right) \leq w\left(\Phi_{2}(y)\right)$ for all $y \in \mathscr{Y}$, where $w(\boldsymbol{A})$ is the width of the interval $\boldsymbol{A} \in I(\mathbb{R})$.

Proof. The $g H$-weak subdifferentiability of $\Phi_{1}$ at $u$ implies that $\partial^{w} \Phi_{1}(u)$ is nonempty. Hence, there exists $\left(\widehat{\mathbf{U}^{w}}, c\right) \in I(\mathbb{R}) \times \mathbb{R}_{+}$such that

$$
\begin{equation*}
\widehat{\mathbf{U}}^{\top}{ }^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \text { for all } y \in \mathscr{Y} . \tag{4.5}
\end{equation*}
$$

Since $u$ is a weak efficient point of $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)$, one has

$$
\begin{equation*}
\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(u) \preceq\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y) \forall y \in \mathscr{Y} . \tag{4.6}
\end{equation*}
$$

- Case 1. If $w\left(\Phi_{1}(y)\right) \geq w\left(\Phi_{2}(y)\right)$, then, for all $y \in \mathscr{Y}$, we have from inequality (4.6) that

$$
\begin{align*}
& {\left[\bar{\phi}_{2}(u)-\bar{\phi}_{1}(u), \underline{\phi}_{2}(u)-\underline{\phi}_{1}(u)\right] \preceq\left[\bar{\phi}_{2}(y)-\bar{\phi}_{1}(y), \underline{\phi}_{2}(y)-\underline{\phi}_{1}(y)\right] } \\
\Longrightarrow & \bar{\phi}_{1}(y)-\bar{\phi}_{1}(u) \leq \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u), \& \underline{\phi}_{1}(u)-\underline{\phi}_{1}(u) \leq \underline{\phi}_{2}(y)-\underline{\phi}_{2}(u) \tag{4.7}
\end{align*}
$$

Now there arise two subcases.

- Subcase 1. If $\underline{\phi}_{1}(y)-\underline{\phi}_{1}(u) \leq \bar{\phi}_{1}(y)-\bar{\phi}_{1}(u)$,
$\phi_{1}(y)-\phi_{1}(u) \leq \min \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}$ and
$\bar{\phi}_{1}(y)-\bar{\phi}_{1}(u) \leq \max \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}$.
Clearly, we have $\left[\underline{\phi}_{1}(y)-\underline{\phi}_{1}(u), \bar{\phi}_{1}(y)-\bar{\phi}_{1}(u)\right] \preceq\left[\min \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}\right.$, $\left.\max \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}\right]$.
- Subcase 2. If $\bar{\phi}_{1}(y)-\bar{\phi}_{1}(u) \leq \underline{\phi}_{1}(y)-\underline{\phi}_{1}(u)$,
$\bar{\phi}_{1}(y)-\bar{\phi}_{1}(u) \leq \min \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}$ and
$\underline{\phi}_{1}(y)-\underline{\phi}_{1}(u) \leq \max \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}$.
Clearly we have $\left[\bar{\phi}_{1}(y)-\bar{\phi}_{1}(u), \underline{\phi}_{1}(y)-\underline{\phi}_{1}(u)\right] \preceq\left[\min \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}\right.$, $\left.\max \left\{\underline{\phi}_{2}(y)-\underline{\phi}_{2}(u), \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u)\right\}\right]$.

Combining Subcase 1 and Subcase 2, we have

$$
\begin{equation*}
\Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u) . \tag{4.8}
\end{equation*}
$$

- Case 2. If $w\left(\Phi_{2}(u)\right) \geq w\left(\Phi_{1}(u)\right)$, then from the inequality (4.6), for all $y \in \mathscr{Y}$, we have

$$
\begin{align*}
& {\left[\underline{\phi}_{2}(u)-\underline{\phi}_{1}(u), \bar{\phi}_{2}(u)-\bar{\phi}_{1}(u)\right] \preceq\left[\underline{\phi}_{2}(y)-\underline{\phi}_{1}(y), \bar{\phi}_{2}(y)-\bar{\phi}_{1}(y)\right] } \\
\Longrightarrow \quad & \underline{\phi}_{1}(y)-\underline{\phi}_{1}(u) \leq \underline{\phi}_{2}(y)-\underline{\phi}_{2}(u) \& \bar{\phi}_{1}(y)-\bar{\phi}_{1}(u) \leq \bar{\phi}_{2}(y)-\bar{\phi}_{2}(u) . \tag{4.9}
\end{align*}
$$

By a similar manner as in Case 1, we have $\Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u)$.
Hence, in all cases, we have $\Phi_{1}(y) \ominus_{g H} \Phi_{1}(u) \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u)$. In view of (4.5), we have

$$
\widehat{\mathbf{U}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Phi_{2}(y) \ominus_{g H} \Phi_{2}(u) \text { for all } y \in \mathscr{Y}, \text { by Lemma } 2.3 \text { (ii) of [1], }
$$

which implies $\left(\widehat{\mathbf{U}^{w}}, c\right) \in \partial^{w} \Phi_{2}(u)$. Hence, the result follows.
Note 4.2. If we take an efficient solution of $\Phi_{2} \ominus_{g H} \Phi_{1}$ instead of a weak efficient solution, the additional condition $w\left(\Phi_{1}(y)\right) \geq w\left(\Phi_{2}(y)\right)$ or $w\left(\Phi_{1}(y)\right) \leq w\left(\Phi_{2}(y)\right)$ for all y becomes essential for Theorem 4.2 to hold. For instance, consider the IVFs $\Phi_{1}:[-1,1] \rightarrow I(\mathbb{R})$ and $\Phi_{2}:[-1,1] \rightarrow I(\mathbb{R})$ which are defined by

$$
\Phi_{1}(y)=\left\{\begin{array}{ll}
{\left[y^{3}, y\right],} & \text { if } 0 \leq y \leq 1 \\
{[4 y, y],} & \text { if }-1 \leq y<0
\end{array} \text { and } \Phi_{2}(y)= \begin{cases}{\left[y^{3}, 5 y\right],} & \text { if } 0 \leq y \leq 1 \\
{[3 y, 2 y],} & \text { if }-1 \leq y<0,\end{cases}\right.
$$

respectively. Now, according to Theorem 4.2,

$$
\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y)= \begin{cases}{[0,4 y],} & \text { if } 0 \leq y \leq 1 \\ {[y,-y],} & \text { if }-1 \leq y<0\end{cases}
$$

obtains an efficient solution at 0 because $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(0) \preceq\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y)$ for all $y \in[0,1]$ and $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(0)$ is not comparable with the values $\left(\Phi_{2} \ominus_{g H} \Phi_{1}\right)(y)$ for all $y \in[-1,0]$. It is not difficult to check that

$$
\begin{aligned}
\partial^{w} \Phi_{1}(0) & =\left\{\left(\boldsymbol{K}_{1}^{w}, c_{1}\right):[1,4] \preceq\left(\boldsymbol{K}_{1}^{w} \oplus c_{1}\right), \boldsymbol{K}_{1}^{w} \ominus_{g H} c_{1} \preceq[0,1]\right\} \\
\text { and } \partial^{w} \Phi_{2}(0) & =\left\{\left(\boldsymbol{K}_{2}^{w}, c_{2}\right):[2,3] \preceq \boldsymbol{K}_{2}^{w} \oplus c_{2}, \boldsymbol{K}_{2}^{w} \ominus_{g H} c_{2} \preceq[0,5]\right\} .
\end{aligned}
$$

Here, we see that $\partial^{w} \Phi_{1}(0)$ and $\partial^{w} \Phi_{2}(0)$ are not comparable and at the same time, and we notice that $w\left(\Phi_{2}(y)\right) \geq w\left(\Phi_{1}(y)\right)$ on $[0,1]$ and $w\left(\Phi_{1}(y)\right) \geq w\left(\Phi_{2}(y)\right)$ on $[-1,0]$.

Remark 4.1. In Theorem 4.2, inclusion (4.4) is a necessary but not sufficient condition for weak efficient point of $\Phi_{2} \ominus_{g H} \Phi_{1}$. For instance, consider the IVFs $\Phi_{1}:[-1,1] \rightarrow I(\mathbb{R})$ and $\Phi_{2}:[-1,1] \rightarrow$ $I(\mathbb{R})$ that are defined by

$$
\Phi_{1}(y)=\left\{\begin{array}{ll}
{\left[y^{3}, y\right],} & \text { if } 0 \leq y \leq 1 \\
{[3 y, 1.5 y],} & \text { if }-1 \leq y<0
\end{array} \text { and } \Phi_{2}(y)= \begin{cases}{\left[y^{3}+y^{2}, 2 y^{2}+y\right],} & \text { if } 0 \leq y \leq 1 \\
{[3 y, 2 y],} & \text { if }-1 \leq y<0 .\end{cases}\right.
$$

We notice that $w\left(\Phi_{2}(y)\right) \geq w\left(\Phi_{1}(y)\right)$ on $[0,1]$ and $w\left(\Phi_{2}(y)\right) \leq w\left(\Phi_{1}(y)\right)$ on $[-1,0]$. Note that

$$
\begin{aligned}
\partial^{w} \Phi_{1}(0) & =\left\{\left(\boldsymbol{K}_{1}^{w}, c_{1}\right):[1.5,3] \preceq \boldsymbol{K}_{1}^{w} \oplus c_{1}, \boldsymbol{K}_{1}^{w} \ominus_{g H} c_{1} \preceq[0,1]\right\} \\
\text { and } \partial^{w} \Phi_{2}(0) & =\left\{\left(\boldsymbol{K}_{2}^{w}, c_{2}\right):[2,3] \preceq \boldsymbol{K}_{2}^{w} \oplus c_{2}, \boldsymbol{K}_{2}^{w} \ominus_{g H} c_{2} \preceq[0,1]\right\} .
\end{aligned}
$$

Hence, $\partial^{w} \Phi_{1}(0) \subset \partial^{w} \Phi_{2}(0)$ but 0 is not a weak efficient point of $\Phi_{2} \ominus_{g H} \Phi_{1}$ on $[-1,1]$.
Next, we study a relation between the augmented normal cone and $g H$-weak subdifferential. So, let us define the augmented normal cone to $\mathscr{Y}$ as below.

Definition 4.1. (Augmented normal cone). An augmented normal cone to $\mathscr{Y}$ at $u$ is

$$
\mathscr{N}_{\mathscr{Y}}^{c}(u)=\left\{(\widehat{\boldsymbol{G}}, c) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}: \widehat{\boldsymbol{G}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \boldsymbol{0} \forall y \in \mathscr{Y}\right\} .
$$

Theorem 4.3. (Optimality condition via augmented normal cone). An IVF $\Psi: \mathscr{Y} \rightarrow I(\mathbb{R})$ attains weak efficient solution at $u$ if and only if $(\mathbf{0}, 0) \in \partial^{w} \Psi(u) \oplus \mathscr{N}_{\mathscr{O}}^{c}(u)$, where $(\mathbf{0}, 0)$ denotes the zero of $I(\mathbb{R}) \times \mathbb{R}_{+}$.

Proof. Since $u$ is a weak efficient point of $\Psi$ on $\mathscr{Y}$,

$$
\begin{aligned}
& \Psi(u) \preceq \Psi(y) \forall y \in \mathscr{Y} \\
\Longrightarrow & \mathbf{0} \preceq \Psi(y) \ominus_{g H} \Psi(u) \forall y \in \mathscr{Y} \text { by Lemma 2.1(ii) of [13] } \\
\Longrightarrow & (\mathbf{0}, 0) \in \partial^{w} \Psi(u) .
\end{aligned}
$$

Let $\delta_{\mathscr{Y}}: \mathscr{Y} \rightarrow I(\mathbb{R})$ be an indicator function, defined by $\delta_{\mathscr{Y}}(y)=\left\{\begin{array}{ll}\mathbf{0}, & \text { for } y \in \mathscr{Y} \\ \infty, & \text { for } y \notin \mathscr{Y}\end{array}\right.$. Since

$$
\left(\Psi \oplus \delta_{\mathscr{Y}}\right)(y)= \begin{cases}\Psi(y) & \text { if } y \in \mathscr{Y} \\ \infty & \text { if } y \notin \mathscr{Y}\end{cases}
$$

$(\mathbf{0}, 0) \in \partial^{w} \Psi(u)=\partial^{w}\left(\Psi \oplus \delta_{\mathscr{Y}}\right)(u)$. It needs to show that $\partial^{w}\left(\Psi \oplus \delta_{\mathscr{Y}}\right)(u) \subset \partial^{w} \Psi(u) \oplus \mathscr{N}_{\mathscr{Y}}^{c}(u)$. To prove this, let $\widehat{\mathbf{G}^{w}} \in \partial^{w}\left(\Psi_{1} \oplus \boldsymbol{\delta}_{\mathscr{Y}}\right)(u)$. Then,

$$
\begin{aligned}
& {\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq\left(\Psi \oplus \boldsymbol{\delta}_{\mathscr{Y}}\right)(y) \ominus_{g H}\left(\Psi \oplus \boldsymbol{\delta}_{\mathscr{Y}}\right)(u) \\
\Longrightarrow & {\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq\left(\Psi(y) \oplus \boldsymbol{\delta}_{\mathscr{Y}}(y)\right) \ominus_{g H}\left(\Psi(u) \oplus \boldsymbol{\delta}_{\mathscr{Y}}(u)\right) \\
\Longrightarrow & {\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi(y) \ominus_{g H} \Psi(u),
\end{aligned}
$$

which implies $\widehat{\mathbf{G}^{w}} \in \partial^{w} \Psi(u) \subset \partial^{w} \Psi(u) \oplus \partial^{w} \delta_{\mathscr{Y}}(u)$, where $\{(\mathbf{0}, 0)\} \subset \partial^{w} \delta_{\mathscr{Y}}(u)$. Hence, $\widehat{\mathbf{G}^{w}} \in$ $\partial^{w} \Psi(u) \oplus \partial^{w} \delta_{\mathscr{Y}}(u)=\partial^{w} \Psi(u) \oplus \mathscr{N}_{\mathscr{Y}}^{c}(u)$.

To show the converse part, let $(\mathbf{0}, 0) \in \partial^{w} \Psi(u) \oplus \mathscr{S}_{\mathscr{Y}}^{c}(u)=\partial^{w}\left(\Psi(u) \oplus \delta_{\mathscr{Y}}(u)\right)$. Now, for any $y \in \mathscr{Y}$, we have

$$
\begin{aligned}
& \quad \mathbf{0} \odot(y-u) \ominus_{g H} 0\|y-u\| \preceq\left(\Psi(y) \oplus \boldsymbol{\delta}_{\mathscr{Y}}(y)\right) \ominus_{g H}\left(\Psi(u) \oplus \boldsymbol{\delta}_{\mathscr{Y}}(u)\right) \\
& \text { or, } \mathbf{0} \preceq \Psi(y) \ominus_{g H} \Psi(u) \\
& \text { or, } \Psi(u) \preceq \Psi(y) \text { by Lemma 2.1(ii) of [13]. }
\end{aligned}
$$

So, $u$ is a weak efficient solution of $\Psi$.

## 5. $g H$-Directional Derivative and $g H$-Weak Subdifferential for IVF

In the section, we investigate a relation between $g H$-Directional derivative and $g H$-weak subdifferential for IVFs based on supremum relation, which facilitates the analysis on the existence of efficient solution for nonconvex IVFs. With the help of the proposed relation, we introduce $\mathscr{W}-g H$ weak subgradient method to obtain weak efficient solution of an unconstrained IOP in the coming section.

Lemma 5.1. Let $\mathscr{Y} \subseteq \mathbb{R}^{n}$ be starshaped at $u \in \mathscr{Y}$. Let, at $u$, the $I V F \Phi: \mathscr{Y} \rightarrow I(\mathbb{R})$ has $g H$ Directional derivative in every direction $y-u$ for any $y \in \mathscr{Y}$, and

$$
\begin{equation*}
\Phi_{\mathscr{D}}(u ; y-u) \preceq \Phi(y) \ominus_{g H} \Phi(u) \forall y \in \mathscr{Y} . \tag{5.1}
\end{equation*}
$$

Then, $u$ is a weak efficient point of $\Phi$ over $\mathscr{Y}$ if and only if

$$
\begin{equation*}
\mathbf{0} \preceq \Phi_{\mathscr{D}}(u ; y-u) \forall y \in \mathscr{Y} . \tag{5.2}
\end{equation*}
$$

Proof. Let us assume that condition (5.2) is satisfied. Thus, by using (5.1), we have $\mathbf{0} \preceq \Phi(y) \ominus_{g H}$ $\Phi(u)$ for all $y \in \mathscr{Y}$, which implies that $u$ is a weak efficient point of $\Phi$ over $\mathscr{Y}$. It is given that for all $y \in \mathscr{Y}, \Phi_{\mathscr{D}}(u ; y-u)$ exists. Then,

$$
\begin{equation*}
\Phi_{\mathscr{D}}(u ; y-u)=\lim _{\beta \rightarrow 0} \frac{1}{\beta} \odot\left[\Phi\left(u+\beta(y-u) \ominus_{g H} \Phi(u)\right)\right] . \tag{5.3}
\end{equation*}
$$

As $u$ is a weak efficient point of $\Phi$ on $\mathscr{Y}$, we have $\mathbf{0} \preceq \Phi_{\mathscr{D}}(u ; y-u)$.
Theorem 5.1. Let all the suppositions of Lemma 5.1 be satisfied. In addition, let at $u$, the $g H$ Directional derivative $\Phi_{\mathscr{D}}(u, \cdot)$ be gH-lower semicontinuous on $\mathscr{K}=$ cone $(\mathscr{Y}-u)$ and

$$
\begin{equation*}
-\infty \prec \inf \left\{\Phi_{\mathscr{D}}(u ; h): h \in \mathscr{K} \cap \mathscr{U}\right\}, \tag{5.4}
\end{equation*}
$$

where $\mathscr{U}=\left\{v \in \mathbb{R}^{n}:\|v\|=1\right\}$. Then, $\Phi$ is $g H$-weak subdifferentiable at $u$ on $\mathscr{Y}$, that is $\partial_{\mathscr{Y}}^{w} \Phi(u)$ is nonempty and

$$
\begin{equation*}
\Phi_{\mathscr{D}}(u ; h)=\sup \left\{{\widehat{\boldsymbol{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\boldsymbol{G}^{w}}, c\right) \in \partial_{\mathscr{Y}}^{w} \Phi(u), c>0\right\}, \forall h \in \mathscr{K} . \tag{5.5}
\end{equation*}
$$

Proof. For convenience, we suppose $\Psi(h)=\Phi_{\mathscr{D}}(u ; h) \forall h \in \mathscr{K}$. Clearly, for $\alpha \geq 0$,

$$
\begin{aligned}
& \Psi(\alpha h)=\Phi_{\mathscr{D}}(u ; \alpha h)=\lim _{\beta \rightarrow 0} \frac{1}{\beta} \odot\left[\Phi(u+(\beta \alpha) h) \ominus_{g H} \Phi(u)\right] \\
& =\alpha \odot \lim _{\beta \rightarrow 0} \frac{1}{\beta \alpha} \odot\left[\Phi(u+(\beta \alpha) h) \ominus_{g H} \Phi(u)\right]=\alpha \odot \Phi_{\mathscr{D}}(u ; h)=\alpha \odot \Psi(h) .
\end{aligned}
$$

So, $\Psi$ is a nonnegative homogeneous IVF and $\Psi(0)=\mathbf{0}$. By the hypothesis, $\Psi$ is bounded below on $\mathscr{K} \cap \mathscr{U}$. Due to this fact, for any given $\widehat{\mathbf{G}^{w}} \in I(\mathbb{R})^{n}$, the relation

$$
\begin{equation*}
{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\| \preceq \Psi(h) \ominus_{g H} \Psi(0) \forall h \in \mathscr{K} \cap \mathscr{U} \tag{5.6}
\end{equation*}
$$

holds for sufficiently large $c$. Inequality (5.6) shows that $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0)$, which means $\Psi$ is $g H$-weak subdifferentiable on $\mathscr{Y}-u$ at 0 . So, $\partial_{\mathscr{Y}-u}^{w} \Psi(0)$ is nonempty. Now it remains to show that

$$
\begin{equation*}
\partial_{\mathscr{Y}}^{W} \Phi(\bar{y})=\partial_{\mathscr{Y}-u}^{w} \Psi(0) . \tag{5.7}
\end{equation*}
$$

Let $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0)$. Thus, from (5.1) and (5.6), it implies that (3.1) is fulfilled, i.e., $\left(\widehat{\mathbf{G}^{w}}, c\right) \in$ $\partial_{\mathscr{Y}}^{w} \Phi(u)$. To prove the reverse inclusion of equality (5.7), let us take $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}}^{w} \Phi(u)$. Then, for any fixed $y \in \mathscr{Y}$, we have

$$
\begin{align*}
\Psi(y-u)= & \Phi_{\mathscr{D}}(u ; y-u) \\
= & \lim _{\beta \rightarrow 0+} \frac{1}{\beta} \odot\left[\Phi(u+\beta(y-u)) \ominus_{g H} \Phi(u)\right] \\
= & \lim _{\beta \rightarrow 0+} \frac{1}{\beta} \odot[\min \{\underline{\phi}(u+\beta(y-u))-\underline{\phi}(u), \bar{\phi}(u+\beta(y-u))-\bar{\phi}(u)\}, \\
& \max \{\underline{\phi}(u+\beta(y-u))-\underline{\phi}(u), \bar{\phi}(u+\beta(y-u))-\bar{\phi}(u)\}] . \tag{5.8}
\end{align*}
$$

Let the first $m$ number of components of $(y-u)$ be nonnegative and the rest $n-m$ number of components of $(y-u)$ be negative. Then, by the definition of weak subgradient on $\underline{\phi}$ and $\bar{\phi}$, we have $c_{1}>0$
and $c_{2}>0$ such that

$$
\begin{align*}
& \quad \sum_{i=1}^{m} \beta\left(y_{i}-u_{i}\right) \underline{g}_{i}+\sum_{j=m+1}^{n} \beta\left(y_{j}-u_{j}\right) \underline{g}_{j}-\lambda c_{1}\|y-u\| \leq \underline{\phi}(u+\beta(y-u))-\underline{\phi}(u)  \tag{5.9}\\
& \text { and } \sum_{i=1}^{m} \beta\left(y_{i}-u_{i}\right) \bar{g}_{i}+\sum_{j=m+1}^{n} \beta\left(y_{j}-u_{j}\right) \bar{g}_{j}-\lambda c_{2}\|y-u\| \leq \bar{\phi}(u+\beta(y-u))-\bar{\phi}(u) . \tag{5.10}
\end{align*}
$$

With the help of (5.9) and (5.10), (5.8) breaks into two cases.

- Case 1.

$$
\begin{align*}
& \lim _{\beta \rightarrow 0+} \frac{1}{\beta} \odot[\underline{\phi}(u+\beta(y-u))-\underline{\phi}(u), \bar{\phi}(u+\beta(y-u))-\bar{\phi}(u)]=\Psi(y-u) \\
\Longrightarrow & \lim _{\beta \rightarrow 0+} \frac{1}{\beta} \odot\left[\sum_{i=1}^{m} \beta\left(y_{i}-u_{i}\right) \underline{g}_{i}+\sum_{j=m+1}^{n} \beta\left(y_{j}-u_{j}\right) \underline{g}_{j}-\beta c_{1}\|y-u\|,\right. \\
& \left.\sum_{i=1}^{m} \beta\left(y_{i}-u_{i}\right) \bar{g}_{i}+\sum_{j=m+1}^{n} \beta\left(y_{j}-u_{j}\right) \bar{g}_{j}-\beta c_{2}\|y-u\|\right] \preceq \Psi(y-u) \\
\Longrightarrow & \bigoplus_{i=1}^{m}\left[g_{i}, \bar{g}_{i}\right] \odot\left(y_{i}-u_{i}\right) \bigoplus_{j=m+1}^{n}\left[\bar{g}_{j}, \underline{g}_{j}\right] \odot\left(y_{j}-u_{j}\right) \ominus_{g H} \max \left\{c_{1}, c_{2}\right\}\|y-u\| \\
\preceq & \Psi(y-u) . \tag{5.11}
\end{align*}
$$

- Case 2.

$$
\begin{align*}
& \lim _{\beta \rightarrow 0^{+}} \frac{1}{\beta} \odot[\underline{\phi}(u+\beta(y-u))-\underline{\phi}(u), \bar{\phi}(u+\beta(y-u))-\bar{\phi}(u)]=\Psi(y-u) \\
\Longrightarrow & \bigoplus_{i=1}^{m}\left[\underline{g}_{i}, \bar{g}_{i}\right] \odot\left(y_{i}-u_{i}\right) \bigoplus_{j=m+1}^{n}\left[\bar{g}_{j}, \underline{g}_{j}\right] \odot\left(y_{j}-u_{j}\right) \ominus_{g H} \max \left\{c_{1}, c_{2}\right\}\|y-u\| \\
\preceq & \Psi(y-u) . \tag{5.12}
\end{align*}
$$

Combining (5.11) and (5.12), we obtain

$$
\bigoplus_{i=1}^{m}\left(y_{i}-u_{i}\right)^{\top} \odot \mathbf{G}_{i}^{w} \bigoplus_{j=m+1}^{n}\left(y_{j}-u_{j}\right)^{\top} \odot \mathbf{G}_{j}^{w} \ominus_{g H} c\|y-u\| \preceq \Psi(y-u), \text { where } c=\max \left\{c_{1}, c_{2}\right\}
$$

which implies ${\widehat{\mathbf{G}^{w}}}^{\top} \odot(y-u) \ominus_{g H} c\|y-u\| \preceq \Psi(y-u)$. This leads to (5.6); that is, $\left(\widehat{\mathbf{G}^{w}}, c\right) \in$ $\partial_{\mathscr{Y}-u}^{w} \Psi(0)$.

Now we prove that

$$
\begin{equation*}
\Psi(h)=\sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0), c \geq 0\right\} \forall h \in \mathscr{K} . \tag{5.13}
\end{equation*}
$$

Supposing $h=0$, equality in (5.13) is obvious. Hence we take care of the case $h \neq 0$. Let $h \in \mathscr{K}$ be a point on the boundary of the unit sphere, i.e., $\|h\|=1$; that is, $h \in \mathscr{K} \cap \mathscr{U}$. Let $\varepsilon \geq 0$ be arbitrary. It suffices now to prove that

$$
\begin{equation*}
\left(\Psi(h) \ominus_{g H} \boldsymbol{\varepsilon} \oplus c\right) \odot h^{T} z \ominus_{g H} c\|z\| \preceq \Psi(z) \forall z \in \mathscr{K} \cap \mathscr{U} \tag{5.14}
\end{equation*}
$$

is valid for sufficiently large numbers $c$. Now, we proceed by the contrary that there exist two sequences $\left\{c_{n}\right\}$ and $\left\{z_{n}\right\}$ with $c_{n} \rightarrow \infty$ and $z_{n} \in \mathscr{K} \cap \mathscr{U}$ such that

$$
\begin{align*}
\Psi\left(z_{n}\right) & \preceq\left(\Psi(h) \ominus_{g H} \varepsilon \oplus c_{n}\right) \odot h^{T} z_{n} \ominus_{g H} c_{n}\left\|z_{n}\right\| \text { for all } n=1,2, \ldots \\
& =\left(\Psi(h) \ominus_{g H} \varepsilon\right) \odot h^{T} z_{n} \oplus c_{n} \odot\left(h^{T} z_{n}-1\right) \text { for all } n=1,2, \ldots . \tag{5.15}
\end{align*}
$$

Since $\mathscr{K} \cap \mathscr{U}$ is closed and bounded, $\left\{z_{n}\right\}$ has a convergent subsequence. Without loss of generality, we presume that $z_{n}$ converges to $z \in \mathscr{K} \cap \mathscr{U}$. Let $z \neq h$ and $\|h\|=1$. Then $h^{\top} z \leq h^{\top} h=\|h\|^{2}=1$ follows. Thus, letting $c_{n}$ approaches to $\infty$ in (5.15), we have $\Psi(z)=-\infty$, which contradicts (5.4). Thus, $z=h$ which ensures that $\|h\|^{2}=1$. By $g H$-lower semicontinuity of $g H$-Directional derivative $\Phi_{\mathscr{D}}(u ; h)$, we have

$$
\begin{equation*}
\Psi(h) \preceq \liminf _{n \rightarrow \infty} \Psi\left(z_{n}\right) \preceq\left(\Psi(h) \ominus_{g H} \varepsilon\right)\|h\|^{2}=\Psi(h) \ominus_{g H} \varepsilon, \tag{5.16}
\end{equation*}
$$

which leads to a contradiction. Note that the inequality (5.14) is true for some $c \geq 0$. Denote $\widehat{\mathbf{G}^{\boldsymbol{w}}}=$ $\left(\Psi(h) \ominus_{g H} \varepsilon \oplus c\right) \odot h^{\top}$. The inequality (5.14) then gives $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}}^{w}-u(0)$. It is obvious that

$$
\left(\Psi(h) \ominus_{g H} \boldsymbol{\varepsilon} \oplus c\right) \odot h^{\top} h \ominus_{g H} c\|h\| \preceq \sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0), c \geq 0\right\} .
$$

As for $\|h\|=1$, we have

$$
\Psi(h) \ominus_{g H} \varepsilon \preceq \sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0), c \geq 0\right\} .
$$

Since this inequality holds for every $\varepsilon>0$, we deduce that

$$
\begin{equation*}
\Psi(h) \preceq \sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0), c \geq 0\right\} . \tag{5.17}
\end{equation*}
$$

In the other words, ${\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\| \preceq \Psi(h)$ for all $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0)$, which yields

$$
\begin{equation*}
\Psi(h)=\sup \left\{{\widehat{\mathbf{G}^{w}}}^{\top} \odot h \ominus_{g H} c\|h\|:\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{\mathscr{Y}-u}^{w} \Psi(0), c \geq 0\right\} . \tag{5.18}
\end{equation*}
$$

Thus, (5.13) is true. Then, (5.6) is followed by (5.7) and (5.14), which completes the proof of the theorem.

## 6. $\mathscr{W}$-g $H$-Weak Subgradient Method

In this section, we illustrate a $\mathscr{W}-g H$-weak subgradient method to obtain a weak efficient solution of the following unconstrained IOP:

$$
\begin{equation*}
\min _{y \in \mathbb{R}^{n}} \Phi(y) \tag{6.1}
\end{equation*}
$$

where $\Phi: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ is a nonsmooth nonconvex $g H$-Lipschitz continuous IVF. In order to derive the method, we define the weak efficient direction of an IVF.

Definition 6.1. (Weak efficient-direction). A direction $d \in \mathbb{R}^{n}$ is said to be a weak efficient-direction of an IVF $\Phi: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ at $u \in \mathbb{R}^{n}$ if there exists a $\delta>0$ such that
(i) $\Phi(u+\lambda d) \preceq \Phi(u)$ for all $\lambda \in(0, \delta)$, and
(ii) there also exists a point $y^{\prime}=u+\alpha d$ with $\alpha \in(0, \delta)$ and a positive real number $\delta^{\prime} \leq \alpha$ such that $\Phi\left(y^{\prime}\right) \preceq \Phi\left(y^{\prime}+\lambda d\right)$ for all $\lambda \in\left(-\delta^{\prime}, \delta^{\prime}\right)$. The point $y^{\prime}$ is known as a weak efficient solution of $\Phi$ in the direction $d$.

In the proposed method, similar to the existing result for $g H$-differentiable IVF [14, Theorem 5.4], we use the weak efficient direction $-\mathscr{W}\left(\widehat{\mathbf{G}^{w}}\right)$, where $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u)$ at any point $u \in \mathbb{R}^{n}$ and the mapping $\mathscr{W}: I(\mathbb{R})^{n} \rightarrow \mathbb{R}^{n}$ is defined by

$$
\mathscr{W}\left(\mathbf{B}_{1}, \mathbf{B}_{2}, \ldots, \mathbf{B}_{n}\right)=\left(w_{1} \underline{b}_{1}+w_{2} \bar{b}_{1}, w_{1} \underline{b}_{2}+w_{2} \bar{b}_{2}, \ldots, w_{1} \underline{b}_{n}+w_{2} \bar{b}_{n}\right)^{\top}
$$

for two given numbers $w_{1}, w_{2} \in[0,1]$ with $w_{1}+w_{2}=1$ and $\mathbf{B}_{j}=\left[\underline{b}_{j}, \bar{b}_{j}\right] \in I(\mathbb{R})$. To identify the weak efficient solution, we employ the $\mathscr{W}$-map. Applying $\mathscr{W}$-map, the weak efficient solution of IOP (6.1) can be found by solving the following problem:

$$
\begin{equation*}
\min _{y \in \mathbb{R}^{n}} w_{1} \underline{\phi}(y)+w_{2} \bar{\phi}(y) . \tag{6.2}
\end{equation*}
$$

The reason is as follows:
Clearly, $\left(w_{1} \underline{g}^{w}+w_{2} \bar{g}^{w}, c\right) \in \partial^{w}\left(w_{1} \underline{\phi}(y)+w_{2} \bar{\phi}(y)\right)$ for any $y \in \mathbb{R}^{n}$, where $\left(\underline{g} \underline{g}^{w}, c\right) \in \partial^{w} \underline{\phi}(y)$ and $\left(\bar{g}^{w}, c\right) \in \partial^{w} \bar{\phi}(\bar{y})$. It can be noted that $w_{1} \underline{g}^{w}+w_{2} \bar{g}^{w} \in\left[\underline{g}^{w}, \bar{g}^{w}\right]$, which implies $\left(w_{1} \underline{g}^{w}+w_{2} \bar{g}^{w}, c\right) \in$ $\partial^{w} \Phi(y)$. To be certain, we will prove a theorem to show that $\left(w_{1} \underline{g}^{w}+w_{2} \bar{g}^{w}, c\right) \in \partial^{w} \Phi(y)$ is correct.

Since $\Phi$ is $g H$-Lipschitz continuous IVF with Lipschitz constant $L, \Phi$ is $g H$-lower Lipschitz at any $u \in \mathbb{R}^{n}$ as well. Then, the $g H$-weak subdifferential set of $\Phi, \partial^{w} \Phi(u)$ is nonempty. Along with this, we also assume that $L$ be a positive real number with

$$
\partial_{L}^{w} \Phi(u)=\left\{\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial^{w} \Phi(u): c \leq L, j \in \mathbb{N}\right\} \neq \emptyset,
$$

is clearly found to be compact set and $\left\|\widehat{\mathbf{G}^{w}}\right\| \leq l+L$ for every $\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{L}^{w} \Phi(u)$. This compactness of $\partial_{L}^{w} \Phi(u)$ will be used to produce an algorithm for the computation of weak efficient direction using the computation of $g H$-weak subgradients at any given point. To compute an approximate $g H$-weak subgradients, we will use the relation between $g H$-Direction derivative and $g H$-weak subdifferential (see Theorem 5.1) and consider all assumptions that given in Lemma 5.1 and Theorem 5.1.

To describe the algorithm for computing $g H$-weak subgradient, we first consider the following set and sequence for using the relation (5.5):
$Q=\left\{\vartheta=\left(\vartheta_{1}, \vartheta_{2}, \ldots, \vartheta_{n}\right) \in \mathbb{R}^{n}:\left|\vartheta_{j}\right|=1, j=1,2, \ldots, n\right\}$. For $\vartheta \in Q$, consider the sequence of $n$ vectors $\vartheta^{j}=\vartheta^{j}(\mu), j=1,2, \ldots, n$ with $\mu \in(0,1]$, where $\vartheta^{j}=\left(\mu \vartheta_{1}, \mu^{2} \vartheta_{2}, \ldots, \mu^{j} \vartheta_{j}, 0, \ldots, 0\right)$.
From the compactness of $g H$-weak subdifferential set $\partial_{L}^{w} \Phi(u)$ and the relation (5.5), there exists a gH-weak subgradients $\left(\widehat{\overline{\mathbf{G}}^{w}}, \bar{c}\right)$ such that

$$
\Phi_{\mathscr{D}}\left(u ; \vartheta^{j}(\mu)\right)={\widehat{\overline{\mathbf{G}}^{w}}}^{\top} \odot \vartheta^{j}(\mu) \ominus_{g H} \bar{c}\left\|\vartheta^{j}(\mu)\right\| .
$$

Then, the set $\mathscr{G}_{c}=\left\{\widehat{\mathbf{G}^{w}} \in I(\mathbb{R})^{n}:\left(\widehat{\mathbf{G}^{w}}, \bar{c}\right) \in \partial_{L}^{w} \Phi(u)\right\}$ is nonempty. Suppose that there is a set $\mathscr{A} \subset \mathscr{G}_{c}$ such that

$$
\Phi_{\mathscr{D}}\left(u ; \vartheta^{j}(\mu)\right)=\sup \left\{{\widehat{\overline{\mathbf{G}}^{w}}}^{\top} \odot \vartheta^{j}(\mu) \ominus_{g H} \bar{c}\left\|\vartheta^{j}(\mu)\right\|: \widehat{\mathbf{G}^{w}} \in \mathscr{G}_{c}\right\}
$$

Next, we reconstruct a few following auxiliary sets similar to existing construction for weak subgradients (see [9] Remark 3.1): For any $\vartheta \in Q$ and $\mu>0, \mathscr{R}_{0}(\vartheta)=\mathscr{A}$,

$$
\begin{aligned}
\mathscr{R}_{j}(\vartheta) & =\left\{\widehat{\mathbf{M}^{w}}=\left(\mathbf{M}_{1}^{w}, \mathbf{M}_{2}^{w}, \ldots, \mathbf{M}_{n}^{w}\right) \in \mathscr{A}: \vartheta_{j} \odot \mathbf{M}_{j}^{w}=\sup \left\{\vartheta_{j} \odot \mathbf{G}_{j}^{w}: \widehat{\mathbf{G}^{w}}\right.\right. \\
& =\left(\mathbf{G}_{1}^{w}, \mathbf{G}_{2}^{w}, \ldots, \mathbf{G}_{n}^{w}\right) \in \mathscr{R}_{j-1},
\end{aligned}
$$

and

$$
\begin{aligned}
\mathscr{R}\left(u, \vartheta^{j}(\mu)\right) & =\left\{\widehat{\mathbf{M}^{w}} \in \mathscr{A}: \vartheta^{j}(\mu) \odot \widehat{\mathbf{M}}\right. \\
& =\sup \left\{\vartheta^{j}(\mu) \odot \widehat{\mathbf{G}^{w}}: \widehat{\mathbf{G}^{w}} \in \mathscr{A}\right\} \text { for all } j=1,2, \ldots, n .
\end{aligned}
$$

By using this construction, we have that, for every $\vartheta^{j}(\mu), j=1,2, \ldots, n$, there is an element $\widehat{\overline{\mathbf{G}}^{W}} \in$ $\mathscr{R}\left(u, \vartheta^{j}(\mu)\right)$ such that

$$
\begin{equation*}
\Phi_{\mathscr{D}}\left(u ; \vartheta^{j}(\mu)\right)={\widehat{\overline{\mathbf{G}}^{w}}}^{\top} \odot \vartheta^{j}(\mu) \ominus_{g H} \bar{c}\left\|\vartheta^{j}(\mu)\right\| . \tag{6.3}
\end{equation*}
$$

In the sequel, like to the existing definition in p .1527 of [9], we are ready to define a vector $\widehat{\mathbf{G}^{\boldsymbol{w}}}(\vartheta, \mu, \lambda) \in I(\mathbb{R})^{n}$ and a set $\mathscr{U}(\vartheta, \mu)$ as follows: For any given $\vartheta \in Q, \lambda>0$ and $\mu>0$
, consider the following points: $y_{0}=u, y_{j}=y_{0}+\lambda \vartheta^{j}(\mu), j=1,2, \ldots, n$. Then, clearly $y_{j}=$ $y_{j-1}+\left(0, \ldots, 0, \lambda \mu^{j} \vartheta_{j}, 0, \ldots\right)$ for every $j=1,2, \ldots, n$. Let $\widehat{\mathbf{G}^{w}}=\widehat{\mathbf{G}^{w}}(\vartheta, \mu, \lambda) \in I(\mathbb{R})^{n}$ be a vector with $n$ coordinates:

$$
\widehat{\mathbf{G}_{j}^{\omega}}(\vartheta, \mu, \lambda)=\frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\Phi\left(y_{j}\right) \ominus_{g H} \Phi\left(y_{j-1}\right)\right\}+\frac{\bar{c}}{\vartheta_{j}}, j=1,2, \ldots, n .
$$

For any fixed $\vartheta \in Q$ and $\mu>0$, we define the set:

$$
\mathscr{U}(\vartheta, \mu)=\left\{\left(\widehat{\mathbf{M}^{w}}, \bar{c}\right) \in I(\mathbb{R})^{n} \times \mathbb{R}_{+}: \exists\left(\lambda_{k} \rightarrow+0, k \rightarrow+\infty\right), \widehat{\mathbf{M}^{w}}=\lim _{k \rightarrow \infty} \widehat{\mathbf{G}^{w}}\left(\vartheta, \mu, \lambda_{k}\right)\right\}
$$

We claim that $\left(\widehat{\mathbf{G}_{j}^{w}}, \bar{c}\right)$ is an approximate $g H$-weak subgradient of $\Phi$ at $u$, which need to satisfy the relation (6.3). To show $\left(\widehat{\mathbf{G}_{j}^{w}}, \bar{c}\right)$ certainly satisfies the relation (6.3), it is sufficient to prove Theorem 6.1. This theorem will also show that $\left(\mathscr{W}\left(\widehat{\mathbf{G}_{j}^{w}}\right), \bar{c}\right)$ is also an approximate $g H$-weak subgradient of $\Phi$ at $u$. So, it indicates that $-\mathscr{W}\left(\widehat{\mathbf{G}_{j}^{W}}\right)$ is an appropriate choice for weak efficient direction in the proposed $\mathscr{W}$-gH-weak subgradient method. Therefore, this method easily reduces to the conventional weak subgradient method of optimization problems in [9].
For establishing Theorem 6.1, we need the following two lemmas.
Lemma 6.1. For any $\vartheta \in Q, \mathscr{R}_{n}(\vartheta)$ is singleton set.
Proof. The proof is analogous to the proof of Proposition 3.1 for real-valued functions of real variables (see p. 1525 of [9]).

Lemma 6.2. There exist $\mu_{0}>0$ and $\widehat{\boldsymbol{M}^{w}} \in \mathscr{R}_{j}(\vartheta)$ such that

$$
\Phi_{\mathscr{D}}\left(u, \vartheta^{j}(\mu)\right)=\Phi_{\mathscr{D}}\left(u, \vartheta^{j-1}(\mu)\right) \oplus \mu^{j} \vartheta_{j} \odot \widehat{\boldsymbol{M}^{w}} \ominus_{g H} \bar{c} \mu^{j}
$$

for all $\mu \in\left(0, \mu_{0}\right]$ and for every $j=1,2, \ldots, n$.
Proof. The proof is analogous to the proof of Corollary 3.4 for real-valued functions of real-variables (see p. 1527 of [9]).

In order to show that $\left(\widehat{\mathbf{G}_{j}^{w}}, \bar{c}\right)$ is an approximate $g H$-weak subgradient of $\Phi$ at $u$, we establish a relationship between the sets $\mathscr{U}(\vartheta, \mu)$ and $\partial_{L}^{w} \Phi(u)$ via the following theorem.
Theorem 6.1. There exists $\mu_{0}>0$ such that $\mathscr{U}(\vartheta, \mu) \subseteq \partial_{L}^{w} \Phi(u)$ for all $\mu \in\left(0, \mu_{0}\right]$.
Proof. Let $\widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)=\left[\underline{g}_{j}^{w}(\vartheta, \mu, \lambda), \bar{g}_{j}^{w}(\vartheta, \mu, \lambda)\right]=\frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\Phi\left(y_{j}\right) \ominus_{g H} \Phi\left(y_{j-1}\right)\right\} \oplus \frac{\bar{c}}{\vartheta_{j}}$. It implies that

$$
\widehat{\mathbf{G}_{j}^{\hat{w}}}(\vartheta, \mu, \lambda) \subseteq \frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\left\{\Phi\left(y_{j}\right) \ominus_{g H} \Phi(u)\right\} \ominus_{g H}\left\{\Phi\left(y_{j-1}\right) \ominus_{g H} \Phi(u)\right\}\right\} .
$$

Since $\Phi_{\mathscr{D}}\left(u, \vartheta^{j}(\mu)\right)=\lim _{\lambda \rightarrow+0} \frac{1}{\lambda} \odot\left\{\Phi\left(y_{j}\right) \ominus_{g H} \Phi(u)\right\}$, we have

$$
\begin{aligned}
& \left.\widehat{\mathbf{G}_{j}^{w}} \vartheta, \mu, \lambda\right) \\
\subseteq & \frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\lambda \odot \Phi_{\mathscr{D}}\left(u, \vartheta^{j}(\mu)\right) \ominus_{g H} \lambda \odot \Phi_{\mathscr{D}}\left(u, \vartheta^{j-1}(\mu)\right) \oplus o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)\right\}+\frac{\bar{c}}{\vartheta_{j}},
\end{aligned}
$$

where $\lambda^{-1} o\left(\lambda, \vartheta^{i}\right) \rightarrow 0, \lambda \rightarrow+0, i=j-1, j$. Due to nonemptiness of $\mathscr{R}_{j}(\vartheta)$ for all $j=1,2, \ldots, n$, we let $\mathbf{M}=\left(\mathbf{M}_{1}, \mathbf{M}_{2}, \ldots, \mathbf{M}_{n}\right)=\left(\left[\underline{m}_{1}, \bar{m}_{1}\right],\left[\underline{m}_{2}, \bar{m}_{2}\right], \ldots,\left[\underline{m}_{n}, \bar{m}_{n}\right]\right) \in \mathscr{R}_{n}(\vartheta)$. By Lemma 6.1, $\mathbf{M}$ is unique element of $\mathscr{R}_{n}(\vartheta)$. From the definition $\mathscr{R}_{j}(\vartheta)$ for all $j=1,2, \ldots, n$, it is clear that $\mathscr{R}_{n}(\vartheta) \subseteq$
$\mathscr{R}_{j}(\vartheta)$ for all $j=1,2, \ldots, n$. Then, from this inclusion and Lemma 6.2, we have that there exist $\mu_{0}>0$ such that

$$
\begin{aligned}
\widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda) & \subseteq \frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\lambda \odot\left(\mu^{j} \vartheta_{j} \odot \widehat{\mathbf{M}_{j}^{w}} \ominus_{g H} \bar{c} \mu^{j}\right)+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)\right\}+\frac{\bar{c}}{\vartheta_{j}} \\
& =\widehat{\mathbf{M}_{j}^{w}} \ominus_{g H} \\
& =\widehat{\vartheta_{j}} \oplus \frac{o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta^{j}} \oplus \frac{\bar{c}}{\vartheta_{j}} \\
& \frac{o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta^{j}}
\end{aligned}
$$

for all $\mu \in\left(0, \mu_{0}\right]$. Then, for any $\mu \in\left(0, \mu_{0}\right]$, we have

$$
\lim _{\lambda \rightarrow+0} \widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda) \ominus_{g H} \widehat{\mathbf{M}_{j}^{\omega}} \subseteq\{\boldsymbol{0}\} \Longrightarrow \lim _{\lambda \rightarrow+0} \widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)=\widehat{\mathbf{M}_{j}^{w}} .
$$

Consequently, $\lim _{\lambda \rightarrow+0} \widehat{\mathbf{G}^{w}}(\vartheta, \mu, \lambda)=\widehat{\mathbf{M}^{w}} \in \mathscr{G}_{c}$. On the other hand,

$$
\begin{aligned}
& \mathscr{W}\left(\widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)\right)=w_{1} \underline{g}_{j}^{w}(\vartheta, \mu, \lambda)+w_{2} \bar{g}_{j}^{w}(\vartheta, \mu, \lambda) \\
= & \frac{\left(w_{1} \underline{\phi}\left(y^{j}\right)+w_{2} \bar{\phi}\left(y^{j}\right)\right)-\left(w_{1} \underline{\phi}\left(y^{j-1}\right)+w_{2} \bar{\phi}\left(y^{j-1}\right)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\left(w_{1}+w_{2}\right) \bar{c}}{\vartheta_{j}} \\
= & w_{1}\left\{\frac{\left(\underline{\phi}\left(y^{j}\right)-\underline{\phi}\left(y^{j-1}\right)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}}\right\}+w_{2}\left\{\frac{\left(\bar{\phi}\left(y^{j}\right)-\bar{\phi}\left(y^{j-1}\right)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}}\right\} \\
= & \frac{w_{1} \lambda\left\{\underline{\phi}_{\mathscr{D}}\left(\lambda, \vartheta^{j}(\mu)\right)-\underline{\phi}_{\mathscr{D}}\left(\lambda, \vartheta^{j-1}(\mu)\right)\right\}+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}} \\
& +\frac{w_{2} \lambda\left\{\bar{\phi}_{\mathscr{D}}\left(\lambda, \vartheta^{j}(\mu)\right)-\bar{\phi}_{\mathscr{D}}\left(\lambda, \vartheta^{j-1}(\mu)\right)\right\}+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}} \\
= & \frac{w_{1} \lambda\left\{\underline{m}_{j} \mu^{j} \vartheta_{j}-\bar{c} \mu^{j}\right\}+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}} \\
& +\frac{w_{2} \lambda\left\{\bar{m}_{j} \mu^{j} \vartheta_{j}-\bar{c} \mu^{j}\right\}+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}} \\
= & \frac{\lambda\left\{\left(w_{1} \underline{m}_{j}+w_{2} \bar{m}_{j}\right) \mu^{j} \vartheta_{j}-\bar{c} \mu^{j}\right\}+o\left(\lambda, \vartheta^{j}(\mu)\right)-o\left(\lambda, \vartheta^{j-1}(\mu)\right)}{\lambda \mu^{j} \vartheta_{j}}+\frac{\bar{c}}{\vartheta_{j}} .
\end{aligned}
$$

Similarly, $\lim _{\lambda \rightarrow+0} w_{1} \underline{g}_{j}^{w}(\vartheta, \mu, \lambda)+w_{2} \bar{g}_{j}^{w}(\vartheta, \mu, \lambda)=\left(w_{1} \underline{m}_{j}+w_{2} \bar{m}_{j}\right)$. Since $w_{1} \underline{g}_{j}^{w}(\vartheta, \mu, \lambda)+w_{2} \bar{g}_{j}^{w}(\vartheta, \mu$, $\lambda) \in \widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)$, is closed and bounded interval, then each point of $\widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)$ is a limit point of $\widehat{\mathbf{G}_{j}^{w}}(\vartheta, \mu, \lambda)$ and $\lim _{\lambda \rightarrow+0} w_{1} \underline{g}_{j}^{w}(\vartheta, \mu, \lambda)+w_{2} \bar{g}_{j}^{w}(\vartheta, \mu, \lambda)=\left(w_{1} \underline{m}_{j}+w_{2} \bar{m}_{j}\right) \in \widehat{\mathbf{M}_{j}^{w}}$. Therefore, $\lim _{\lambda \rightarrow+0} w_{1}$ $\underline{g}^{w}(\vartheta, \mu, \lambda)+w_{2} \bar{g}^{w}(\vartheta, \mu, \lambda)=\left(w_{1} \underline{m}+w_{2} \bar{m}\right) \in \widehat{\mathbf{M}^{w}} \in \mathscr{G}_{c}$.

In the Algorithm 1 below, we describe a step-by-step procedure for computing $g H$-Weak subgradient $\left(\widehat{\mathbf{G}^{w}}, c\right)$ approximately of the given IVF $\Phi$ at the point $u \in \mathbb{R}^{n}$ based on the above assumptions, lemmas and theorems.

From Algorithm 1, we obtain $g H$-weak subgradients of the objective IVF $\Phi$ at every iteration. Algorithm 2 is initialized by choosing a point. We take the function value at this initial point and name this value UB. Algorithm 2 uses one of $g H$-weak subgradients obtained from Algorithm 1 for computing weak efficient direction at every iterative step and attempts to find a weak efficient solution by sequentially moving along the weak efficient direction for the diminishing stepsize. This

```
Algorithm 1 Approximate estimating of the \(g H\)-weak subgradient \(\left(\widehat{\mathbf{G}^{w}}, c\right) \in \partial_{L}^{w} \Phi(u)\).
    Let \(\vartheta \in Q=\left\{\vartheta=\left(\vartheta_{1}, \vartheta_{2}, \ldots, \vartheta_{n}\right) \in \mathbb{R}^{n}:\left|\vartheta_{j}\right|=1, j=1,2, \ldots, n\right\}\) and \(\lambda>0, \mu \in(0,1], u \in \mathbb{R}^{n}\).
    Set \(\vartheta^{j}(\mu)=\left(\vartheta_{1} \mu, \vartheta_{2} \mu^{2}, \ldots, \vartheta_{j} \mu^{j}, 0, \ldots, 0\right), j=1,2, \ldots, n\).
    Let \(y^{0}=u\).
    Select a number \(c>0\).
    \(j \leftarrow 1\).
    while \(j \leq n\) do
    \(y_{j}=y_{0}+\lambda \vartheta^{j}(\mu)\)
    \(\widehat{\mathbf{G}_{j}^{w}}=\frac{1}{\lambda \mu^{j} \vartheta_{j}} \odot\left\{\Phi\left(y_{j}\right) \ominus_{g H} \Phi\left(y_{j-1}\right)\right\}+\frac{c}{\vartheta_{j}}\).
    \(j=j+1\)
    end while
```

algorithm will not stop until the function value at any point of the sequence $\left\{y_{k}\right\}_{k=1}^{\infty}$ is not less than UB. In the below, we present a step-by-step procedure via Algorithm 2 for finding weak efficient points for a given IOP (6.1) with the help of the above process.

```
Algorithm \(2 \mathscr{W}\)-gH-weak subgradient method
    bound be \(\mathrm{UB}=\boldsymbol{\Phi}\left(y_{0}\right)\), and weak efficient solution be \(y_{e f f}=y_{0}\).
    Define the initial iteration and let \(k \leftarrow 1\).
    while \(k \leq n\) do
                        \(\alpha_{k}>0, \lim _{k \rightarrow \infty} \alpha_{k}=0\) and \(\sum_{k=1}^{\infty} \alpha_{k}=\infty\).
        Calculate
            \(y_{k+1}=y_{k}-\alpha_{k} \mathscr{W}\left(\widehat{\mathbf{G}_{k}^{w}}\right)\).
        if \(\Phi\left(y_{k+1}\right) \prec\) UB then
        \(\mathrm{UB}=\Phi\left(y_{k+1}\right)\)
        \(y_{e f f}=y_{k+1}\).
        end if
        Set \(k=k+1\)
    end while
    return : the weak efficient solution
```

Require: Given an initial solution $y_{0} \in \mathbb{R}^{n}, w_{1}, w_{2} \in[0,1]$ such that $w_{1}+w_{2}=1$, let the current upper
From Algorithm 1, choose a $\left(\widehat{\mathbf{G}_{k}^{w}}, c\right) \in \partial_{L}^{w} \Phi\left(y_{k}\right)$ such that $\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{W}}\right) \neq 0$ and an $\alpha_{k}$ such that

In the numerical example below, we apply the proposed Algorithm 1 to calculate a $g H$-weak subgradient of the objective function to the IOP.
Example 6.1. Consider the following IOP:

$$
\begin{equation*}
\min _{\left(y_{1}, y_{2}\right) \in \mathbb{R}^{2}} \Phi\left(y_{1}, y_{2}\right)=[2,6] \odot\left|y_{1}-2\right| \oplus[5,7] \odot\left|y_{2}-3\right| \oplus[5,12] . \tag{6.4}
\end{equation*}
$$

We solve this IOP (6.4) by the method of gH-weak subgradient method. For this, we first start Algorithm 1 with initial point $u=[2.1,3.1]$ and perform two iterations with the parameters $\vartheta=$ $(1,1), \lambda=0.1, \mu=0.5, c=1$. Thereafter, we obtain pair of two $g H$-weak subgradients $\left(\widehat{\boldsymbol{G}^{w}}, c\right)=$ $\left(\left(\boldsymbol{G}_{1}^{w}, \boldsymbol{G}_{2}^{w}\right), c\right)=(([3,7],[6,8]), 1) \in \partial^{w} \Phi((2.1,3.1))$ in two successive iterations.

Geometrically, $\left(\widehat{\boldsymbol{G}^{w}}, c\right)$ represents that there exists a concave and gH-continuous IVF $\boldsymbol{H}\left(y_{1}, y_{2}\right)=$ $[3,7] \odot\left(y_{1}-2\right) \oplus[6,8] \oplus\left(y_{2}-3\right)-\left(\left|y_{1}-2\right|+\left|y_{2}-3\right|\right) \oplus \Phi(2.1,3.1)=[3,7] \odot\left(y_{1}-2\right) \oplus[6,8] \odot$


Figure 2. Visualization of the IVF $\Phi$ with its supporting below conic surface $\mathbf{H}$ in Example 6.1
$\left(y_{2}-3\right)-\left(\left|y_{1}-2\right|+\left|y_{2}-3\right|\right) \oplus[5.7,13.3]$, is a conic surface that coincides with some section of $\underline{\phi}\left(y_{1}, y_{2}\right)=2\left|y_{1}-2\right|+5\left|y_{2}-3\right|+5$ and also intersects $\underline{\phi}$ at least the point $(2,3)$ from bottom.

Taking a gH-weak subgradient $\widehat{\boldsymbol{G}_{1}^{w}}$ in first iteration of Algorithm 1, we start Algorithm 2 with diminishing step length $\alpha_{k}=\frac{1}{k}$ at $k$-th iteration, we compute an unique weak efficient point $(2,3)$ (shown in Figure 2) of IOP (6.4) after four iterations for seven different combinations of $w_{1}$ and $w_{2}$ with different initial points, depicted in Table 1.

Table 1. Result of Algorithm 2 to find efficient solutions of IOP (6.4)

| $w_{1}$ | $w_{2}$ | Initial point | Weak efficient solution |
| :---: | :---: | :---: | :---: |
| 0.1 | 0.9 | $(3.95,4.95)$ | $(2,3)$ |
| 0.3 | 0.7 | $(3.85,4.85)$ | $(2,3)$ |
| 0.4 | 0.6 | $(3.80,4.80)$ | $(2,3)$ |
| 0.5 | 0.5 | $(3.75,4.75)$ | $(2,3)$ |
| 0.6 | 0.4 | $(3.70,4.70)$ | $(2,3)$ |
| 0.9 | 0.1 | $(3.55,4.55)$ | $(2,3)$ |
| 0.7 | 0.3 | $(3.65,4.65)$ | $(2,3)$ |

6.1. Convergence analysis of $\mathscr{W}-g H$-weak subgradient algorithm. $\mathscr{W}-g H$-weak subgradient algorithm generates the sequence of points $\left\{y_{k}\right\}_{k=1}^{\infty} \subseteq \mathbb{R}^{n}$, given by

$$
y_{k+1}=y_{k}-\mu_{k} \mathscr{W}\left(\widehat{\mathbf{G}_{k}^{w}}\right), \text { where }\left(\widehat{\mathbf{G}_{k}^{w}}, c_{k}\right) \in \partial^{w} \Phi\left(y_{k}\right) .
$$

Towards the convergence of $\mathscr{W}$-gH-weak subgradient method, we need the following lemma.
Lemma 6.3. Let $\left\{y_{k}\right\}$ be the sequence generated by $\mathscr{W}$-gH-weak subgradient method. Then, for all $k \geq 0$, we have

$$
\left\|y_{k+1}-y^{*}\right\|^{2} \leq\left\|y_{k}-y^{*}\right\|^{2}-2 \mu_{k}\left\{\mathscr{W}\left(\Phi\left(y_{k}\right)\right)-\mathscr{W}\left(\Phi\left(y^{*}\right)\right)-c_{k}\left\|y^{*}-y_{k}\right\|\right\}+\mu_{k}^{2}\left\|\mathscr{W}\left(\widehat{\boldsymbol{G}_{k}^{W}}\right)\right\|^{2} .
$$

Proof. From Definition 3.1, we have for every $\left(\widehat{\mathbf{G}_{k}^{w}}, c_{k}\right)$ that

$$
{\widehat{\mathbf{G}_{k}^{w}}}^{\top} \odot\left(y^{*}-y_{k}\right) \ominus_{g H} c_{k}\left\|y^{*}-y_{k}\right\| \preceq \Phi\left(y^{*}\right) \ominus_{g H} \Phi\left(y_{k}\right)
$$

$$
\begin{align*}
& \Longrightarrow\left\{\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right\} \ominus_{g H} c_{k}\left\|y^{*}-y_{k}\right\| \preceq{\widehat{\mathbf{G}^{w}}}^{\top} \odot\left(y_{k}-y^{*}\right) \\
& \Longrightarrow \Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right) \preceq{\widehat{\mathbf{G}^{w}}}^{\top} \odot\left(y_{k}-y^{*}\right) \oplus c_{k}\left\|y^{*}-y_{k}\right\| \\
& \Longrightarrow \mathscr{W}\left(\left\{\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right\}\right) \preceq \mathscr{W}\left({\widehat{\mathbf{G}^{w}}}^{\top} \odot\left(y_{k}-y^{*}\right) \oplus c_{k}\left\|y^{*}-y_{k}\right\|\right) . \tag{6.5}
\end{align*}
$$

We note that

$$
\boldsymbol{\Phi}\left(y_{k}\right) \ominus_{g H} \boldsymbol{\Phi}\left(y^{*}\right)=\left[\min \left\{\underline{\phi}\left(y_{k}\right)-\underline{\phi}\left(y^{*}\right), \overline{\boldsymbol{\phi}}\left(y_{k}\right)-\overline{\boldsymbol{\phi}}\left(y^{*}\right)\right\}, \max \left\{\underline{\phi}\left(y_{k}\right)-\underline{\phi}\left(y^{*}\right), \overline{\boldsymbol{\phi}}\left(y_{k}\right)-\overline{\boldsymbol{\phi}}\left(y^{*}\right)\right\}\right] .
$$

We now consider the following two cases.

- Case 1. If $\underline{\phi}\left(y_{k}\right)-\underline{\phi}\left(y^{*}\right)<\bar{\phi}\left(y_{k}\right)-\bar{\phi}\left(y^{*}\right)$, then

$$
\begin{aligned}
\mathscr{W}\left(\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right) & =w_{1}\left(\underline{\phi}\left(y_{k}\right)-\underline{\phi}\left(y^{*}\right)\right)+w_{2}\left(\bar{\phi}\left(y_{k}\right)-\bar{\phi}\left(y^{*}\right)\right) \\
& =\left(w_{1} \underline{\phi}\left(y_{k}\right)+w_{2} \bar{\phi}\left(y_{k}\right)\right)-\left(w_{1} \underline{\phi}\left(y^{*}\right)+w_{2} \bar{\phi}\left(y^{*}\right)\right) \\
& =\mathscr{W}\left(\Phi\left(y_{k}\right)\right) \ominus_{g H} \mathscr{W}\left(\Phi\left(y^{*}\right)\right) .
\end{aligned}
$$

- Case 2. If $\overline{\boldsymbol{\phi}}\left(y_{k}\right)-\overline{\boldsymbol{\phi}}\left(y^{*}\right)<\underline{\boldsymbol{\phi}}\left(y_{k}\right)-\underline{\boldsymbol{\phi}}\left(y^{*}\right)$, then

$$
\begin{aligned}
\mathscr{W}\left(\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right) & =w_{1}\left(\overline{\bar{\phi}}\left(y_{k}\right)-\bar{\phi}\left(y^{*}\right)\right)+w_{2}\left(\underline{\phi}\left(y_{k}\right)-\underline{\phi}\left(y^{*}\right)\right) \\
& =\left(w_{1} \bar{\phi}\left(y_{k}\right)+w_{2} \underline{\phi}\left(y_{k}\right)\right)-\left(w_{1} \bar{\phi}\left(y^{*}\right)+w_{2} \underline{\phi}\left(y^{*}\right)\right) \\
& =\mathscr{W}\left(\Phi\left(y_{k}\right)\right) \ominus_{g H} \mathscr{W}\left(\Phi\left(y^{*}\right)\right) .
\end{aligned}
$$

Accumulating the above two cases, we have from (6.5) that

$$
\begin{align*}
& \mathscr{W}\left(\Phi\left(y_{k}\right)\right) \ominus_{g H} \mathscr{W}\left(\Phi\left(y^{*}\right)\right) \preceq \mathscr{W}\left({\widehat{\mathbf{G}^{W}}}^{\top} \odot\left(y_{k}-y^{*}\right) \oplus c_{k}\left\|y^{*}-y_{k}\right\|\right) \\
& \Longrightarrow \mathscr{W}\left(\Phi\left(y_{k}\right)\right) \ominus_{g H} \mathscr{W}\left(\Phi\left(y^{*}\right)\right) \preceq \mathscr{W}\left(\widehat{\mathbf{G}^{W}}\right)^{\top}\left(y_{k}-y^{*}\right) \oplus c_{k}\left\|y^{*}-y_{k}\right\| . \tag{6.6}
\end{align*}
$$

Using (6.6), we obtain

$$
\begin{aligned}
& \left\|y_{k+1}-y^{*}\right\|^{2}=\left\|y_{k}-\mu_{k} \mathscr{W}\left(\widehat{\mathbf{G}^{w}}\right)-y^{*}\right\|^{2} \\
= & \left\|y_{k}-y^{*}\right\|^{2}-2 \mu_{k} \mathscr{W}\left(\widehat{\mathbf{G}^{W}}\right)^{\top}\left(y_{k}-y^{*}\right)+\mu_{k}^{2}\left\|\mathscr{W}\left(\widehat{\mathbf{G}^{W}}\right)\right\|^{2} \\
\leq & \left\|y_{k}-y^{*}\right\|^{2}-2 \mu_{k}\left\{\mathscr{W}\left(\Phi\left(y_{k}\right)\right)-\mathscr{W}\left(\Phi\left(y^{*}\right)\right\}-c_{k}\left\|y^{*}-y_{k}\right\|\right\}+\mu_{k}^{2}\left\|\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{W}}\right)\right\|^{2} .
\end{aligned}
$$

Theorem 6.2. (Convergence analysis of $\mathscr{W}$ - $g H$-weak subgradient method for the constant stepsize). For the sequence $\left\{y_{k}\right\}$ generated by $\mathscr{W}-g H$-weak subgradient method with constant stepsize $\mu$, we have
(i) if $\Phi\left(y^{*}\right)=-\infty$, then

$$
\begin{equation*}
\liminf _{k \rightarrow \infty} \Phi\left(y_{k}\right)=-\infty, \text { and } \tag{6.7}
\end{equation*}
$$

(ii) if $-\infty \prec \Phi\left(y^{*}\right)$, then

$$
\begin{equation*}
\liminf _{k \rightarrow \infty} \Phi\left(y_{k}\right) \preceq \Phi\left(y^{*}\right) \oplus \mu \frac{(l+L)^{2}}{2} \oplus \liminf _{k \rightarrow \infty} c_{k} d_{\mathscr{Y}} \tag{6.8}
\end{equation*}
$$

where $d_{\mathscr{Y}}$ is the diameter of $\mathscr{Y}$, denoted by $d_{\mathscr{Y}}=\operatorname{diam}(\mathscr{Y})=\max _{y_{1}, y_{2} \in \mathscr{Y}}\left\|y_{1}-y_{2}\right\|$.

Proof. The statements (6.7) and (6.8) can be proven simultaneously. If possible, let there exist an $\varepsilon>0$ such that

$$
\Phi\left(y^{*}\right) \oplus \mu \frac{(l+L)^{2}}{2} \oplus \liminf _{k \rightarrow \infty} c_{k} d \mathscr{Y} \oplus \varepsilon \prec \liminf _{k \rightarrow \infty} \Phi\left(y_{k}\right),
$$

and let $k_{0}$ be sufficiently large such that for all $k \geq k_{0}$. It follows that

$$
\begin{aligned}
& \mu \frac{(l+L)^{2}}{2} \oplus \varepsilon \prec\left(\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right) \ominus_{g H} c_{k} d \mathscr{Y} \\
\Longrightarrow & \mu \frac{(l+L)^{2}}{2} \oplus \varepsilon \prec \mathscr{W}\left(\left(\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right) \ominus_{g H} c_{k} d_{\mathscr{Y}}\right) \\
\Longrightarrow & \mu \frac{(l+L)^{2}}{2} \oplus \varepsilon \prec \mathscr{W}\left(\Phi\left(y_{k}\right)\right) \ominus_{g H} \mathscr{W}\left(\Phi\left(y^{*}\right)\right) \ominus_{g H} c_{k} d_{\mathscr{Y}} \text { by Lemma 6.3. }
\end{aligned}
$$

Since $\left\|y_{k}-y^{*}\right\| \leq d \mathscr{V}$, we have, from Lemma 6.3, that

$$
\begin{aligned}
& \left\|y_{k+1}-y^{*}\right\|^{2} \\
\leq & \left\|y_{k}-y^{*}\right\|^{2}-2 \mu\left\{\mathscr{W}\left(\Phi\left(y_{k}\right)\right)-\mathscr{W}\left(\Phi\left(y^{*}\right)\right)-c_{k}\left\|y^{*}-y_{k}\right\|\right\}+\mu^{2}\left\|\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{w}}\right)\right\|^{2} \\
\leq & \left\|y_{k}-y^{*}\right\|^{2}-2 \mu\left\{\mathscr{W}\left(\Phi\left(y_{k}\right)\right)-\mathscr{W}\left(\Phi\left(y^{*}\right)\right)-c_{k} d \mathscr{\mathscr { }} \|\right\}+\mu^{2}\left\|\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{W}}\right)\right\|^{2} \\
\leq & \left\|y_{k}-y^{*}\right\|^{2}-2 \mu\left[\mu \frac{(l+L)^{2}}{2} \oplus \varepsilon\right]+\mu^{2}\left\|\widehat{\mathbf{G}_{k}^{W}}\right\|^{2} \\
\leq & \left\|y_{k}-y^{*}\right\|^{2}-\mu^{2}(l+L)^{2}-2 \mu \varepsilon+\mu^{2}(l+L)^{2} \\
= & \left\|y_{k}-y^{*}\right\|-2 \mu \varepsilon \\
\leq & \left\|y_{k-1}-y^{*}\right\|-4 \mu \varepsilon \\
\leq & \cdots \leq\left\|y_{k_{0}}-y^{*}\right\|^{2}-2\left(k+1-k_{0}\right) \mu \varepsilon
\end{aligned}
$$

which may not hold for $k$ large enough, so it is a contradiction.
Theorem 6.3. (Convergence analysis of $\mathscr{W}-g H$-weak subgradient method for the diminishing stepsize). Let the stepsize $\mu_{k}$ be such that $\lim _{k \rightarrow \infty} \mu_{k}=0$ and $\sum_{k=0}^{\infty} \mu_{k}=\infty$. Then, for sequence $\left\{y_{k}\right\}$ generated by the $\mathscr{W}$-gH-weak subgradient method with the diminishing stepsize $\mu_{k}$,

$$
\liminf _{k \rightarrow \infty} \Phi\left(y_{k}\right) \preceq \Phi\left(y^{*}\right) \oplus \liminf _{k \rightarrow \infty} c_{k} d \mathscr{y} .
$$

Proof. On contrary, if possible let there exist an $\varepsilon>0$ such that

$$
\Phi\left(y^{*}\right) \oplus \liminf _{k \rightarrow \infty} c_{k} d_{\mathscr{Y}} \oplus \varepsilon \prec \liminf _{k \rightarrow \infty} \Phi\left(y_{k}\right) .
$$

Letting $k_{0}$ be sufficiently large so that for all $k \geq k_{0}$, we have $\varepsilon \prec\left(\Phi\left(y_{k}\right) \ominus_{g H} \Phi\left(y^{*}\right)\right) \ominus_{g H} c_{k} d_{\mathscr{Y}}$. By using Lemma 6.3 and following similar steps used in the proof of Theorem 6.2, we obtain

$$
\left\|y_{k+1}-y^{*}\right\|^{2} \leq\left\|y_{k}-y^{*}\right\|^{2}-2 \mu_{k} \varepsilon+\mu_{k}\left(\mu_{k}\left\|\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{w}}\right)\right\|^{2}\right) .
$$

Since $\mu_{k} \rightarrow 0$ and $\left\{\widehat{\mathbf{G}_{k}^{w}}\right\}$ is bounded, then $k_{0}$ is large enough so that $\mu_{k}\left\|\widehat{\mathbf{G}_{k}^{w}}\right\|^{2}<\varepsilon$ for all $k \geq k_{0}$. Consequently, $\mu_{k}\left\|\mathscr{W}\left(\widehat{\mathbf{G}_{k}^{w}}\right)\right\|^{2}<\varepsilon$ for all $k \geq k_{0}$. This implies that

$$
\begin{aligned}
\left\|y_{k+1}-y^{*}\right\|^{2} & \leq\left\|y_{k}-y^{*}\right\|^{2}-2 \mu_{k} \varepsilon+\mu_{k} \varepsilon \\
& =\left\|y_{k}-y^{*}\right\|^{2}-\mu_{k} \varepsilon \leq\left\|y_{k-1}-y^{*}\right\|^{2}-\left(\mu_{k-1}+\mu_{k}\right) \varepsilon \\
& \leq \cdots \leq\left\|y_{k_{0}}-y^{*}\right\|^{2}-\varepsilon \sum_{j=k_{0}}^{k} \mu_{j} .
\end{aligned}
$$

Since $\sum_{k=0}^{\infty} \mu_{k}=\infty$, this relation may not hold for $k$ sufficient large, so it leads to a contradiction.

## 7. Conclusion

In this paper, the concepts of $g H$-weak subdifferentials and $g H$-weak subgradients (Definition 3.1) for IVFs with illustrative examples were provided. The $g H$-weak subdifferential set of an IVF was shown to be convex (Theorem 3.1) and closed (Theorem 3.2). We further introduced a necessary and sufficient condition (Theorem 3.4) for the set of $g H$-weak subgradients to be non-empty. We derived the necessary optimality condition (Theorem 3.10) involving $g H$-Fréchet differential and $g H$ weak subdifferential for IVFs. We derived a necessary optimality criterion for the difference of two IVFs (Theorem 4.1 and Theorem 4.3). We provided a necessary and sufficient condition for a weak efficient solution in terms of two notions of augmented normal cone and $g H$-weak subdifferential. Towards the end of the paper, we proposed the $\mathscr{W}$-gH-weak subgradient method and its algorithmic implementations (Algorithm 1 and Algorithm 2) to obtain efficient solutions of an unconstrained IOP with the nonconvex and nonsmooth objective IVF. The convergence of the proposed method using the constant and diminishing stepsize was explained (Theorem 6.2 and Theorem 6.3).

Continuing the present study, in the forthcoming work, we attempt to solve the following three problems.

- Introducing a $g H$-weak subgradient algorithm with the dynamic stepsize, which characterizes efficient solutions for nonsmooth nonconvex interval optimization problems.
- In the future, we take up the practical optimization problems to be solved by $g H$-weak subgradient algorithm.
- Analogous to the notion of weak-stability for conventional optimization problems [26], in the future, one may attempt to extend the notion for the following IOP (P):

$$
\begin{aligned}
& \min \Phi(y) \\
& \text { subject to } g_{j}(y) \leq 0, j=1,2, \ldots, p \\
& y \in \mathscr{Y}
\end{aligned}
$$

where $\Phi: \mathscr{Y} \rightarrow I(\mathbb{R}) \cup\{-\infty,+\infty\}$ is an IVF and $g_{j}: \mathscr{Y} \rightarrow \mathbb{R}$ is a real-valued constraint, $j=1,2, \ldots, p$, and the feasible set $C$ is

$$
C=\left\{y \in \mathbb{R}^{n}: y \in \mathscr{Y}, g_{j}(y) \leq 0, j=1,2, \ldots, p\right\} .
$$

To establish an interrelation between strong duality and weak stability for (P), one may define the augmented Lagrange interval-valued function for $(\mathrm{P})$ as follows. Let $J$ be an arbitrary index set, for which we define

$$
\begin{aligned}
\mathbb{R}_{\lambda}^{(J)} & :=\left\{e \in \mathbb{R}^{(J)}:\left|e_{j}\right| \leq 1, j \in J(\lambda)\right\} \\
\text { and } \Lambda & :=\left\{(\lambda, k) \in \mathbb{R}^{(J)}: \exists e \in \mathbb{R}_{\lambda}^{(J)}, k e-\lambda \in \mathbb{R}_{+}^{(J)}\right\},
\end{aligned}
$$

where

$$
\begin{aligned}
\mathbb{R}^{(J)} & :=\left\{\lambda=\left(\lambda_{j}\right)_{j \in J}: \lambda_{j}=0 \text { for all } j \in J \text { but only finitely many } \lambda_{j} \neq 0\right\}, \\
J(\lambda) & :=\left\{j \in J: \lambda_{j} \neq 0\right\}, \text { is a finite subset of } J \\
\text { and } \mathbb{R}_{+}^{J} & :=\left\{\lambda=\left(\lambda_{j}\right)_{j \in J} \in \mathbb{R}^{(J)}: \lambda_{j} \geq 0, j \in J\right\} .
\end{aligned}
$$

For each $j \in J$, the augmented Lagrange interval-valued function for $(\mathrm{P})$ can be defined by

$$
\mathbf{L}(y, \Lambda, k)=\Phi(y) \ominus_{g H}\left\langle\lambda,\left(g_{j}(y)\right)_{j}\right\rangle \oplus \beta\left(\left(g_{j}(y)\right), \lambda, k\right),
$$

where $\beta(u, \lambda, k): \mathbb{R}^{J} \times \mathbb{R}^{(J)} \times \mathbb{R}_{+} \rightarrow \mathbb{R}$ is such that

$$
\beta(y, \lambda, k)= \begin{cases}\sup _{e \in \mathbb{R}_{\lambda}^{(J)}}\left\{\langle k e, u\rangle: k e-\lambda \in \mathbb{R}_{+}^{(J)}\right\} & \text { if } J(\lambda) \neq \emptyset \\ 0 & \text { if } J(\lambda)=\emptyset\end{cases}
$$

The dual of (P) can be found as

$$
\begin{array}{r}
\max \inf \mathbf{L}(x, \lambda, k) \\
\text { subject to }(\lambda, k) \in \Lambda .
\end{array}
$$

We will make an effort to reduce the duality gap by the weak-stability property of the following perturbation function $\Psi: \mathscr{Y} \times \mathbb{R}^{n} \rightarrow I(\mathbb{R}) \cup\{+\infty\}$ associated to the IOP $(\mathrm{P})$ :

$$
\Psi(y, u)= \begin{cases}\Phi(y) & \text { if } y \in \mathscr{Y} \subset \mathbb{R}^{n} \text { and } g_{j}(y) \leq u_{j}, \forall j=1,2,3, \ldots, p \\ +\infty & \text { otherwise }\end{cases}
$$

where $u=\left(u_{1}, u_{2}, \ldots, u_{n}\right)$ is called the perturbation vector.

- One may also try to apply the $g H$-weak subdifferential in the context of zero duality gap in IOPs and interval-valued differential equations. The method for eliminating the duality gap will be immediately applicable in the following areas:
- two-person zero-sum game [22],
- optimal solutions of control problems with first order differential equations [23],
- Hamilton-Jacobi field theory [23],
- difference of convex programming [10].
- The newly defined augmented normal cone and $g H$-weak subdifferential together lead to the thought of introducing supporting cones for a set of intervals in the future. This new concept may be used later to describe the conic gap, which may be a crucial property to capturing the geometry of a nonconvex set of intervals.


## Appendix A. Proof of Lemma 2.3

Proof. Let $\mathbf{W}=[\underline{w}, \bar{w}], \mathbf{Y}=[\underline{y}, \bar{y}]$ and $\mathbf{Z}=[\underline{z}, \bar{z}]$. From the $g H$-difference, we have the following four possible cases:
(i) Give $\varepsilon \preceq\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{w}-\underline{y}-\underline{z}, \bar{w}-\bar{y}-\bar{z}]$. Since $\underline{w}-\underline{y} \geq \underline{z}+\varepsilon$ and $\bar{w}-\bar{y} \geq \bar{z}+\varepsilon$, we have $\underline{z}+\varepsilon \leq \bar{z}+\varepsilon \leq \bar{w}-\bar{y}$. This implies $\underline{z}+\varepsilon \leq \min \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}$. Also, $\bar{z}+\varepsilon \leq \bar{w}-\bar{y} \leq$ $\max \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}$. Clearly we have $[\underline{z}+\varepsilon, \bar{z}+\varepsilon] \preceq[\min \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}, \max \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}]$ and hence $\overline{\mathbf{Z}} \oplus \varepsilon \preceq \mathbf{W} \ominus_{g H} \mathbf{Y}$.
(ii) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{w}-\bar{y}-\bar{z}, \underline{w}-\underline{y}-\underline{z}]$. Thus, the proof is straightforward and identical to Case (i).
(iii) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{w}-\bar{y}-\underline{z}, \underline{w}-\underline{y}-\bar{z}]$. Since $\bar{w}-\bar{y} \geq \underline{z}+\varepsilon, \underline{w}-\underline{y} \geq \bar{z}+\varepsilon$, we have $\underline{z}+\varepsilon \leq \bar{z}+\varepsilon \leq \underline{w}-\underline{y}$. This implies $\underline{z}+\varepsilon \leq \min \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}$. Also, $\bar{z}+\varepsilon \leq \underline{w}-\underline{y} \leq$ $\max \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}$. Clearly we have $[z+\varepsilon, \bar{z}+\varepsilon] \preceq[\min \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}, \max \{\underline{w}-\underline{y}, \bar{w}-\bar{y}\}]$ and hence $\mathbf{Z} \oplus \varepsilon \preceq \mathbf{W} \ominus_{g H} \mathbf{Y}$.
(iv) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{w}-y-\bar{z}, \bar{w}-\bar{y}-z]$. Thus, the proof is identical to Case (iii).

## Appendix B. Proof of Lemma 2.4

Proof. Let $\mathbf{X}=[\underline{x}, \bar{x}], \mathbf{Y}=[\underline{y}, \bar{y}], \mathbf{Z}=[\underline{z}, \bar{z}]$ and $\mathbf{W}=[\underline{w}, \bar{w}]$. Then,

$$
(\mathbf{X} \oplus \mathbf{Y}) \ominus_{g H}(\mathbf{Z} \oplus \mathbf{W})
$$

$$
\begin{align*}
& =[\min \{\underline{x}+\underline{y}-\underline{z}-\underline{w}, \bar{x}+\bar{y}-\bar{z}-\bar{w}\}, \max \{\underline{x}+\underline{y}-\underline{z}-\underline{w}, \bar{x}+\bar{y}-\bar{z}-\bar{w}\}] \\
& =[\min \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\}, \max \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\}] . \tag{B.1}
\end{align*}
$$

We have

$$
\begin{align*}
\min \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\} & \geq \min \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}+\min \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\}  \tag{B.2}\\
\text { and } \max \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\} & \leq \max \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}+\max \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\} . \tag{B.3}
\end{align*}
$$

By (B.2) and (B.3), from (B.1), we write

$$
\begin{aligned}
& (\mathbf{X} \oplus \mathbf{Y}) \ominus_{g H}(\mathbf{Z} \oplus \mathbf{W}) \\
= & {[\min \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\}, \max \{\underline{x}-\underline{z}+\underline{y}-\underline{w}, \bar{x}-\bar{z}+\bar{y}-\bar{w}\}] } \\
\subseteq & {[\min \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}+\min \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\}, \max \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}+\max \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\}] } \\
= & {[\min \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}, \max \{\underline{x}-\underline{z}, \bar{x}-\bar{z}\}]+[\min \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\}, \max \{\underline{y}-\underline{w}, \bar{y}-\bar{w}\}] } \\
= & \left(\mathbf{X} \ominus_{g H} \mathbf{Z}\right) \oplus\left(\mathbf{Y} \ominus_{g H} \mathbf{W}\right) .
\end{aligned}
$$

## Appendix C. Proof of Lemma 2.5

Proof. Let $\mathbf{W}=[\underline{w}, \bar{w}], \mathbf{Y}=[\underline{y}, \bar{y}]$, and $\mathbf{Z}=[\underline{z}, \bar{z}]$. Then,

$$
-1 \odot \mathbf{W}=[-\bar{w},-\underline{w}],-1 \odot \mathbf{Y}=[-\bar{y},-\underline{y}],-1 \odot \mathbf{Z}=[-\bar{z},-\underline{z}] .
$$

From Definition of gH -difference of two intervals, we have: either

$$
-1 \odot \mathbf{W} \ominus_{g H}-1 \odot \mathbf{Y}=[\bar{y}-\bar{w}, \underline{y}-\underline{w}]
$$

or

$$
-1 \odot \mathbf{W} \ominus_{g H}-1 \odot \mathbf{Y}=[\underline{y}-\underline{w}, \bar{y}-\bar{w}] .
$$

Then, one of the following holds true
(a) $\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})=[\bar{y}-\bar{w}+\bar{z}, \underline{y}-\underline{w}+\underline{z}]$,
(b) $\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})=[y-\underline{w}+\underline{z}, \overline{\bar{y}}-\bar{w}+\bar{z}]$,
(c) $\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})=[\underline{y}-\underline{w}+\bar{z}, \bar{y}-\bar{w}+\underline{z}]$,
(d) $\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})=[\overline{\bar{y}}-\bar{w}+\underline{z}, \underline{y}-\underline{w}+\bar{z}]$.

From this, we have
(a) $\mathbf{0} \ominus_{g H}\left\{\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})\right\}=[\underline{w}-\underline{y}-\underline{z}, \bar{w}-\bar{y}-\bar{z}]$,
(b) $\mathbf{0} \ominus_{g H}\left\{\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})\right\}=[\bar{w}-\overline{\bar{y}}-\bar{z}, \underline{w}-\underline{y}-\underline{z}]$,
(c) $\mathbf{0} \ominus_{g H}\left\{\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})\right\}=[\bar{w}-\bar{y}-\underline{z}, \underline{w}-\bar{y}-\bar{z}]$,
(d) $\mathbf{0} \ominus_{g H}\left\{\left((-1 \odot \mathbf{W}) \ominus_{g H}(-1 \odot \mathbf{Y})\right) \ominus_{g H}(-1 \odot \mathbf{Z})\right\}=[\underline{w}-\underline{y}-\bar{z}, \bar{w}-\bar{y}-\underline{z}]$.

On the other hand, we have
(a) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{w}-y-\underline{z}, \bar{w}-\bar{y}-\bar{z}]$,
(b) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{w}-\bar{y}-\bar{z}, \underline{w}-\underline{y}-\underline{z}]$,
(c) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{w}-\bar{y}-\underline{z}, \underline{w}-\underline{y}-\bar{z}]$,
(d) $\left(\mathbf{W} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{w}-\underline{y}-\bar{z}, \bar{w}-\overline{\bar{y}}-\underline{z}]$.

Hence, the desired result follows.

## Appendix D. Proof of Lemma 2.6

Proof. Let $\mathbf{X}=[\underline{x}, \bar{x}], \mathbf{Y}=[\underline{y}, \bar{y}]$ and $\mathbf{Z}=[\underline{z}, \bar{z}]$.
(i) Let us consider the following four representations:
(a) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{x}-y-\underline{z}, \bar{x}-\bar{y}-\bar{z}]$,
(b) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\underline{x}-\bar{y}-\bar{z}, \bar{x}-\bar{y}-\underline{z}]$,
(c) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{x}-\bar{y}-\underline{z}, \underline{x}-y-\bar{z}]$,
(d) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}=[\bar{x}-\bar{y}-\bar{z}, \underline{x}-\underline{y}-\underline{z}]$.

- Case 1. Give that $\mathbf{0} \preceq \mathbf{X} \ominus_{g H} \mathbf{Y}$. Then we have

$$
\begin{align*}
& 0 \leq \underline{x}-\underline{y} \text { and } 0 \leq \bar{x}-\bar{y} \\
\Longrightarrow & 0-\underline{z} \leq \underline{x}-\underline{y}-\underline{z} \text { and } 0-\bar{z} \leq \bar{x}-\bar{y}-\bar{z} \\
\Longrightarrow & {[0-\underline{z}, 0-\bar{z}] \underline{x} \underline{x}-\underline{y}-\underline{z}, \bar{x}-\bar{y}-\bar{z}] . } \tag{D.1}
\end{align*}
$$

So, from (D.1), we have $\mathbf{0} \ominus_{g H} \mathbf{Z} \preceq\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}$.

- Case 2. Similarly, we can arrive at this conclusion (D.1). So, from (D.1), we have $\mathbf{0} \ominus_{g H} \mathbf{Z} \preceq$ $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{Z}$.
- Case 3. This case can be proved by using the same steps as Case 1.
- Case 4. This case can be proved by using the same steps as Case 2.
(ii) Let $\mathbf{W}=[\underline{w}, \bar{w}]$. By the definition of $g H$-difference, there may be the following four cases.
(a) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}=[\underline{x}-\underline{y}-\underline{w}, \bar{x}-\bar{y}-\bar{w}]$,
(b) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}=[\underline{x}-\underline{y}-\bar{w}, \bar{x}-\bar{y}-\underline{w}]$,
(c) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}=[\bar{x}-\overline{\bar{y}}-\underline{w}, \underline{x}-\underline{y}-\bar{w}]$,
(d) $\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}=[\bar{x}-\bar{y}-\bar{w}, \underline{x}-\underline{y}-\underline{w}]$.

The following two cases are needed to consider for the representation of these above four cases.

- Case 1. Since $\mathbf{Z} \preceq \mathbf{X} \ominus_{g H} \mathbf{Y}$, we have

$$
\begin{align*}
& \underline{z} \leq \underline{x}-\underline{y} \text { and } \bar{z} \leq \bar{x}-\bar{y} \\
& \Longrightarrow \underline{z}-\underline{w} \leq \underline{x}-\underline{y}-\underline{w} \text { and } \bar{z}-\bar{w} \leq \bar{x}-\bar{y}-\bar{w} \\
& \Longrightarrow \text { either }[\underline{z}-\underline{w}, \bar{z}-\bar{w}] \preceq[\underline{x}-\underline{y}-\underline{w}, \bar{x}-\bar{y}-\bar{w}]  \tag{D.2}\\
& \text { or }[\bar{z}-\bar{w}, \underline{z}-\underline{w}] \preceq[\bar{x}-\bar{y}-\bar{w}, \underline{z}-\underline{y}-\underline{w}] . \tag{D.3}
\end{align*}
$$

From (D.2) and (D.3), we have $\mathbf{Z} \ominus_{g H} \mathbf{W} \preceq\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}$.

- Case 2. Similarly, at the last step, we have

$$
\begin{align*}
& \text { either }[\underline{z}-\underline{w}, \bar{z}-\bar{w}] \preceq[\bar{x}-\bar{y}-\underline{w}, \underline{x}-\underline{y}-\bar{w}]  \tag{D.4}\\
& \quad \text { or }[\bar{z}-\bar{w}, \underline{z}-\underline{w}] \preceq[\underline{x}-\underline{y}-\bar{w}, \bar{x}-\bar{y}-\underline{w}] . \tag{D.5}
\end{align*}
$$

From (D.4) and (D.5), we have $\mathbf{Z} \ominus_{g H} \mathbf{W} \preceq\left(\mathbf{X} \ominus_{g H} \mathbf{Y}\right) \ominus_{g H} \mathbf{W}$.
(iii) Give $\mathbf{X} \ominus_{g H} \mathbf{Y} \preceq[L, L]$. From the formula of $g H$-difference of intervals,

$$
\begin{aligned}
& \underline{x}-\underline{y} \leq L \text { and } \bar{x}-\bar{y} \leq L \\
\Longrightarrow & -L \leq \underline{y}-\underline{x},-L \leq \bar{y}-\bar{x} \\
\Longrightarrow & \text { either }[-L,-L] \preceq[\underline{y}-\underline{x}, \bar{y}-\bar{x}] \text { or }[-L,-L] \preceq[\bar{y}-\bar{x}, \underline{y}-\underline{x}] .
\end{aligned}
$$

Hence, $[-L,-L] \preceq \mathbf{Y} \ominus_{g H} \mathbf{X}$.
(iv) Give $[-\gamma,-\gamma] \preceq \mathbf{X} \ominus_{g H} \mathbf{Y}$. From the formula of $g H$-difference of intervals,

$$
\begin{aligned}
& -\gamma \leq \underline{x}-\underline{y} \text { and }-\gamma \leq \bar{x}-\bar{y} \\
\Longrightarrow & \underline{y}-\gamma \leq \underline{x} \text { and } \bar{y}-\gamma \leq \bar{x}
\end{aligned}
$$

$$
\Longrightarrow[\underline{y}-\gamma, \bar{y}-\gamma] \preceq[\underline{x}, \bar{x}] .
$$

Hence, $\mathbf{Y} \ominus_{g H}[\gamma, \gamma] \preceq \mathbf{X}$.
(v) Give $\mathbf{Z} \preceq \mathbf{X} \oplus \mathbf{Y}$. Then,

$$
\begin{aligned}
\underline{z}, \bar{z} \preceq[\underline{x}, \bar{x}] \oplus[\underline{y}, \bar{y}] & \Longrightarrow \underline{z} \leq \underline{x}+\underline{y}, \bar{z} \leq \bar{x}+\bar{y} \\
& \Longrightarrow \underline{z}-\underline{y} \leq \underline{x}, \bar{z}-\bar{y} \leq \bar{x} \\
& \Longrightarrow[\underline{z}-\underline{y}, \bar{z}-\bar{y}] \preceq \underline{x}, \overline{\bar{x}}] .
\end{aligned}
$$

Hence, $\mathbf{Z} \ominus_{g H} \mathbf{Y} \preceq \mathbf{X}$.

## Appendix E. Proof of Lemma 3.1

Proof. Let $y^{\top} \odot \widehat{\mathbf{C}}=\mathbf{D}$ and $\mathbf{D}=[\underline{d}, \bar{d}]$. Note that

$$
\begin{equation*}
\|\mathbf{D}\|_{I(\mathbb{R})}=\max \{|\underline{d}|,|\bar{d}|\} . \tag{E.1}
\end{equation*}
$$

On the other hand,

$$
\begin{align*}
\|\mathbf{D}\|_{I(\mathbb{R})} & =\left\|y_{1} \odot \mathbf{C}_{1} \oplus y_{2} \odot \mathbf{C}_{2} \oplus \cdots \oplus y_{n} \odot \mathbf{C}_{n}\right\|_{I(\mathbb{R})} \\
& \leq\left\|y_{1} \odot \mathbf{C}_{1}\right\|_{I(\mathbb{R})}+\left\|y_{2} \odot \mathbf{C}_{2}\right\|_{I(\mathbb{R})}+\cdots+y_{n} \odot \mathbf{C}_{n} \|_{I(\mathbb{R})} \\
& =\left|y_{1}\left\|\mathbf{C}_{1}\right\|_{I(\mathbb{R})} \oplus\right| y_{2}\left|\left\|\mathbf{C}_{2}\right\|_{I(\mathbb{R})}+\cdots+\right| y_{n}\| \| \mathbf{C}_{n} \|_{I(\mathbb{R})} \\
& \leq\|y\| \sum_{i=1}^{n}\left\|\mathbf{C}_{i}\right\|_{I(\mathbb{R})} \\
& =\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} . \tag{E.2}
\end{align*}
$$

Then, taking into account (E.1) and (E.2), we obtain

$$
\begin{array}{ll} 
& |\underline{d}| \leq\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \text { and }|\bar{d}| \leq\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \\
\Longrightarrow \quad & -\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq \underline{d} \text { and }-\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq \bar{d} \\
\Longrightarrow \quad & -\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq|\underline{d}| \text { and }-\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq|\bar{d}| \\
\Longrightarrow \quad & -\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq \max \{|\underline{d}|,|\bar{d}|\} \\
\Longrightarrow \quad & -\|y\|\|\widehat{\mathbf{C}}\|_{I(\mathbb{R})^{n}} \leq\|\mathbf{D}\|_{I(\mathbb{R})} .
\end{array}
$$

Thus, we arrived at the desired result.

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